Hall-Effect Geartooth Sensor Datasheet

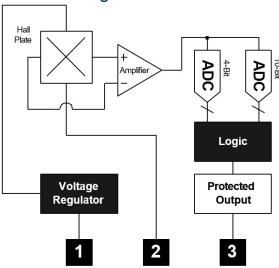


General description

Features & benefits

- Geartooth Sensor
- Zero Speed Detection
- Insensitive to Orientation
- Short Circuit Protection
- Self-Adjusting Magnetic Range
- On-chip 10 bit A/D Converter
- High Speed Operation
- No Chopper Delay

Functional Diagram



Pin 1: V_{DD} (Supply) Pin 2: V_{SS} (Ground) Pin 3: Output

Note: Static sensitive device, please observe ESD precautions.

Applications examples

- Geartooth Sensor
- Speed Sensor
- Camshaft Sensor
- Direction Detection (see applications example)

Description

The MLX90217 is a self-adjusting digital output rotary position gear tooth sensor designed for use in automotive camshaft sensing as well as other speed sensing applications. It is designed to be used with a bias magnet south facing the back (non-marked) side of the IC. The device has an open collector output which is short circuit protected.

The MLX90217 is a sophisticated IC featuring an on-chip 10-bit A/D Converter and logic that acts as a digital sample and hold circuit. A separate 4- bit A/D converter provides a fixed hysteresis. The 90217 does not have a chopper delay. The 90217 uses a single Hall plate which is immune to rotary alignment problems. The bias magnet can be from 50 to 400mT.

As the signal is sampled, the logic recognizes an increasing or decreasing flux density. The output will turn on (BOP) after the flux has reached its peak and decreased by an amount equal to the hysteresis. Similarly, the output will turn off (BRP) after the flux has reached its minimum value and increased by an amount equal to the hysteresis.

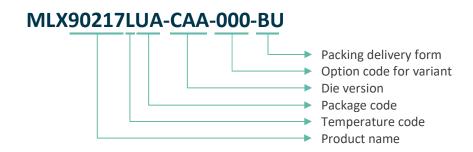
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Ordering information

Product code	Temperature	Package	Application	Packing
MLX90217LUA-CAA-000-BU	-40 to 150 °C	UA	3.5mT typical hysteresis	BU
MLX90217LUA-CCA-000-BU	-40 to 150 °C	UA	5.5mT typical hysteresis	BU

Table 1 – Product codes





Absolute Maximum Ratings

DC Operating Parameters TA = -40°C to 150°C, VDD = 3.5V to 24V (unless otherwise specified).

Parameter	Symbol	Min.	Max.	Unit	Condition
Supply Voltage	V_{DD}		30	V	Operating
Supply Current	I _{DD}		50	mA	Fault
Output Current	I _{OUT}		30	mA	Fault
Output Current	I _{FAULT}		50	mA	Fault
Output Voltage	V _{OUT}		30	V	
Power Dissipation	P _D		100	mW	
Operating Temperature	T _A	-40	150	°C	
Storage Temperature	Ts	-65	150	°C	
Junction Temperature	TJ		175	°C	

Table 2 – Absolute Maximum Ratings

Electrical Specifications

DC Operating Parameters TA = -40°C to 150°C, VDD = 3.5V to 24V (unless otherwise specified).

Parameter	Symbol	Min.	Тур	Max.	Unit	Condition
Supply Voltage	V_{DD}	3.5	-	24	V	Operating
Supply Current	I_{DD}	1.5	3.0	4.5	mA	V _{DD} = 12V
Supply Current	I_{DD}	1	-	6	mA	V _{DD} = 3.5V to 24V
Leakage Current	I _{LEAK}	-	-	10	μΑ	V _{OUT} = 3.5V to 24V
Output Current	I _{OUT}	-	-	25	mA	Operating
Output Saturation Voltage	V_{SAT}	-	-	600	mV	$V_{DD} = 12V, I_{OUT} = 25mA$
Output Short Circuit Current	I _{FAULT}	50	100	150	mA	Fault
Output Short Circuit Shutdown	T _{FAULT}	100	-	200	S	Fault
Clock Frequency	f_{CLK}	300	500	800	kHz	Operating
Output Rise Time	t _r		-	400	ns	$V_{DD} = 12V, R_1 = 880\Omega,$
						$C_1 = 20pf$
Output Fall Time	t_f		-	400	ns	$V_{DD} = 12V, R_1 = 880\Omega,$
						$C_1 = 20pf$
Bandwidth	BW	-	-	15	kHz	Operating
Thermal Resistance	R _{TH}	-	-	200	°C/W	Operating

Table 3 – Electrical Specifications

Magnetic Specifications

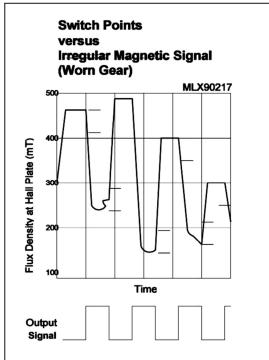
DC Operating Parameters TA = -40°C to 150°C, VDD = 3.5V to 24V (unless otherwise specified). 1mT = 10Gauss

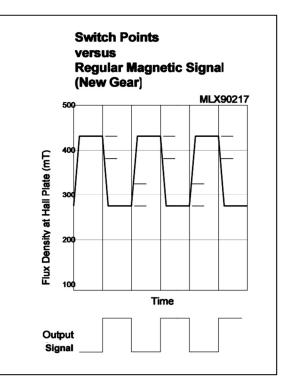
Parameter	Symbol	Min.	Тур	Max.	Unit	Condition
Back Bias Range	B _{BIAS}	-30	-	400	mT	Operating
Linear Region	B _{LIN}	50	-	500	mT	$V_{DD} = 12V$
Hysteresis	B _{HYS}	1.8	3.5	10	mT	CAA-000
Hysteresis	B _{HYS}	3.8	5.5	12	mT	CCA-000

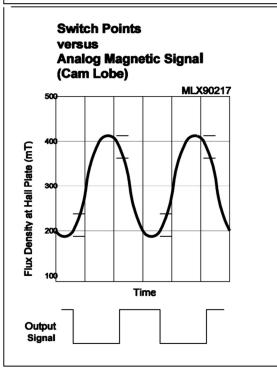
Table 4 – Magnetic Specifications



Performance Graphs







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Application Notes

Maximum dynamic range is 500mT. The hysteresis is fixed at 5.0mT. Best angular accuracy will be obtained when the magnetic circuit provides peak magnetic flux at the chip near the high end of the linear range of 500mT. EMC protections using external components are recommended. Two possibilities are shown on the following page. Normally the South pole faces the unbranded side of the device. A North pole will enable a test sequence used in factory testing.

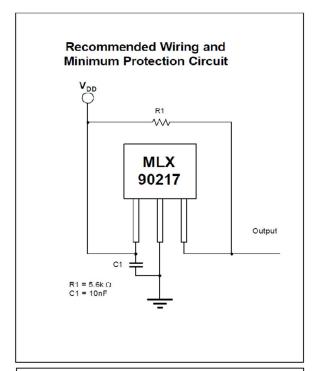
Unique Features

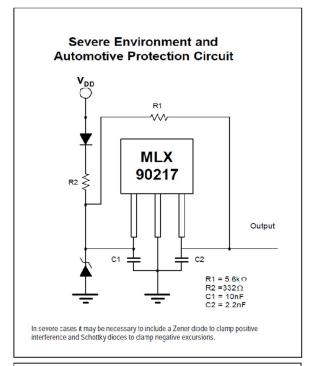
The output is reset to the high-Z state at power on (output driver is off) whatever the field is. The output only changes after the first min is detected. The reset state holds no information about the field. If the supply of the chip is raised slowly, the reset state is not stable. This has been observed at 0 field but it should be the same with small and large fields.

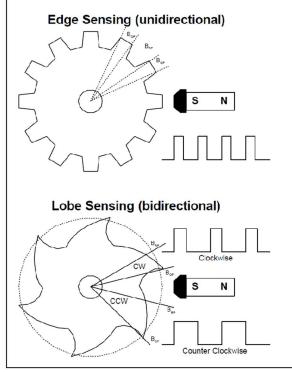
Gear tooth sensors often need to be adjusted after the module is assembled to align the magnet with differential Hall plates or orient with teeth. However, the MLX90217 is "self-adjusting" over a wide range of back bias flux eliminating the need for any trimming in the application. The magnet may be glued to the back surface (non-branded side) of the IC using a cyanoacrylate adhesive or suitable epoxy.

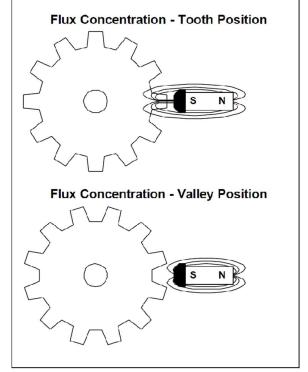


Application Examples



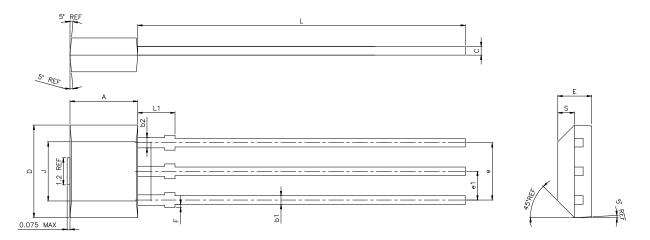








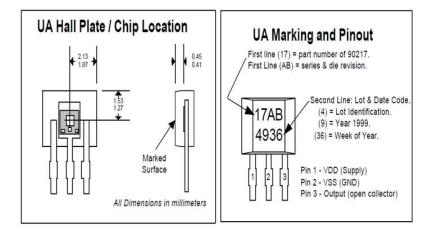
Physical Characteristics



SYMBOL	MINIMUM	MAXIMUM			
Α	2.90	3.10			
D	4.00	4.20			
Ε	1.40	1.60			
F	0.00	0.20			
J	2.51	2.72			
L	14.00	15.00			
L1	1.55	1.75			
S	0.63	0.84			
b1	0.35	0.44			
b2	0.43	0.52			
С	0.35	0.44			
е	2.51	2.57			
e1	1.24	1.30			

NOTE :

- 1. DIMENSIONS IN MILLIMETERS (mm) UNLESS NOTED OTHERWISE.
- 2. PACKAGE DIMENSIONS DO NOT INCLUDE MOLD FLASHES AND PROTRUSIONS.
- 3. DIMENSION A AND D DO NOT INCLUDE MOLD GATE AND SIDE FLASH (PROTRUSION) of MAXIMUM 0.127 mm PER SIDE.
- 4. THE LEADS MAY BE SLIGHTLY DEFORMED DURING TRANSPORTATION IF PACKED IN BULK (BAG), AFFECTING e1 DIMENSION. IT IS RECOMMENDED TO ORDER RADIAL TAPE (REEL OR AMMOPACK) IF SUCH DEFORMATION IS CRITICAL FOR THE LEAD FORMING PROCESS, EVEN IF MANUAL LOADING INTO THE TOOL IS FORESEEN.



Note: When parts are shipped in bulk (bag) LSL / USL limits on e and e1 are not applicable and dimensions should be considered as a reference value.

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Standard information regarding manufacturability of Melexis products with different soldering processes

Our products are classified and qualified regarding soldering technology, solderability and moisture sensitivity level according to following test methods:

Reflow Soldering SMD's (Surface Mount Devices)

- IPC/JEDEC J-STD-020
 - Moisture/Reflow Sensitivity Classification for Nonhermetic Solid-State Surface Mount Devices (classification reflow profiles according to table 5-2)
- EIA/JEDEC JESD22-A113
 Preconditioning of Non-hermetic Surface Mount Devices Prior to Reliability Testing (reflow profiles according to table 2)

Wave Soldering SMD's (<u>Surface Mount Devices</u>) and THD's (<u>Through Hole Devices</u>)

- EN60749-20
 - Resistance of plastic- encapsulated SMD's to combined effect of moisture and soldering heat
- EIA/JEDEC JESD22-B106 and EN60749-15
 Resistance to soldering temperature for through-hole mounted devices

Iron Soldering THD's (Through Hole Devices)

EN60749-15
 Resistance to soldering temperature for through-hole mounted devices

Solderability SMD's (<u>Surface Mount Devices</u>) and THD's (<u>Through Hole Devices</u>)

 EIA/JEDEC JESD22-B102 and EN60749-21 Solderability

For all soldering technologies deviating from above mentioned standard conditions (regarding peak temperature, temperature gradient, temperature profile etc) additional classification and qualification tests have to be agreed upon with Melexis.

The application of Wave Soldering for SMD's is allowed only after consulting Melexis regarding assurance of adhesive strength between device and board.

Melexis is contributing to global environmental conservation by promoting **lead free** solutions. For more information on qualifications of **RoHS** compliant products (RoHS = European directive on the Restriction Of the use of certain Hazardous Substances) please visit the quality page on our website: http://www.melexis.com/quality.aspx

ESD Precautions

Electronic semiconductor products are sensitive to Electro Static Discharge (ESD).

Always observe Electro Static Discharge control procedures whenever handling semiconductor products.

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Revision History

Revision	Date	Change history
011	02-Sep-25	Updated package drawing, new template, layout and cleanup of text

Table 5 – Revision History

Hall-Effect Geartooth Sensor Datasheet



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