

DATASHEET

CC3500AC52FB Conduction Cooled Wide-Output-Range Rectifier

Input: 100-120/200-240 V_{ac}; 3500W capable; Output: 18-58 V_{dc}, 5 V_{dc} @ 10W

RoHS Compliant



Description

The CC3500AC52FB Rectifier has an extremely wide programmable output voltage capability. Featuring high-density, fully enclosed, conduction-cooled packaging, it is designed for minimal space utilization and is highly expandable for future growth. This standard rectifier incorporates both RS485 and dual-redundant I²C communications busses that allow it to be used in a broad range of applications. Feature-set flexibility makes this rectifier an excellent choice for applications requiring operation over a wide output-voltage range.

Applications

- Wide band power amplifier
- Broadcast systems
- Lasers
- Acoustic noise sensitive systems
- LED signage

Features

- Efficiency exceeding 96%¹ (meets 80+ Titanium)
- Compact 1RU form factor with 40 W/in³ density
- 3500W from nominal 200-240V_{AC} up to 50°C case
- 1500W from nominal 100 – 120V_{AC} for V_O > 52V_{DC}
- Output voltage programmable from 18V – 58V_{DC}
- ON/OFF control of the main output
- Comprehensive input, output and overtemp. protection
- PMBus compliant dual I²C serial bus and RS485
- Precision measurement reporting such as input power consumption, input/output voltage & current
- Remote firmware upgrade capable
- Power factor correction (meets EN/IEC 61000-3-2 and EN 60555-2 requirements)
- Redundant, parallel operation with active load sharing
- Redundant +5V @ 2A Aux power
- Completely enclosed, conduction cooled
- Hot insertion/removal (hot plug)
- Four front panel LED indicators
- UL and cUL approved to UL/CSA†62368-1, TUV (EN62368- 1), CE[§] Mark (for LVD) and CB Report available
- RoHS Directive 2011/65/EU and amended Directive (EU) 2015/863
- Compliant to REACH Directive (EC) No 1907/2006

See footnotes on page no 49

Page 1

Technical Specifications

Absolute Maximum Ratings

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

| Parameter | Symbol | Min | Max | Unit |
|---|-----------|-----|------------------|----------|
| Input Voltage : Continuous | V_{IN} | 0 | 264 | V_{AC} |
| Operating Case Temperature (sink side) ² | T_A | -40 | 75 ²⁴ | °C |
| Storage Temperature | T_{stg} | -40 | 85 | °C |

Electrical Specifications

Unless otherwise indicated, specifications apply over all operating input voltage $V_o = 52V_{DC}$, resistive load, and temperature conditions.

| INPUT | | | | | |
|--|----------|----------------------|------------|-----|----------------------|
| Parameter | Symbol | Min | Typ | Max | Unit |
| Startup Voltage | V_{IN} | 80 | 85 | 90 | V_{AC} |
| Low-line Operation | | | | 185 | |
| High-line Operation | | | | | |
| Operating Voltage Range | | | | | |
| Low-line Configuration | | 90 | 100 – 120 | 140 | |
| High-line Configuration | | 185 | 200 - 240 | 265 | |
| Voltage Swell (no damage) | | 275 | | | |
| Turn OFF Voltage | | 75 | 80 | 85 | |
| Hysteresis | | 5 | | | |
| Frequency | F_{IN} | 47 | | 66 | Hz |
| Source Impedance (NEC allows 2.5% of source voltage drop inside a building) | | | 0.2 | | Ω |
| Operating Current; at 110 V_{AC} at 240 V_{AC} | I_{IN} | | 15.5 16 | | A_{AC} |
| Inrush Transient (220 V_{RMS} , 25°C, excluding X-Capacitor charging) | I_{IN} | | 25 | 40 | A_{PK} |
| Idle Power (at 240 V_{AC} , 25°C) 52V OFF 52V ON @ $I_o = 0$ | P_{IN} | | 9 18 | | W |
| Leakage Current (265 V_{AC} , 60Hz) | I_{IN} | | 2.5 | 3.5 | mA |
| Power Factor (50 – 100% load) | PF | 0.97 | 0.995 | | |
| Efficiency ³ , 240 V_{AC} , 52 V_{DC} , @ 25°C 10% of FL 20% of FL 50% of FL FL | η | 90 94 96 91 | | | % |
| Holdup time (output allowed to decay down to 40 V_{DC}) For loads below 1500W | T | | 10 15 | | ms |
| Ride through (at 240 V_{AC} , 25°C) | T | 1/2 | 1 | | cycle |
| Power Good Warning ⁴ (main output allowed to decay to | PG | 3 | 5 | | ms |
| Isolation (per EN62368) (consult factory for testing to this requirement) Input to Chassis & Signals Input to Output | V | 1500 3000 | | | V_{AC} V_{AC} |

² See the derating guidelines under the Environmental Specifications section

³ 5V output at 0A load.

⁴ Internal protection circuits may override the PG signal and may trigger an immediate shutdown. PG should not indicate normal (HI) until the main output is within regulation. PG should be asserted if the main output is about to shut down for any detectable reason.

²⁴ From 50°C-75°C see derating guidelines

Technical Specifications (continued)

Electrical Specifications (continued)

| 52V _{DC} MAIN OUTPUT | | | | | |
|---|--|-------------------------|---------------|-------------------|--|
| Parameter | Symbol | Min | Typ | Max | Unit |
| Output Power ⁵ @ low line input 100 – 120V _{AC} , T _C < 50°C @ high line input 200 – 240V _{AC} , V _O > 42V _{DC} , T _C < 50°C | W | 1500 3500 | | | W _{DC} |
| Factory set default set point | | | 52 | | V _{DC} |
| Overall regulation (load, temperature, aging) 0 - 45°C LOAD > 2.5A > 45°C | V _{OUT} | -1 -2 | | +1 +2 | % |
| Output Voltage Set Range | | 18 | | 58 ⁽⁹⁾ | V _{DC} |
| Response to a voltage change | T | | 400 | 500 | ms |
| Output Current - @ 1500W (100 – 120V _{ac}), V _O >= 52V @ 3500W (200 – 240V _{AC}), V _O >= 52V | I _{OUT} | 1 | | 28.3/28.9 | A _{DC} |
| Current Share (> 50% FL) V _O > 42V _{DC} V _O < 42V _{DC} | | -5 -10 | | 5 10 | %FL |
| Output Ripple (20MHz bandwidth, load > 1A) RMS (5Hz to 20MHz) Peak-to-Peak (5Hz to 20MHz) | V _{OUT} | | | 100 500 | mV _{rms} mV _{p-p} |
| External Bulk Load Capacitance | C _{OUT} | 0uF to at least 36000uF | | | μF |
| Turn-On (monotonic turn-ON from 30 – 100% of V _{nom} above 5°C) Delay Rise Time – PMBus mode Rise Time - RS-485 mode ⁷ Output Overshoot | T V _{OUT} | | 5 100 5 | | s ms s % |
| Load Step Response (I _{O,START} > 2.5A) ΔI ⁸ ΔV, Response Time | I _{OUT} V _{OUT} T | | | 2.0 50 2 | %FL V _{DC} ms |
| Permissible Load Boundary | Power limit , high line (down to 52V _{DC}) | P _{OUT} | 3500 | | W |
| | Low line | P _{OUT} | 1500 | | W |
| | The overload current limit threshold is set @ 3% above the load envelope shown here. | | | | |

⁵ Output power capability is proportional to output voltage setting, see the permissible load boundary

⁶ Input line range: 90 – 264 VRMS (±10%)

⁷ Below -5°C, the rise time is approximately 5 minutes to protect the bulk capacitors.

⁸ di/dt (output current slew rate) 1A/μs

Technical Specifications (continued)

Electrical Specifications (continued)

| High line: | | | | | | | | | | | | | |
|--------------------|----|----|----|------|------|----|------|------|------|----|----|------|------|
| V _o (V) | 18 | 23 | 28 | 32 | 36 | 40 | 42 | 48 | 52 | 53 | 54 | 56 | 58 |
| I _o (A) | 29 | 37 | 45 | 51.3 | 57.7 | 64 | 67.3 | 67.3 | 67.3 | 66 | 65 | 62.7 | 60.3 |

$I_o = 1.596 * V_o + 0.275$ while $V_o < 42V$.

| Low line: | | | | | | | | | | | | | |
|--------------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|------|------|------|------|
| V _o (V) | 18 | 23 | 28 | 32 | 36 | 40 | 42 | 48 | 52 | 53 | 54 | 56 | 58 |
| I _o (A) | 28.85 | 28.85 | 28.85 | 28.85 | 28.85 | 28.85 | 28.85 | 28.85 | 28.85 | 28.3 | 27.8 | 26.8 | 25.9 |

| | |
|-----------------|--|
| | Contract terms are for supporting all loads inside the load map. The customer will develop a control interface which maintains the operating voltage and current so as to not exceed the load map. |
| System power up | Upon insertion the rectifier will delay an overload shutdown for 20 seconds. |

52V_{DC} MAIN OUTPUT

| Parameter | Symbol | Min | Typ | Max | Unit |
|---|------------------|---|---------------|------|-----------------|
| Overvoltage - 200ms delayed shutdown | V _{OUT} | > 60 | | < 65 | V _{DC} |
| Immediate shutdown | | Three restart attempts are implemented within a 1 | | | |
| Latched shutdown | | | | | |
| Over-temperature warning (prior to commencement of shutdown) Shutdown (below the max device rating being protected) Restart attempt Hysteresis (below shutdown level) | T | | 5 20 10 | | °C |
| Isolation Output to Chassis | V | 500 | | | V _{DC} |

52V_{DC} Auxiliary output (return is LGND)

| Parameter | Symbol | Min | Typ | Max | Unit |
|------------------------------------|------------------|-------|-----|-----|-------------------|
| Output Voltage Setpoint | V _{OUT} | | 5 | | V _{DC} |
| Overall Regulation | | -3 | | +3 | % |
| Output Current | | 0.005 | | 2 | A |
| Ripple and Noise (20mHz bandwidth) | | | 50 | 100 | mV _{p-p} |
| Over-voltage Clamp | | | | 7 | V _{DC} |
| Over-current Limit | | 110 | | 175 | %FL |
| Isolation LGND to Chassis | | 100 | | | V _{DC} |

Technical Specifications (continued)

Electrical Specifications (continued)

The 5V_{DC} should be ON before availability of the 52V_{DC} main output and should turn OFF only if insufficient input voltage exists to provide reliable 5V_{DC} power. The PG# signal should have indicated a warning that power would get turned OFF and the 52V_{DC} main output should be OFF way before interruption of the 5V_{DC} output.

General Specifications

| Parameter | Min | Typ | Max | Units | Notes |
|------------------|---|-----------|-----|-------|--|
| Reliability | | 1,000,000 | | Hours | Full load, 25°C ; MTBF per SR232 Reliability protection for electronic equipment, issue 3, method I, case III, |
| Service Life | | 10 | | Years | At 80% load & 40°C cold plate |
| Unpacked Weight | | 4.5 | | Kg | CC3500AC52FB-ES/EC |
| Packed Weight | | 5.0 | | Kg | CC3500AC52FB-ES/EC |
| Unpacked Weight | | 4.1 | | Kg | CC3500AC52FB |
| Packed Weight | | 4.5 | | Kg | CC3500AC52FB |
| Heat Dissipation | 190 Watts or 648 BTUs @ 80% load, 250 Watts or 853 BTUs @ 100% load | | | | |

Signal Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. Signals are referenced to LGND unless noted otherwise. Fault, PG#, OTW, and Alert need to be pulled HI through external pull-up resistors

| Parameter | Symbol | Min | Typ | Max | Unit |
|--|--|--------------------|-----|-------|------------------|
| ON/OFF Main output OFF | V _{OUT} | 0.7V _{DD} | — | 5 | V _{DC} |
| 52V output ON (should be connected to LGND) | V _{OUT} | 0 | — | 0.5 | V _{DC} |
| Margining (by adjusting V _{prog} ; see “Voltage programming” section) | | | | | |
| Programmed output voltage range | V _{OUT} | <19 | | 58 | V _{DC} |
| Linear voltage control range | V _{control} | > 0.1 | | < 3.0 | V _{DC} |
| Voltage adjustment resolution (8-bit A/D) | V _{control} | | 3.3 | | mV _{DC} |
| Output set to 52V _{DC} | V _{control} | 3.0 | | 3.3 | V _{DC} |
| Output set to 18V _{DC} | V _{control} | 0 | | 0.1 | V _{DC} |
| 52 – 18V _{DC} , settling time to new value | T | — | 400 | 600 | ms |
| Interlock | [short pin shorted to V _{OUT} (-) on system side] | | | | |
| Module Present | [short pin to LGND internally] | | | | |
| Over Temperature Warning (OTW#) Logic HI (temperature normal) | V | 0.7V _{DD} | — | 12 | V _{DC} |
| Sink current [note: open collector output FET] | I | — | — | 5 | mA |
| Logic LO (temperature is too high) | V | 0 | — | 0.4 | V _{DC} |
| Power Good (PG) Logic HI (temperature normal) | V | 0.7V _{DD} | — | 12 | V _{DC} |
| Sink current [note: open collector output FET] | I | — | — | 5 | mA |
| Logic LO (temperature is too high) | V | 0 | — | 0.4 | V _{DC} |
| Protocol select Logic HI - Analog/PMBus™ mode | V _{IH} | 2.7 | — | 3.5 | V _{DC} |
| Logic – intermediate – RS485 mode | V _{II} | 1.0 | — | 2.65 | V _{DC} |
| Logic LO – DSP reprogram mode | V _{IL} | 0 | — | 0.4 | V _{DC} |
| Fault# Logic HI (No fault is present) | V | 0.7V _{DD} | — | 12 | V _{DC} |
| Sink current | I | — | — | 5 | mA |
| Logic LO (Fault is present) | V | 0 | — | 0.4 | V _{DC} |
| Alert# (Alert#_0, Alert#_1) Logic HI (No Alert - normal) | V | 0.7V _{DD} | — | 12 | V _{DC} |
| Sink current [note: open collector output FET] | I | — | — | 5 | mA |
| Logic LO (Alert# is set) | V | 0 | — | 0.4 | V _{DC} |

Technical Specifications (continued)

Signal Specifications (continued)

| Parameter | Symbol | Min | Typ | Max | Unit |
|--|--------|-----|-----|-----|-----------------|
| SCL, SDA (SCL_0/1, SDA_0/1) Logic HI | V | 2.1 | — | 12 | V _{DC} |
| Sink current [note: open collector output FET] | I | — | — | 5 | mA |
| Logic LO (Alert# is set) | V | 0 | — | 0.4 | V _{DC} |

Digital Interface Specifications

| Parameter | Conditions | Symbol | Min | Typ | Max | Unit |
|--|--|-----------------------|--------------|----------|--------------|-----------------|
| PMBus Signal Interface Characteristics⁹ | | | | | | |
| Input Logic High Voltage (CLK, DATA) | | V | 2.1 | | 12 | V _{DC} |
| Input Logic Low Voltage (CLK, DATA) | | V | 0 | | 0.8 | V _{DC} |
| Input high sourced current (CLK, DATA) | | I | 0 | | 10 | μA |
| Output Low sink Voltage (CLK, DATA, ALERT#) | I _{OUT} =3.5mA | V | | | 0.4 | V _{DC} |
| Output Low sink current (CLK, DATA, ALERT#) | | I | 3.5 | | | mA |
| Output High open drain leakage current | V _{OUT} =3.6V | I | 0 | | 10 | μA |
| PMBus Operating frequency range | Slave Mode | FPMB | 10 | | 400 | kHz |
| Measurement System Characteristics | | | | | | |
| Clock stretching | | T _{stretch} | | | 25 | ms |
| I _{OUT} measurement range | | I _{rng} | 0 | | 80 | A _{DC} |
| I _{OUT} measurement accuracy 25°C | > 12.8A < 12.8A | I _{out(acc)} | -1 5 | | +1 5 | % of FL % |
| I _{OUT} measurement accuracy 0 - 40°C ¹⁰ | > 12.8A | I _{out(acc)} | -2 | | +2 | % of FL |
| V _{OUT} measurement range | | V _{out(rng)} | 0 | | 70 | V _{DC} |
| V _{OUT} measurement accuracy ¹¹ | | V _{out(acc)} | -1 | | +1 | % |
| Temp measurement range | | Temp _(rng) | 0 | | 150 | °C |
| Temp measurement accuracy ¹² | | Temp _(acc) | -4 | | +4 | °C |
| V _{IN} measurement range | | V _{in(rng)} | 0 | | 320 | V _{AC} |
| V _{IN} measurement accuracy @ 25°C | V _{IN} > 120V _{AC} V _{IN} < 120V _{AC} | V _{in(acc)} | -1.25 -2 | | +1.25 2 | % |
| I _{IN} measurement range | | I _{in(rng)} | 0 | | 30 | I _{AC} |
| I _{IN} measurement accuracy - standard measurement @ 25°C | | I _{in(acc)} | -4 | | +4 | % of FL |
| I _{IN} measurement accuracy - improved measurement @ 25°C | > 1A ≤ 1A | I _{in(acc)} | -2.5 -400 | | 2.5 400 | % mA |
| P _{IN} measurement range | | P _{in(rng)} | 0 | | 4000 | W _{in} |
| P _{IN} measurement accuracy – standard measurement @ 25°C | > 350W < 350W | P _{in(acc)} | -5 | 35 | +5 50 | % W |
| P _{IN} measurement accuracy – improved measurement @ 25°C | > 500W 100 – 500W | P _{in(acc)} | -1.5 -2.0 | 1 1.5 | +1.5 +2.0 | % % |

⁹ Clock, Data, and Alert# need to be pulled up to VDD externally.

¹⁰ Below 20% of FL; 10 – 20% of FL: ±0.64A; 5 – 10% of FL: ±0.45A; 2.5 – 5% of FL: ±0.32A.

¹¹ Above 2.5A of load current

¹² Within 30° of the default warning and fault levels.

Technical Specifications (continued)

Environmental Specifications (continued)

| Parameter | Min | Typ | Max | Units | Notes |
|----------------------------------|-------------------|---------|-------------|--------|---|
| Operating Case Temperature | -40 ¹³ | | 50 | °C | Measured at the surface that mounted to coldplate and just above the HS_1 and HS2 |
| Storage Temperature | -40 | | 85 | °C | |
| Operating Altitude | | | 5000/16,400 | m / ft | |
| Non-operating Altitude | | | 8200/27,000 | m / ft | |
| Power Derating with Temperature | | | 2 | %/°C | 50°C - 75°C |
| Acoustic noise | | 0 | | dbA | Full load |
| Over Temperature Protection | | 125/110 | | °C | Shutdown / restart [internally measured points] |
| Humidity | | | | | |
| Operating | 5 | | 95 | % | Relative humidity, non-condensing |
| Storage | 5 | | 95 | % | |
| Shock and Vibration acceleration | | | 2.4 | Grms | IPC-9592B, Class II |

| EMC | | | | |
|------------------------|-----------------------------|---|---------------------------|--|
| Parameter | Measurement | Standard | Level | Test |
| AC input ¹⁴ | Conducted emissions | EN55032, FCC Docket 20780 part 15, subpart J Meets EN 55032 Class A with a 6dB Margin Meets Telcordia GR1089-CORE by a 3dB margin | A | 0.15 – 30MHz |
| | Radiated emissions | EN55032 to comply with system enclosure | A | 30 – 10000MHz |
| | Line harmonics | EN61000-3-2THD | Table 1 5% | 0 – 2 kHz 230 Vac, full load, 25°C |
| Parameter | Measurement | Standard | Criteria ¹⁵ | Test |
| AC Input Immunity | Line sags and Interruptions | EN61000-4-11 Output will stay above 40V _{DC} @ 75% load Sag must be higher than 80V _{rms} . | B | -30%, 10ms |
| | | | B | -60%, 100ms |
| | | | B | -100%, 5sec |
| | Lightning surge | EN61000-4-5, Level 4, 1.2/50µs – error free ANSI C62.41 - level A3 | A | 25% line sag for 2 seconds |
| | | | A | 1 cycle interruption |
| | | | B | 4kV, common mode 2kV, differential mode |
| Fast transients | EN61000-4-4, Level 3 | B | 5/50ns, 2kV (common mode) | |
| Enclosure immunity | Conducted RF fields | EN61000-4-6, Level 3 | A | 130dBµV, 0.15-80MHz, 80% AM |
| | Radiated RF fields | EN61000-4-3, Level 3 | A | 10V/m, 80-1000MHz, 80% AM |
| | | ENV 50140 | A | |
| | ESD | EN61000-4-2, Level 4 | B | 8kV contact, 15kV air |

¹³ Designed to start and work at an ambient as low as -40°C, but may not meet operational limits until above -5°C

¹⁴ Emissions requirements apply to rectifiers with the “-EC” and “-ES” options (which include filters), not the blind-mate-connector version where an external filter must be added to meet these requirements. External EMI filter reference design is included in this datasheet.

¹⁵ Criteria A: The product must maintain performance within specification limits. Criteria B: Temporary degradation which is self recoverable. Criteria C: Temporary degradation which requires operator intervention.

Technical Specifications (continued)

Characteristic Curves

The following figures provide typical characteristics for the CC3500AC52TE rectifier and 25°C.

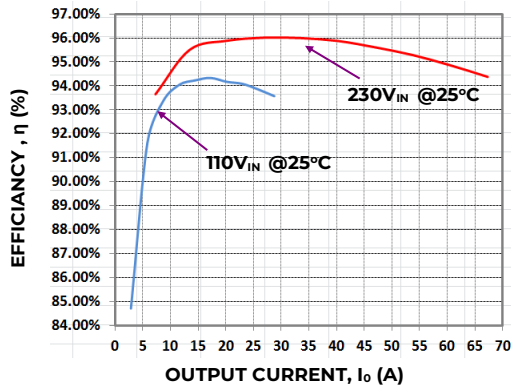


Figure 1. Rectifier Efficiency versus Output Current.

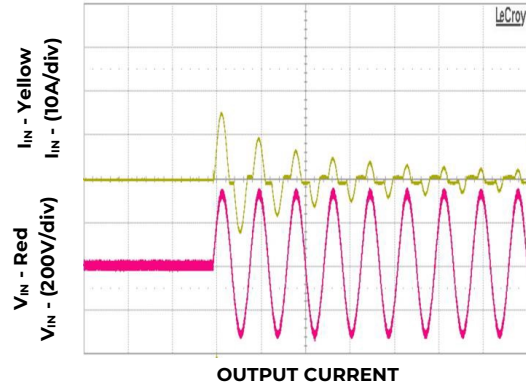
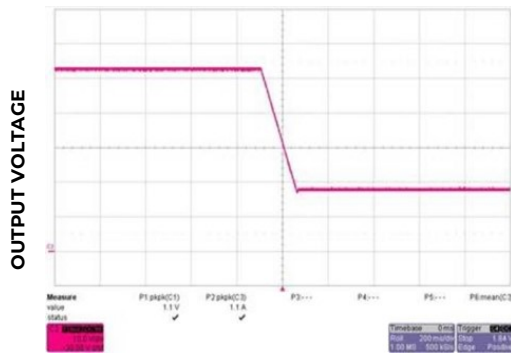


Figure 2. Inrush current $V_{IN} = 230V_{AC}$, 0°C phase angle



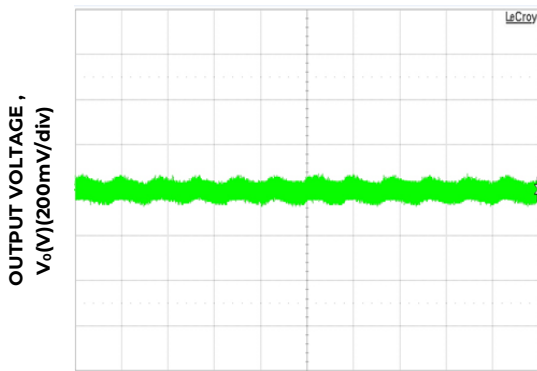
TIME, t (200ms/div)

Figure 3. Main output: Output changed from 52V to 18V; commanded via I²C.



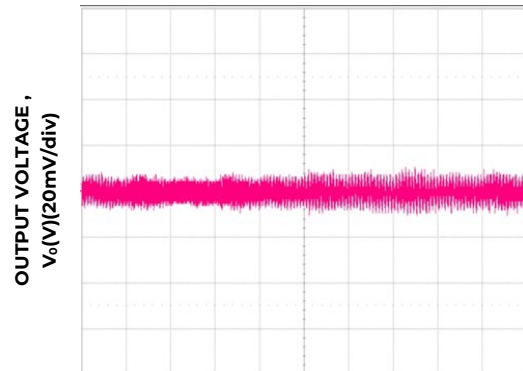
TIME, t (200ms/div)

Figure 4. Main output: Output changed from 18V to 52V; commanded via I²C



TIME, t (10ms/div)

Figure 5. 52V_{DC} output ripple and noise, full load, $V_{IN} = 185V_{AC}$, 20MHz bandwidth



TIME, t (10ms/div)

Figure 6. 5V_{DC} output ripple and noise, all full load, $V_{IN} = 185V_{AC}$, 20MHz bandwidth

Technical Specifications (continued)

Characteristic Curves (Continued)

The following figures provide typical characteristics for the CC3500AC52TE rectifier and 25°C

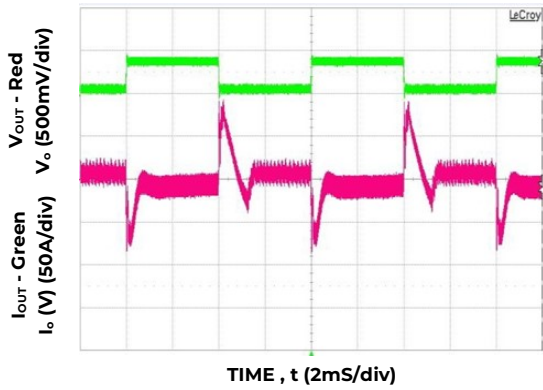


Figure 7. Transient response 52V_{DC} load step 10 – 60%, Slew rate: 1A/μs, V_{IN} = 230V_{AC}

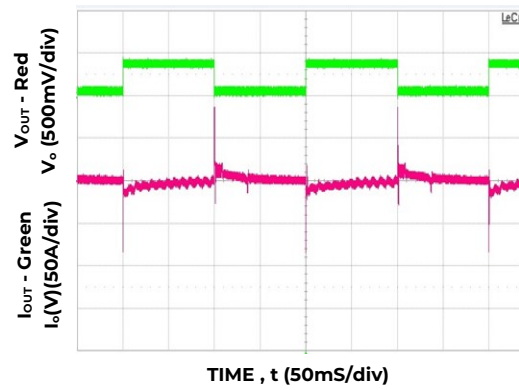


Figure 8. Transient response 52V_{DC} load step 10 – 60%, Slew rate: 1A/μs, V_{IN} = 230V_{AC}

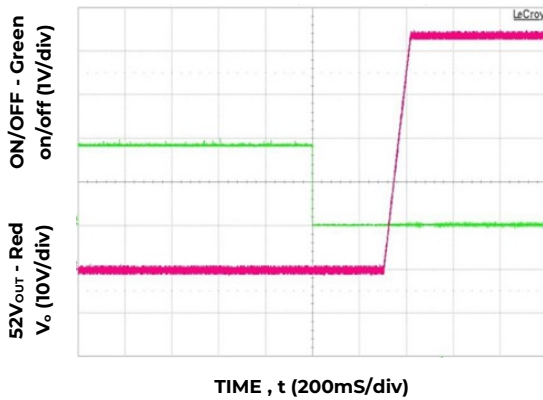


Figure 9. 52V_{DC} soft start delay when ON/OFF is asserted, V_{IN}=230V_{AC} - I²C mode.

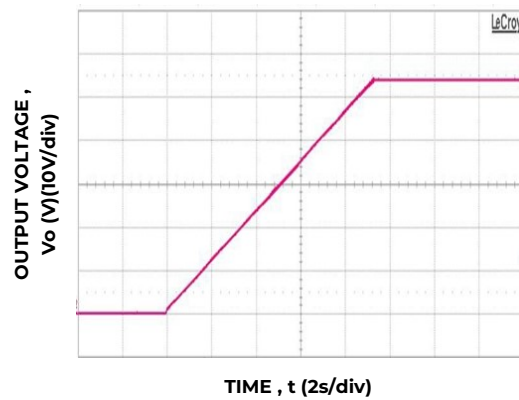


Figure 10. 52V_{DC} soft start, full load, V_{IN} = 230V_{AC} - RS485 mode with 4700μf external capacitance.

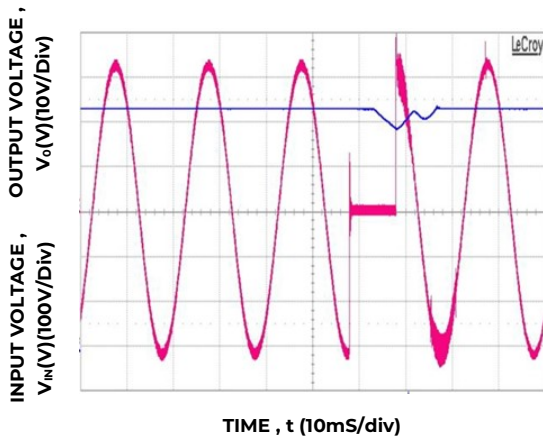


Figure 11. Ride through missing ½ cycle, full load, V_{IN} = 230V_{AC}.

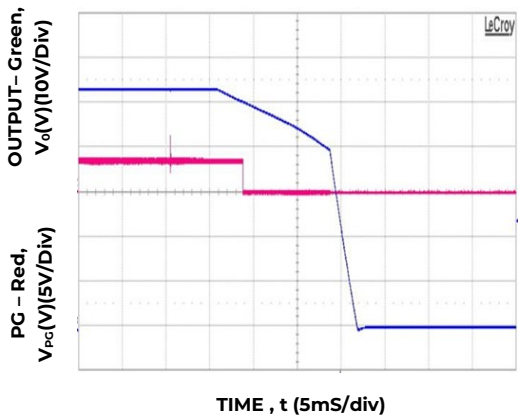


Figure 12. PG# alarmed 10ms prior to V_o < 40V, V_{IN} = 230V_{AC}, Output at Full load

Technical Specifications (continued)

Characteristic Curves (Continued)

The following figures provide typical characteristics for the CC3500AC52TE rectifier and 25°C.

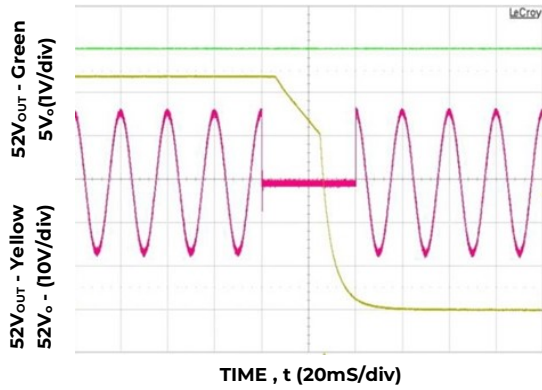


Figure 13. 40ms AC dropout @ full load, $V_{IN} = 230V_{AC}$

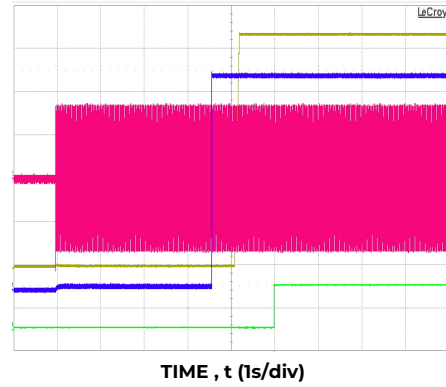


Figure 14. Turn-ON at full load $V_{IN} = 230V_{AC}$.

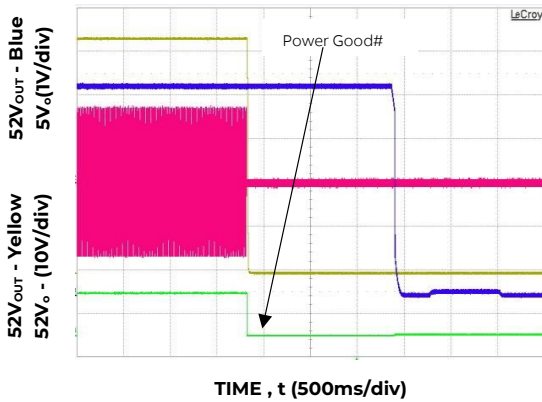


Figure 15. Turn-OFF at full load, $V_{IN}=230V_{AC}$

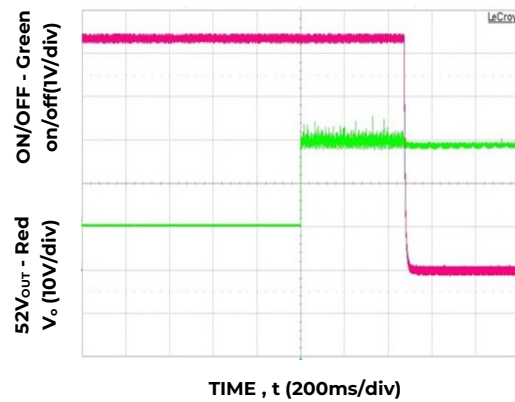


Figure 16. 52V_{DC} turn-OFF delay when ON/OFF is de-asserted, $V_{IN}=230V_{AC}$ - I²C mode.

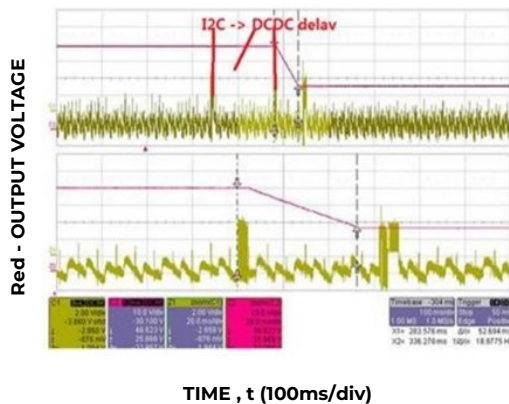


Figure 17. Time delay from sending the I²C command and executing the output voltage change.

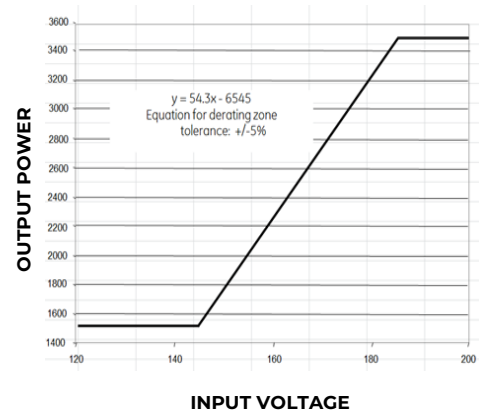
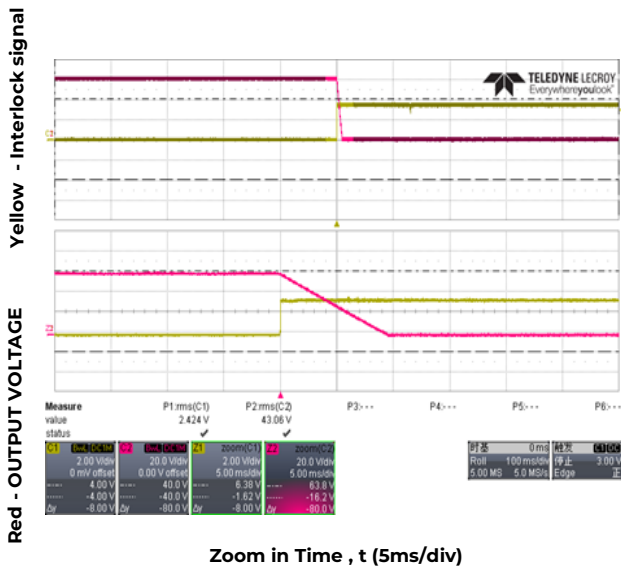


Figure 18. Output power derating below V_{IN} of 185V_{AC}

Technical Specifications (continued)

Characteristic Curves (Continued)

The following figures provide typical characteristics for the CC3500AC52TE rectifier and 25°C.



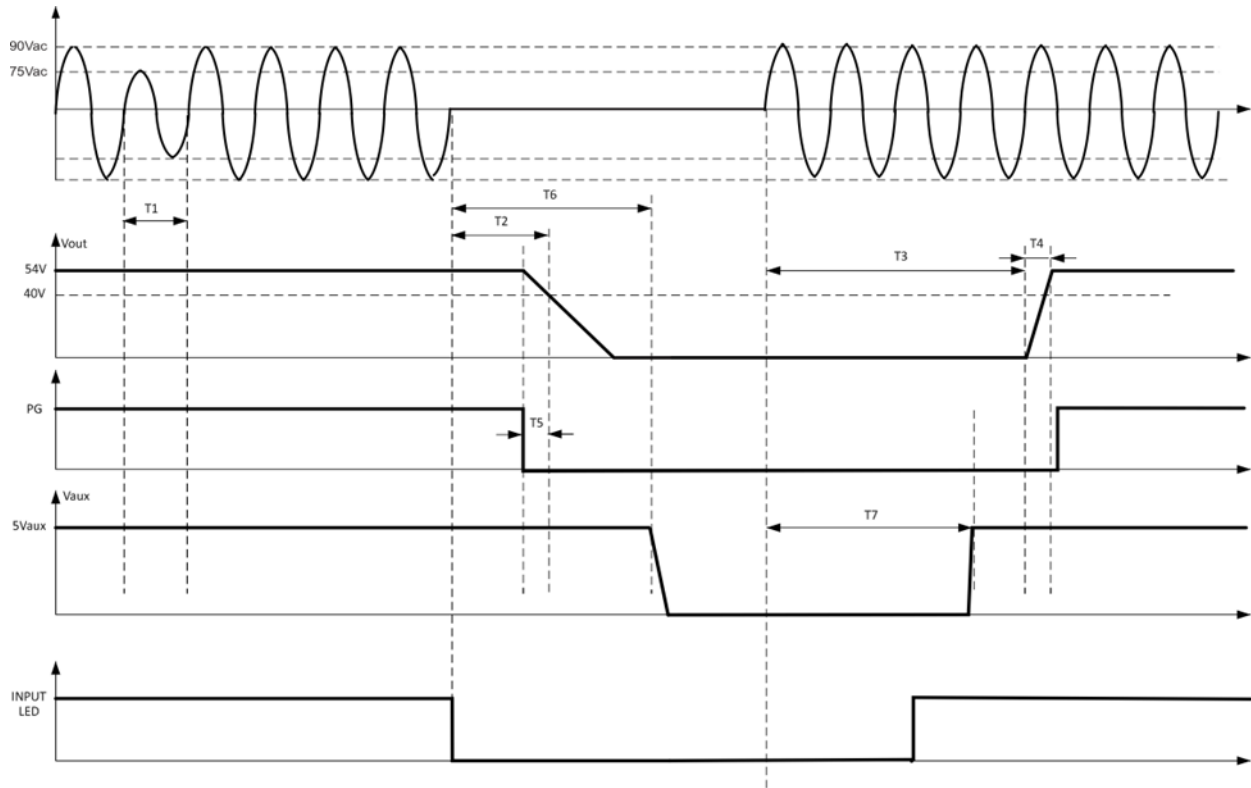
Zoom in Time , t (5ms/div)

Figure 19 . Time delay from interlock reverse and output shut down. interlock signal can be used as quick turn off signal.

Technical Specifications (continued)

Timing Diagrams

Response to input fluctuation



T1 – ride through time – 0.5 to 1 cycles [10 – 20ms] V_{OUT} remains within regulation – load dependent

T2 – hold up time - 15ms – V_{OUT} stays above 40V_{DC}

T3 – delay time – 10s – from when the AC returns within regulation to when the output starts rising in I²C mode

T4 – rise time - 120ms – the time it takes for V_{OUT} to rise from 10% to 90% of regulation in I²C mode

T5 – power good warning – 3ms – the time between assertion of the PG signal and the output decaying below 40V_{DC}.

T6 – hold up time of the 5VAUX output @ full load – 1s – from the time AC input failed

T7 – rise time of the 5VAUX output - 3.65ms – 5VAUX is available at least 450ms before the main output is within regulation
Blinking of the input/AC LED – $V_{IN} < 80V_{AC}$ (the low transitioned signal represents blinking of the input LED).

Technical Specifications (continued)

Control and Status

The Rectifier provides three means for monitor/control: analog, PMBus™, or the OmniOn Power Galaxy-based RS485 protocol.

Details of analog control and the PMBus™ based protocol are provided in this data sheet. OmniOn Power will provide separate application notes on the Galaxy RS485 based protocol for users to interface to the rectifier. Contact your local OmniOn Power representative for details.

Control hierarchy: Some features, such as output voltage, can be controlled both through hardware and firmware. For example, the output voltage is controlled both by a signal pin (V_{prog}) and firmware ($V_{out_command}$, 0x21).

Using output voltage as an example, the V_{prog} signal pin voltage level sets the output voltage if its value is between 0.1 and 3.0 V_{DC} (see the “Voltage programming” section). When the programming signal V_{prog} is either a no - connect (0V) or $> 3V_{DC}$, the output voltage is set at the default value of $52V_{DC}$.

The signal pin controls the corresponding feature until the firmware command is executed. Once the firmware command has been executed, the signal pin is ignored until input power is removed and reapplied, which resets control to the signal pin. In the above example, the rectifier will no longer ‘listen’ to the V_{prog} pin after $V_{out_command}$ has been executed, as long as input power is applied without interruption.

In summary, hardware signals such as V_{prog} are utilized for setting the initial default value and for varying the value until firmware based control takes over. Once firmware control is executed, hardware based control is relinquished so the processor can clearly decide who has control.

Analog controls: Details of analog controls are provided in this data sheet under Feature Specifications.

Signal Reference: Unless otherwise noted, all signals are referenced to LGND (“Logic Ground”). See the Signal Definitions Table at the end of this document for further description of all the signals.

LGND is isolated from the main output of the rectifier for PMBus communications. Communications and the 5V standby output are not connected to main power return ($V_{out(-)}$) and can be tied to the system digital ground point selected by the user. (Note that RS485 communications is referenced to $V_{out(-)}$, main power return of the rectifier).

LGND is capacitively coupled to Earth Ground inside the rectifier where Earth Ground is also wired to the metal case). The maximum voltage differential between LGND and Earth Ground should be less than $100V_{DC}$.

Delayed overcurrent shutdown during startup:

Rectifiers are programmed to stay in a constant current state for up to 20 seconds during power up. This delay has been introduced to permit the orderly application of input power to a subset of paralleled front-ends during power up. If the overload persists beyond the 20 second delay, the front-end will revert back into its programmed state of overload protection.

Unit in Power Limit or in Current Limit: When output voltage is $> 10V_{DC}$ the Output LED will continue blinking.

When output voltage is $< 10V_{DC}$, if the unit is in the RESTART mode, it goes into hiccup. When the unit is ON the output LED is ON, when the unit is OFF the output LED is OFF.

When the unit is in latched shutdown the output LED is OFF.

Auto restart: Auto-restart is the default configuration for over-current and over-temperature shutdowns. These features are configured by the PMBus™ fault_response commands

An overvoltage shutdown is followed by three attempted restarts, each restart delayed 1 second, within a 1 minute window. If within the 1 minute window three attempted restarts failed, the unit will latch OFF. If within the 1 minute less than 3 shutdowns occurred then the count for latch OFF resets and the 1 minute window starts all over again.

Restart after a latching off: PMBus™ fault_response commands can be configured to direct the rectifier to remain latched off for over_temperature and over_current.

Technical Specifications (continued)

Control and Status (continued)

To restart after a latch off either of five restart mechanisms are available.

1. The hardware pin ON/OFF may be cycled OFF and then ON.
2. The unit may be commanded to restart via I²C through the Operation command by cycling the output OFF followed by ON.
3. Remove and reinsert the unit.
4. Turn OFF and then turn ON AC power to the unit.
5. Changing firmware from latch off to restart.

Each of these commands must keep the rectifier in the OFF state for at least 2 seconds, with the exception of changing to **restart**.

A successful restart shall clear all alarm registers, set the **restarted successful** bit of the **Status_2** register.

A power system that is comprised of a number of rectifiers could have difficulty restarting after a shutdown event because of the non-synchronized behavior of the individual rectifiers. Implementing the latch-off mechanism permits a synchronized restart that guarantees the simultaneous restart of the entire system.

A synchronous restart can be implemented by;

1. Issuing a GLOBAL OFF and then ON command to all rectifiers,
2. Toggling Off and then ON the ON/OFF (ENABLE) signal
3. Removing and reapplying input commercial power to the entire system.

The rectifiers should be turned OFF for at least 20 – 30 seconds in order to discharge all internal bias supplies and reset the soft start circuitry of the individual rectifiers.

Control Signals

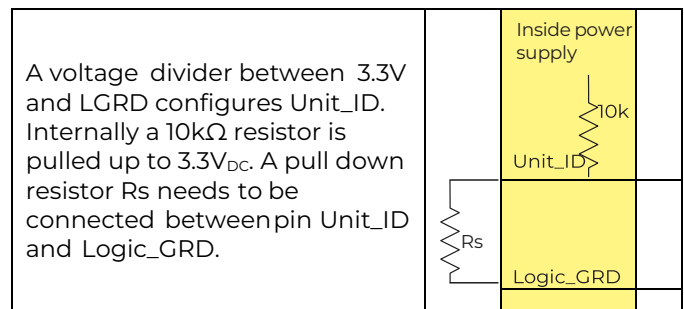
Protocol: This signal pin defines the communications mode setting of the rectifier. Two different states can be configured: State #1 is “Analog/PMBus” mode (I²C) for which the protocol pin should be left a no-connect. State #2 is the RS485 mode for which a resistor value between 1kΩ and 5kΩ should be present between this pin and V_{out} (-).

Device address in I²C mode: Address bits A3, A2, A1, A0 set the specific address of the μP in the rectifier. With these four bits, up to sixteen (16) rectifiers can be independently addressed on a single I²C bus. These four bits are configured by two signal pins, Unit_ID

and Rack_ID. The least significant bit x (LSB) of the address byte is set to either **write [0]** or read [1]. A **write** command instructs the rectifier. A **read** command accesses information from the rectifier.

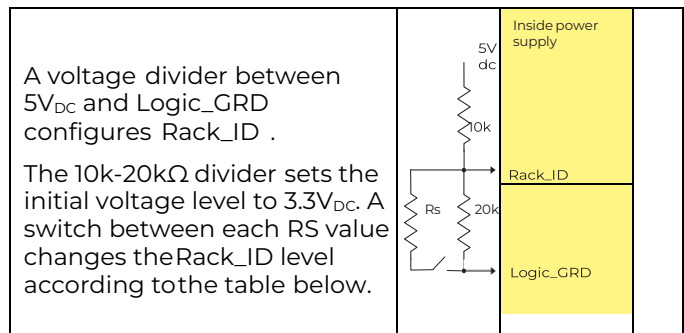
| Device | Address | Address Bit Assignments (Most to Least Significant) | | | | | | | | |
|-------------------|---------|---|---|---|----|----|----|----|-----|--|
| | | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
| μP | 40 – 4F | 1 | 0 | 0 | A3 | A2 | A1 | A0 | R/W | |
| Broadcast | 00 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |
| ARA ¹⁶ | C | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 1 | |
| | | MSB | | | | | | | LSB | |

Unit_ID: Up to 10 different units are selectable



| Unit_ID | Voltage level | RS (± 0.1%) |
|---------|---------------|-------------|
| Invalid | 3.30 | |
| 1 | 3.00 | 100k |
| 2 | 2.67 | 45.3k |
| 3 | 2.34 | 24.9k |
| 4 | 2.01 | 15.4k |
| 5 | 1.68 | 10.5k |
| 6 | 1.35 | 7.15k |
| 7 | 1.02 | 4.99k |
| 8 | 0.69 | 2.49k |
| 9 | 0.36 | 1.27k |
| 10 | 0 | 0 |

Unit_ID: Up to 8 different units are selectable



¹⁶ Implement if feasible, this is a 'read' only address
Page 14

Technical Specifications (continued)

Control Signals (continued)

| Rack_ID | Voltage level | RS ($\pm 0.1\%$) |
|---------|---------------|--------------------|
| 1 | 3.3 | open |
| 2 | 2.8 | 35.2k |
| 3 | 2.3 | 15k |
| 4 | 1.8 | 8k |
| 5 | 1.4 | 4.99k |
| 6 | 1 | 2.87k |
| 7 | 0.5 | 1.27k |
| 8 | 0 | 0 |

Configuration of the A3 – A0 bits: The rectifier will determine the configured address based on the Unit_ID and Rack_ID voltage levels as follows (the order is A3 – A0):

| | | Unit_ID | | | | |
|---------|---|---------|------|------|------|------|
| | | 1 | 2 | 3 | 4 | 5 |
| Rack_ID | 1 | 0000 | 0001 | 0010 | 0011 | |
| | 2 | 0100 | 0101 | 0110 | 0111 | |
| | 3 | 1000 | 1001 | 1010 | 1011 | |
| | 4 | 1100 | 1101 | 1110 | 1111 | |
| | 5 | | | | | |
| | 6 | 0000 | 0001 | 0010 | 0011 | 0100 |
| | 7 | 0101 | 0110 | 0111 | 1000 | 1001 |
| | 8 | 1010 | 1011 | 1100 | 1101 | 1110 |

Unit X Rack : 4 X 4 and 5 X 5

| | | Unit_ID | | | | |
|---------|---|---------|------|------|------|------|
| | | 6 | 7 | 8 | 9 | 10 |
| Rack_ID | 1 | 0000 | 0001 | | | |
| | 2 | 0010 | 0011 | | | |
| | 3 | 0100 | 0101 | | | |
| | 4 | 0110 | 0111 | 0000 | 0001 | 0010 |
| | 5 | 1000 | 1001 | 0011 | 0100 | 0101 |
| | 6 | 1010 | 1011 | 0110 | 0111 | 1000 |
| | 7 | 1100 | 1101 | 1001 | 1010 | 1011 |
| | 8 | 1110 | 1111 | 1100 | 1101 | 1110 |

Unit X Rack : 2 X 8 and 3 X 5

Address detection: The Slot_ID pin must be connected to **V_{out}(-)** in order to deliver output power. This connection provides a second interlock feature. This connection may be a short circuit or any resistance up to 100 kohm, to allow addressing in RS485 mode as described below

Device address in RS485 mode: The address in RS485 mode is divided into three components; Bay_ID, Slot_ID and Shelf_ID

Bay_ID: The Unit_ID definition in I²C mode becomes the bay id in RS485 mode.

Slot_ID: Up to 10 different rectifiers could be positioned across a 19" shelf if the rectifiers are located vertically within the shelf. The resistor below needs to be placed between Slot_ID and V_{out} (-). Internal pull-up to 3.3V is 10k Ω .

| Slot | Resistor | Voltage |
|---------|----------|---------|
| invalid | none | 3.3V |
| 1 | 100k | 3V |
| 2 | 45.3k | 2.67V |
| 3 | 24.9k | 2.34V |
| 4 | 15.4k | 2.01V |
| 5 | 10.5k | 1.68V |

| Slot | Resistor | Voltage |
|------|----------|---------|
| 6 | 7.15k | 1.35V |
| 7 | 4.99k | 1.02V |
| 8 | 2.49k | 0.69V |
| 9 | 1.27k | 0.36V |
| 10 | 0 | 0 |

In the -EC & -ES versions, a 100 k Ω resistor is installed internally to enable the output & indicate slot no. 1. To indicate another slot number, an external resistor should be connected so the parallel combination is the resistance shown in the table above.

Shelf_ID: When placed horizontally up to 10 shelves can be stacked on top of each other in a fully configured rack. The shelf will generate the precision voltage level tabulated below referenced to V_{out} (-).

| Shelf | V _{MIN} | V _{NOM} | V _{MAX} |
|-------|------------------|------------------|------------------|
| 1 | 2.3 | 2.5 | 2.7 |
| 2 | 4.7 | 5.0 | 5.3 |
| 3 | 7.4 | 7.5 | 7.6 |
| 4 | 9.5 | 10.0 | 10.5 |
| 5 | 11.8 | 12.5 | 13.2 |
| 6 | 14.2 | 15.0 | 15.8 |
| 7 | 16.6 | 17.5 | 18.4 |
| 8 | 19 | 20.0 | 21 |
| 9 | 21.3 | 22.5 | 23.6 |
| 10 | 23.8 | 25.0 | 26.3 |

Global Broadcast: This is a powerful command because it instruct all rectifiers to respond simultaneously. A read instruction should never be accessed globally. The rectifier should issue an 'invalid command' state if a 'read' is attempted globally.

For example, changing the 'system' output voltage requires the global broadcast so that all paralleled rectifiers change their output simultaneously. This command can also turn OFF the 'main' output or turn ON the 'main' output of all rectifiers simultaneously. Unfortunately, this command does have a side effect. Only a single rectifier needs to pull down the ninth acknowledge bit. To be certain that each rectifier responded to the global instruction, a READ instruction should be executed to each rectifier to verify that the command properly executed. The GLOBAL BROADCAST command should only be executed for write instructions to slave devices

Technical Specifications (continued)

Control Signals (continued)

Alert Response Address (ARA): This feature enables the ‘master’ to rapidly determine which ‘slave’ rectifier triggered the Alert# signal without having to poll each rectifier one at a time. During normal operation the rectifier activates (pulls down LO) the Alert# signal line indicating that it needs attention when a ‘state’ change occurs. The master can determine who pulled the ‘alert’ line by sending out the alert- response-address, address 12b, with a ‘read’ instruction. If the rectifier triggered the ‘alert’ it should respond back with its address. The instruction takes the form below;

| | | | | | | | | | | |
|---|-------------|--|----|---|------------|---|---|-----|---|---|
| 1 | 8 | | 1 | 8 | | 1 | 8 | 1 | 1 | |
| S | ARA address | | Rd | A | My address | | A | PEC | A | P |

If during the ARA response multiple rectifiers send out their addresses, then the actual address received by the master is the lowest address from the combinations of those rectifiers that responded.

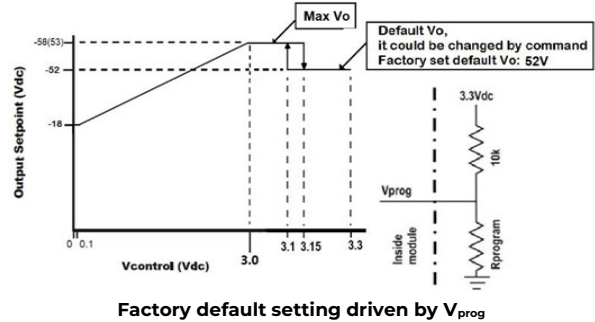
The ‘my address’ field contains the address of the rectifier in the 7 most significant bits (msb) of the byte. The lsb of the byte is a don’t care, it could be a 0 or a 1. For more information refer to the SMBus specification

The μ C needs to read the actual **my address** data byte that is sent back to the master. If the **my address** data byte agrees with the address of this unit, then, and only then, the μ C needs to clear (de-assert) its Alert# signal. Thus, the rectifier whose address has been sent out gets de-asserted from the joint Alert# line.

If the Alert# line is still asserted, the host should send out an ARA request again and find out who else asserted Alert#. This process needs to continue until the Alert# is released which is a clear indication that all rectifiers that asserted Alert# have had their status states read back.

Voltage programming (V_{prog}): Hardware voltage programming controls the output voltage until a software command to change the output voltage is executed. Then software voltage programming overrides the hardware margin setting and the rectifier no longer listens to any hardware margin settings until power to the controller is interrupted, for example if input power or bias power is cycled off, then on.

Under hardware voltage programming, an analog voltage on V_{prog} can vary the output voltage linearly from $18V_{dc}$ to $53V_{dc}$ (FB version) or $18V_{dc}$ to $58V_{dc}$ (FB2 version) for $0.1V \leq V_{prog} \leq 3.0V$ referenced to LGND. If V_{prog} is raised $\geq 3.2V$, V_{out} is reset to its default value of $52V$. If $0 \leq V_{prog} < 0.1V$, the output remains at its minimum value of $18V$.



For the blind-mate rectifier option, the V_{prog} pin level can be set by an external resistor divider between an external voltage source and LGND as shown in the figure above, or by a precision voltage source connected between V_{prog} and LGND.

For the non-blind-mate options, the resistor divider shown above for V_{prog} is internal, connected to the $5V$ bias supply with $46.4\text{ kohm } 1\%$ pull-up resistor. The “ V_{out} Adjust” potentiometer ($100k$) is connected between V_{prog} and LGND when the “Initial V_{out} ” control switch is set to “Trimmed.”

When bias power to the controller is recycled, the controller restarts into its default configuration, programmed to set the output voltage as instructed by the V_{prog} pin. Again, subsequent software commanded settings permanently override the “ V_{out} Adjust” setting.

Before enabling a hot-plugged rectifier, the output voltage should be set to a safe level-no higher than the bus voltage-to avoid a transient or possible shutdown. Assuming the shelf enables the rectifier by shorting ON/OFF to LGND, the shelf should also pull V_{prog} down to a safe level. This could be $0V$ (V_{prog} shorted to LGND), setting V_{out} to $18V$, or some higher voltage that corresponds to an output voltage no greater than the bus voltage. The hot-plugged rectifier will remain at this output voltage, possibly supplying no power, until commanded to a higher voltage.

Load share (Ishare): This is a single wire analog signal that is generated and acted upon automatically by rectifiers connected in parallel. Ishare pins should be connected to each other for rectifiers, if active current share among the rectifiers is desired. No resistors or capacitors should get connected to this pin.

ON/OFF: Controls the main $52V_{DC}$ output when either analog control or PMBus protocols are selected, as configured by the Protocol pin. This pin must be pulled low to turn ON the rectifier. The rectifier will turn OFF if either the ON/OFF or the Interlock pin is released. This signal is referenced to LGND. Note that in RS485 mode the ON/OFF pin is ignored.

Technical Specifications (continued)

Control Signals (continued)

Interlock: This is a shorter pin utilized for hot-plug applications to ensure that the rectifier turns OFF before the power pins are disengaged. It also ensures that the rectifier turns ON only after the power pins have been engaged. Must be connected to V_OUT (-) for the rectifier to be ON, done internally for the -EC and -ES versions.

Module Present: This signal is tied to LGND inside the rectifier. It's intent is to provide a signal to the system that a rectifier is physically present in the slot.

8V_INT: Single wire connection between rectifiers, Provides bias to the DSP of an unpowered rectifier.

Status signals

Power Good Warning (PG#): This signal is HI when the main output is being delivered and goes LO if the main output is about to decay below regulation. Note that should a catastrophic failure occur, the signal may not be fast enough to provide a meaningful warning. PG# also pulses at a 1ms duty cycle if the unit is in overload.

Fault#: A TTL compatible status signal representing whether a Fault occurred. This signal needs to be pulled HI externally through a resistor. This signal goes LO for any failure that requires rectifier replacement. These faults may be due to:

- Over-temperature shutdown
- Over-voltage shutdown
- Internal Rectifier Fault

Over temp warning (OTW#): A TTL compatible status signal representing whether an over temperature exists. This signal needs to be pulled HI externally through a resistor.

If an over temperature should occur, this signal would pull LO for approximately 10 seconds prior to shutting down the rectifier. In its default configuration, the unit would restart if internal temperatures recover within normal operational levels. At that time the signal reverts back to its open collector (HI) state.

Serial Bus Communications

The I²C interface facilitates the monitoring and control of various operating parameters within the unit and transmits these on demand over an industry standard I²C Serial bus.

All signals are referenced to 'LGND'.

Pull-up resistors: The clock, data, and Alert# lines do not have any internal pull-up resistors inside the rectifier. The customer is responsible for ensuring that the transmission impedance of the communications lines complies with I²C and SMBus standards.

Serial Clock (SCL): The clock pulses on this line are generated by the host that initiates communications across the I²C Serial bus. This signal needs to be pulled HI externally through a resistor as necessary to ensure that rise and fall time timing and the maximum sink current is in compliance to the I²C /SMBus specifications.

Serial Data (SDA): This line is a bi-directional data line. This signal needs to be pulled HI externally through a resistor as necessary to ensure that rise and fall time timing and the maximum sink current is in compliance to the I²C /SMBus specifications.

Technical Specifications (continued)

Digital Feature Descriptions

PMBus™ compliance: The rectifier is fully compliant to the Power Management Bus (PMBus™) rev1.2 requirements. This Specification can be obtained from www.pmbus.org.

'Manufacturer Specific' commands are used to support additional instructions that are not in the PMBus™ specification.

All communication over the PMBus interface must support the Packet Error Checking (PEC) scheme. The PMBus master must generate the correct PEC byte for all transactions, and check the PEC byte returned by the rectifier.

The Alert# response protocol (ARA) whereby the PMBus Master can inquire who activated the Alert# signal is also supported. This feature is described in more detail later on.

Non-volatile memory is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory. Only those specifically identified as capable of being stored can be saved. (see the Table of Commands for which command parameters can be saved to non-volatile storage).

Non-supported commands: Non supported commands are flagged by setting the appropriate STATUS bit and issuing an Alert# to the 'host' controller.

If a non-supported read is requested the rectifier will return 0x00h for data.

Data out-of-range: The rectifier validates data settings and sets the data out-of-range bit and Alert# if the data is not within acceptable range.

Master/Slave: The 'host controller' is always the MASTER. Rectifiers are always SLAVES. SLAVES cannot initiate communications or toggle the Clock. SLAVES also must respond expeditiously at the command of the MASTER as required by the clock pulses generated by the MASTER.

Clock` stretching: The 'slave' μ Controller inside the rectifier may initiate clock stretching if it is busy and it desires to delay the initiation of any further communications. During the clock stretch the 'slave' may keep the clock LO until it is ready to receive further instructions from the host controller. The maximum clock stretch interval is 25ms.

The host controller needs to recognize this clock stretching, and refrain from issuing the next clock signal, until the clock line is released, or it needs to delay the next clock pulse beyond the clock stretch interval of the rectifier. Note that clock stretching can only be performed after completion of transmission of the 9th ACK bit, the exception being the START command.

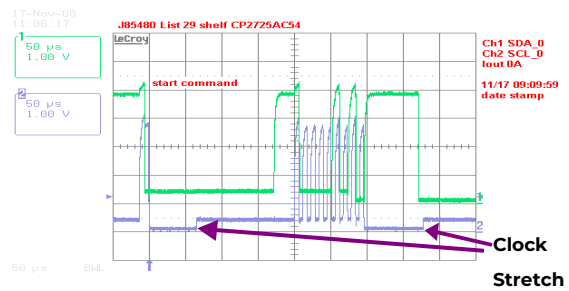


Figure 15. Example waveforms showing clock stretching

I²C Bus Lock-Up detection: The device will abort any transaction and drop off the bus if it detects the bus being held low for more than 35ms.

Communications speed: Both 100kHz and 400kHz clock rates are supported. The rectifiers default to the 100kHz clock rate.

Packet Error Checking (PEC): The rectifier will not respond to commands without the trailing PEC. The integrity of communications is compromised if packet error correction is not employed. There are many functional features, including turning OFF the main output, that require validation to ensure that the desired command is executed.

PEC is a CRC-8 error-checking byte, based on the polynomial $C(x) = x^8 + x^2 + x + 1$, in compliance with PMBus™ requirements. The calculation is based in all message bytes, including the originating write address and command bytes preceding read instructions. The PEC is appended to the message by the device that supplied the last byte.

Alert#: The rectifier can issue Alert# driven from either its internal micro controller (μ C) or from the I²C bus master selector stage. That is, the Alert# signal of the internal μ C funnels through the master selector stage that buffers the Alert# signal and splits the signal to the two Alert# signal pins exiting the rectifier. In addition, the master selector stage signals its own Alert# request to either of the two Alert# signals when required.

Technical Specifications (continued)

Digital Feature Descriptions (Continued)

The μC driven Alert# signal informs the 'master/host' controller that either a STATE or ALARM change has occurred. Normally this signal is HI. The signal will change to its LO level if the rectifier has changed states and the signal will be latched LO until the rectifier receives a 'clear_faults' instruction.

The signal will be triggered for any state change, including the following conditions;

- V_{IN} under or over voltage
- V_{out} under or over voltage
- I_{OUT} over current
- Over Temperature warning or fault
- Communication error
- PEC error
- Invalid command
- Internal faults
- Both Alert#_0 and -1 are asserted during power up to notify the master that a new rectifier has been added to the bus.

The rectifier will clear the Alert# signal (release the signal to its HI state) upon the following events:

- Receiving a CLEAR_FAULTS command
- Bias power to the processor is recycled

The rectifier will re-assert the Alert line if the internal state of the rectifier has changed, even if that information cannot be reported by the status registers until a clear_faults is issued by the host. If the Alert asserts, the host should respond by issuing a clear_faults to retire the alert line (this action also provides the ability to change the status registers). This action triggers another Alert assertion because the status registers changed states to report the latest state of the rectifier. The host is now able to read the latest reported status register information and issue a clear_faults to retire the Alert signal.

Re-initialization: The I²C code is programmed to re-initialize if no activity is detected on the bus for 5 seconds. Re- initialization is designed to guarantee that the I²C μC Controller does not hang up the bus. Although this rate is longer than the timing requirements specified in the SMBus specification, it had to be extended in order to ensure that a re-initialization would not occur under normal transmission rates. During the few μs required to accomplish re-initialization the I²C μC Controller may not recognize a command sent to it. (i.e. a start condition).

Read back delay: The rectifier issues the Alert# notification as soon as the first state change occurred. During an event a number of different states can be transitioned to before the final event occurs. If a read back is implemented rapidly by the host a successive Alert# could be triggered by the transitioning state of the rectifier. In order to avoid successive Alert# s and read back and also to avoid reading a transitioning state, it is prudent to wait more than 2 seconds after the receipt of an Alert# before executing a read back. This delay will ensure that only the final state of the rectifier is captured.

Successive read backs: Successive read backs to the rectifier should not be attempted at intervals faster than every one second. This time interval is sufficient for the internal processors to update their data base so that successive reads provide fresh data.

Dual, redundant buses: Two independent I²C lines provide true communications bus redundancy and allow two independent controllers to sequentially control the rectifier. For example, a short or an open connection in one of the I²C lines does not affect communications capability on the other I²C line. Failure of a 'master' controller does not affect the rectifiers and the second 'master' can take over control at any time.

Conceptually a Digital Signal Processor (DSP) referenced to $V_{\text{out}}(-)$ of the rectifier provides secondary control. A Bidirectional Isolator provides the required isolation between power ground, $V_{\text{out}}(-)$ and signal/ logic ground (LGND). A secondary micro controller provides instructions to and receives operational data from the DSP. The secondary micro controller also controls the communications over two independent I²C lines to two independent system controllers.



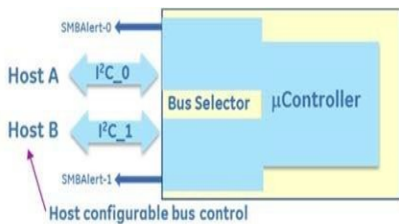
Technical Specifications (continued)

Digital Feature Descriptions (Continued)

The secondary micro controller is designed to default to I²C_0 when powered up. If only a single system controller is utilized, it should be connected to I²C_0. In this case the I²C_1 line is totally transparent as if it does not exist.

If two independent system controllers are utilized, then one of them should be connected to I²C_0 and the other to I²C_1.

At power up the master connected to I²C_0 has control of the bus. See the section on Dual Master Control for further description of this feature .



Conceptual representation of the dual I²C bus system.

PMBus™ Commands

Standard instruction: Up to two bytes of data may follow an instruction depending on the required data content. Analog data is always transmitted as LSB followed by MSB. PEC is mandatory and includes the address and data fields.

| | | | | |
|---|---------------|----|---|--------------|
| 1 | 8 | 1 | 8 | 1 |
| S | Slave address | Wr | A | Command Code |

| | | | | | | |
|---------------|---|----------------|---|-----|---|---|
| 8 | 1 | 8 | 1 | 8 | 1 | 1 |
| Low data byte | A | High data byte | A | PEC | A | P |

Master to Slave Slave to Master

SMBUS annotations; S – Start , Wr – Write, Sr – re-Start, Rd – Read, A – Acknowledge, NA – not-acknowledged, P – Stop

Standard READ: Up to two bytes of data may follow a READ request depending on the required data content. Analog data is always transmitted as LSB followed by MSB. PEC is mandatory and includes the address and data fields.

| | | | | | |
|---|---------------|----|---|--------------|---|
| 1 | 7 | 1 | 1 | 8 | 1 |
| S | Slave address | Wr | A | Command Code | A |

| | | | | | |
|----|---------------|----|---|-----|---|
| 1 | 7 | 1 | 1 | 8 | 1 |
| Sr | Slave Address | Rd | A | LSB | A |

| | | | | |
|-----|---|-----|----|---|
| 8 | 1 | 8 | 1 | 1 |
| MSB | A | PEC | NA | P |

Block communications: When writing or reading more than two bytes of data at a time BLOCK instructions for WRITE and READ commands are used instead of the Standard Instructions above to write or read any number of bytes greater than two.

Block Read Format:

| | | | | | |
|---|---------------|----|---|--------------|---|
| 1 | 7 | 1 | 1 | 8 | 1 |
| S | Slave address | Wr | A | Command Code | A |

| | | | | | |
|----------------|---|--------|---|--------|---|
| 8 | 1 | 8 | 1 | 8 | 1 |
| Byte count = N | A | Data 1 | A | Data 2 | A |

| | | | | | | |
|-------|---|--------|---|-----|---|---|
| 8 | 1 | 8 | 1 | 8 | 1 | 1 |
| | A | Data N | A | PEC | A | P |

Block Read Format:

| | | | | | |
|---|---------------|----|---|---------|---|
| 1 | 7 | 1 | 1 | 8 | 1 |
| S | Slave address | Wr | A | Command | A |

| | | | |
|----|---------------|----|---|
| 1 | 7 | 1 | 1 |
| Sr | Slave Address | Rd | A |

| | | | | | |
|----------------|---|--------|---|--------|---|
| 8 | 1 | 8 | 1 | 8 | 1 |
| Byte count = N | A | Data 1 | A | Data 2 | A |

| | | | | | | |
|-------|---|--------|---|-----|-----|---|
| 8 | 1 | 8 | 1 | 8 | 1 | 1 |
| | A | Data N | A | PEC | NA+ | P |

Linear Data Format: The definition is identical to Part II of the PMBus Specification. All standard PMBus values, with the exception of output voltage related functions, are represented by the linear format described below. Output voltage functions are represented by a 16 bit mantissa. Output voltage has a E=-9 constant exponent.

The Linear Data Format is a two byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent or scaling factor, its format is shown below.

| Data Byte High | | | | | | Data Byte Low | | | | | | | | | | |
|----------------|--------------|---|---|---|---|---------------|--------------|---|---|---|---|---|---|---|---|---|
| Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| | Exponent (E) | | | | | | Mantissa (M) | | | | | | | | | |

The relationship between the Mantissa, Exponent, and Actual Value (V) is given by the following equation:

$$V = M * 2^E$$

Where: V is the value, M is the 11-bit, two's complement mantissa, E is the 5-bit, two's complement exponent

Technical Specifications (continued)

Standard features

Supported features that are not readable: The commands below are supported at the described setting but they cannot be read back through the command set.

| Command | Comments |
|-----------------------|--|
| ON_OFF_CONFIG (0x02) | Both the CNTL pin, and the OPERATION command, enabling or disabling the output, are supported. Other options are not supported. |
| Capability (0x19) | 400KHz, ALERT# |
| PMBus revision (0x98) | 1.2 |

Status and Alarm registers: The registers are updated with the latest operational state of the rectifier. For example, whether the output is ON or OFF is continuously updated with the latest state of the rectifier. However, alarm information is maintained until a clear_faults command is received from the host. For example, the shutdown or OC_fault bits stay in their alarmed state until the host clears the registers.

A clear_faults clears all registers. If a fault still persists after the clear_faults is commanded, the register bit annunciating the fault is reset again.

Adjustment Ranges

Some of the PMBus commands on the next page enable adjustment of operating parameters within the ranges specified below. If a command is received with a value outside this range, the module does not change the present setting. Instead it uses CML to indicate a communication failure.

| Command | Hex Code | Adjustment range | | |
|------------------------|----------|------------------|------|------|
| | | Default HL (LL) | Low | High |
| Vout_command | 0x21 | 52 | 17 | 54 |
| Vout_OV_fault_limit | 0x40 | 55 | 16 | 55 |
| Vout_OV_warn_limit | 0x42 | 54 | 16 | 55 |
| Vout_UV_warn_limit | 0x43 | 17 | 16 | 55 |
| Vout_UV_fault_limit | 0x44 | 16 | 16 | 55 |
| Iout_OC_fault_limit | 0x46 | 68 (30) | 0 | 68 |
| Iout_OC_LV_fault_limit | 0x48 | 16 | 16 | 55 |
| Iout_OC_warn_limit | 0x4A | 67.3 (29.8) | 0 | 67.3 |
| OT_fault_limit | 0x4F | 110 | 0 | 150 |
| OT_warn_limit | 0x51 | 105 | 0 | 150 |
| Vin_OV_fault_limit | 0x55 | 270 | 90 | 270 |
| Vin_OV_warn_limit | 0x57 | 265 | 90 | 265 |
| Vin_UV_warn_limit | 0x58 | 87.5 | 87.5 | 265 |
| Vin_UV_fault_limit | 0x59 | 80 | 80 | 270 |

Command Descriptions

Commands are listed in numerical order, with a summary table at the end of this section.

Operation (0x01): Turns the 52V output ON or OFF. The default state is **ON** at power up. Only the following data bytes are supported:

| FUNCTION | DATA BYTE |
|----------|-----------|
| Unit ON | 0x80 |
| Unit OFF | 0x00 |

To **RESET** the rectifier using this command, command the rectifier OFF, wait at least 2 seconds, and then command the rectifier back ON. All alarms and shutdowns are cleared during a restart.

Clear_faults (0x03): Clears all STATUS and FAULT registers and resets the Alert# line of the I2C side in control. The I2C side not in control cannot clear registers in the rectifier. This command is always executable.

If a fault still persists after the issuance of the clear_faults command, the specific registers indicating the fault first clears but then get set again to indicate that the unit is still in the fault state.

WRITE_PROTECT register (0x10): Used to control writing to the PMBus device. The intent of this command is to provide protection against accidental changes. All supported commands may have their parameters read, regardless of the write_protect settings. The contents of this register cannot be stored into non-volatile memory using the Store_user_code command. The default setting of this register is enable_all_writes, write_protect 0x00h. The write_protect command must always be accepted.

| FUNCTION | DATA BYTE |
|---|-----------|
| Enable all writes | 00 |
| Disable all writes except write_protect | 80 |
| Disable all writes except write_protect and OPERATION | 40 |

Restore_Default_All (0x12): Restores all operating register values and responses to the factory default parameters set in the rectifier. The factory default cannot be changed.

Technical Specifications (continued)

Command Descriptions (continued)

Restore_default_code (0x14): Restore only a specific register parameter into the operating register section of the rectifier.

Store_user_code (0x17): Changes the user default setting of a single register. In this fashion some protection is offered to ensure that only those registers that are desired to be changed are in fact changed.

Restore_user_code (0x18): Restores the user default setting of a single register.

Vout_mode (0x20): This is a 'read only' register. The upper three bits specify the supported data format, in this case Linear mode. The lower five bits specify the exponent of the data in two's complement binary format for output voltage related commands, such as Vout_command. These commands have a 16 bit mantissa. The exponent is fixed by the rectifier and is returned by this command

| Mode | Bits [7:5] | Bits [4:0] (Parameter) |
|--------|------------|------------------------|
| Linear | 000b | xxxxxb |

Vout_Command (0x21) : Used to dynamically change the output voltage of the rectifier. This command can also be used to change the factory programmed default set point of the rectifier by executing a store-user instruction that changes the user default firmware set point.

The default set point can be overridden by the V_{prog} signal pin which is designed to override the firmware based default setting during turn ON.

In parallel operation, changing the output voltage should be performed simultaneously to all rectifiers using the Global Address (Broadcast) feature. If only a single rectifier is instructed to change its output, it may attempt to source all the required power which can cause either a power limit or shutdown condition.

Digital programming of output voltage overrides the set point voltage configured by the V_{prog} signal pin as long as ac input power is applied continuously. The program no longer looks at the 'V_{prog} pin' and will not respond to any hardware voltage settings. If ac input power is removed, the μ Controller is reset to its default configuration, looking at the V_{prog} signal for output voltage control. In many applications, the V_{prog} pin is used for setting initial conditions, if different that the factory setting. Software programming then takes over once a Vout_Command is sent.

To properly hot-plug a rectifier into a live backplane, the system generated voltage should match either the factory adjusted firmware level or the voltage level reconfigured by the V_{prog} pin. Otherwise, the voltage state of the plugged in rectifier could be significantly different than the powered system.

Programmed voltage range: 18V_{DC} – 53V_{DC} for FB version; 18V_{DC} – 58V_{DC} for FB2 version.

A voltage programming example: The task: set the output voltage to 50.45V_{DC}

This rectifier supports the linear mode of conversion specified in the PMBus™ specification. The supported output voltage exponent is documented in the Vout_mode (0x20) command. The exponent for output voltage setting is 2-9 (see the PMBus™ specification for reading this command). Calculate the required voltage setting to be sent; $50.45 \times 2^9 = 25830$. Convert this decimal number into its hex equivalent: 64E6 and send it across the bus LSB first and then MSB; E664 with the trailing PEC.

Vin_ON (0x35): This is a 'read only' register that informs the controller at what input voltage level the rectifier turns ON. The default value is tabulated in the data section. The value is contingent on whether the rectifier operates in the low_line or high_line mode.

The default value is tabulated in the data section. The value is contingent on whether the rectifier operates in the low_line or high_line mode.

Vin_OFF (0x36): This is a 'read only' register that informs the controller at what input voltage level the rectifier turns OFF.

The default value is tabulated in the data section. The value is contingent on whether the rectifier operates in the low_line or high_line mode.

Vout_OV_fault_limit (0x40): Sets the value at which the main output voltage will shut down. The default OV_fault value is set at 60V_{dc}. This level can be permanently changed and stored in non-volatile memory.

Vout_OV_fault_response (0x41): This is a 'read only' register. The only allowable state is a latched state after three retry attempts.

An overvoltage shutdown is followed by three attempted restarts, each successive restart delayed 1 second. If within a 1 minute window three attempted restarts failed, the unit will latch OFF. If less than 3 shutdowns occur within the 1 minute window then the count for latch OFF resets and the 1 minute window starts all over again. This performance cannot be changed.

Technical Specifications (continued)

Command Descriptions (continued)

Restart after a latched state: Either of four restart mechanisms is available;

- The hardware pin ON/OFF may be cycled OFF and then ON.
- The unit may be commanded to restart via i²c through the Operation command by first turning OFF then turning ON .
- The third way to restart is to remove and reinsert the unit.
- The fourth way is to turn OFF and then turn ON ac power to the unit.

A successful restart clears all STATUS and ALARM registers.

A power system that is comprised of a number of rectifiers could have difficulty restarting after a shutdown event because of the non-synchronized behavior of the individual rectifiers. Implementing the latch-off mechanism permits a synchronized restart that guarantees the simultaneous restart of the entire system.

A synchronous restart can be implemented by;

- Issuing a GLOBAL OFF and then a GLOBAL ON command to all rectifiers
- Toggling Off and then ON the ON/OFF signal, if this signal is paralleled among the rectifiers.
- Removing and reapplying input commercial power to the entire system.

The rectifiers should be OFF for at least 20 – 30 seconds in order to discharge all internal bias supplies and reset the soft start circuitry of the individual rectifiers.

Vout_OV_warn_limit (0x42): Sets the value at which a warning will be issued that the output voltage is too high. The default OV_warn limit is set at 56V_{dc}. Exceeding the warning value will set the Alert# signal. This level can be permanently changed and stored in non-volatile memory.

Vout_UV_warn_limit (0x43): Sets the value at which a warning will be issued that the output voltage is too low. The default UV_warning limit is set at 41V_{dc}. Reduction below the warning value will set the Alert# signal. This level can be permanently changed and stored in non-volatile memory.

Vout_UV_fault_limit (0x44): Sets the value at which the rectifier will shut down if the output gets below this level when not in overload (see 0x48 for overload). The default UV_fault limit is set at 36V_{dc}. This register is masked if the UV is caused by interruption of the input voltage to the rectifier. This level can be permanently changed and stored in non-volatile memory.

Vout_UV_fault_response (0x45): Sets the response if the output voltage falls below the UV_fault_limit. The default UV_fault_response is restart (0xC0). The only two allowable states are latched (0x80) and restart (0xC0). The default response state can be permanently changed and stored in non-volatile memory.

Iout_OC_fault_limit (0x46): Sets the value at which the rectifier will shut down at High Line. This level can be permanently changed and stored in non-volatile memory. The Low Line level is not adjustable, it is set at 30A.

Iout_OC_fault_response (0x47): Sets the response if the output overload exceeds the OC_Fault_limit value. The default OC_fault_response is hiccup (0xF8). The only two allowable states are latched (0xC0) or hiccup. The default response state can be permanently changed and stored in non-volatile memory. The response is the same for both low_line and high_line operations.

Iout_OC_LV_fault_limit (0x48): Sets the value at which the rectifier will shut down when the rectifier is in overload and the output gets below this level. The default fault limit is set at 36V_{dc}. This register is masked if the UV is caused by interruption of the input voltage to the rectifier. This level can be permanently changed and stored in non-volatile memory.

Iout_OC_warn_limit (0x4A): Sets the value at which the rectifier issues a warning that the output current is getting too close to the shutdown level at high line. This level can be permanently changed and stored in non-volatile memory. The Low Line level is not adjustable, it is set at 29A.

OT_fault_limit (0x4F): Sets the value at which the rectifier responds to an OT event, sensed by the dc-sec sensor. The response is defined by the OT_fault_response register.

Technical Specifications (continued)

Command Descriptions (continued)

OT_fault_response (0x50): Sets the response if the output overtemperature exceeds the OT_Fault_limit value. The default OT_fault_response is hiccup (0xC0). The only two allowable states are latched (0x80) or hiccup. The default response state can be permanently changed and stored in non-volatile memory.

OT_warn_limit (0x51): Sets the value at which the rectifier issues a warning when the dc-sec temperature sensor exceeds the warn limit.

Vin_OV_fault_limit (0x55): Sets the value at which the rectifier shuts down because the input voltage exceeds the allowable operational limit. The default Vin_OV_fault_limit is set at 300V_{ac}. This level can be permanently lowered and stored in non-volatile memory.

Vin_OV_fault_response (0x56): Sets the response if the input voltage level exceeds the Vin_OV_fault_limit value. The default Vin_OV_fault_response is restart (0xC0). The only two allowable states are latched (0x80) and restart (0xC0). The default response state can be permanently changed and stored in non-volatile memory.

Vin_UV_warn_limit (0x58): This is another warning flag indicating that the input voltage is decreasing dangerously close to the low input voltage shutdown level. The default UV_fault_limit is 90V_{ac}. This level can be permanently raised, but not lowered, and stored in non-volatile memory.

Vin_UV_fault_limit (0x59): Sets the value at which the rectifier shuts down because the input voltage falls below the allowable operational limit. The default Vin_UV_fault_limit is set at 85V_{ac}. This level can be permanently raised and stored in non-volatile memory.

Vin_UV_fault_response (0x5A): Sets the response if the input voltage level falls below the Vin_UV_fault_limit value. The default Vin_UV_fault_response is restart (0xC0). The only two allowable states are latched (0x80) and restart (0xC0). The default response state can be permanently changed and stored in non-volatile memory.

STATUS_BYTE (0x78) : Returns one byte of information with a summary of the most critical device faults.

| Bit Position | Flag | Default Value |
|--------------|------------------------------|---------------|
| 7 | Unit is busy | 0 |
| 6 | OUTPUT OFF | 0 |
| 5 | VOUT Overvoltage Fault | 0 |
| 4 | IOUT Overcurrent Fault | 0 |
| 3 | VIN Undervoltage Fault | 0 |
| 2 | Temperature Fault or Warning | 0 |
| 1 | CML (Comm. Memory Fault) | 0 |
| 0 | None of the above | 0 |

STATUS_WORD (0x79): Returns status_byte as the low byte and the following high_byte.

| Bit Position | Flag | Default Value |
|--------------|--------------------------|---------------|
| 7 | VOUT Fault or Warning | 0 |
| 6 | IOUT Fault or Warning | 0 |
| 5 | INPUT Fault or Warning | 0 |
| 4 | MFR SPECIFIC | 0 |
| 3 | POWER_GOOD# (is negated) | 0 |
| 2 | N/A | 0 |
| 1 | OTHER | 0 |
| 0 | UNKNOWN Fault or Warning | 0 |

STATUS_VOUT (0x7A): Returns one byte of information of output voltage related faults.

| Bit Position | Flag | Default Value |
|--------------|-----------------|---------------|
| 7 | VOUT OV Fault | 0 |
| 6 | VOUT_OV_WARNING | 0 |
| 5 | VOUT_UV_WARNING | 0 |
| 4 | VOUT UV Fault | 0 |
| 3 - 0 | X | 0 |

STATUS_IOUT (0x7B): Returns one byte of information of output current related faults.

| Bit Position | Flag | Default Value |
|--------------|------------------------|---------------|
| 7 | IOUT OC Fault | 0 |
| 6 | IOUT OC LV Fault | 0 |
| 5 | IOUT OC Warning | 0 |
| 4 | X | 0 |
| 3 | CURRENT SHARE Fault | 0 |
| 2 | IN POWER LIMITING MODE | 0 |
| 1 - 0 | X | 0 |

The OC Fault limit sets where current limit is set. The rectifier actually shuts down below the LV fault limit setting.

Technical Specifications (continued)

Command Descriptions (continued)

STATUS_INPUT (0X7C): Returns one byte of information of input voltage related faults.

| Bit Position | Flag | Default Value |
|--------------|------------------------|---------------|
| 7 | VIN_OV_Fault | 0 |
| 6 | VIN_OV_Warning | 0 |
| 5 | VIN_UV_Warning | 0 |
| 4 | VIN_UV_Fault | 0 |
| 3 | Unit OFF for low input | 0 |
| 2 | IIN_OC_Fault | 0 |
| 1 - 0 | X | 0 |

STATUS_TEMPERATURE (0x7D): Returns one byte of information of temperature related faults.

| Bit Position | Flag | Default Value |
|--------------|------------|---------------|
| 7 | OT Fault | 0 |
| 6 | OT Warning | 0 |
| 5 - 0 | X | 0 |

STATUS_CML (0x7E): Returns one byte of information of communication related faults

| Bit Position | Flag | Default Value |
|--------------|---------------------------|---------------|
| 7 | Invalid/Unsupported | 0 |
| 6 | Invalid/Unsupported Data | 0 |
| 5 | Packet Error Check Failed | 0 |
| 4 - 2 | X | 0 |
| 1 | Other Communication | 0 |
| 0 | X | 0 |

Read back Descriptions

Single parameter read back: Functions can be read back one at a time using the read_word_protocol with PEC. A command is first sent out notifying the slave what function is to be read back followed by the data transfer.

Analog data is always transmitted LSB followed by MSB. A NA following the PEC byte signifies that the transmission is complete and is being terminated by the 'host'.

| | | | | |
|---|---------------|----|---|--------------|
| 1 | 8 | 1 | 8 | 1 |
| S | Slave address | Wr | A | Command Code |

| | | |
|----|---------------|----|
| 1 | 8 | 1 |
| Sr | Slave address | Rd |
| | | A |

| | | | | | | |
|-----|---|-----|---|-----|----|---|
| 8 | 1 | 8 | 1 | 8 | 1 | 1 |
| LSB | A | MSB | A | PEC | NA | P |

Read back error: If the μ C does not have sufficient time to retrieve the requested data, it has the option to return all FF's instead of incorrect data.

Read_FRU_ID (0x99,0x9A,0x9B,0x9E): Returns FRU information. Must be executed one register at a time

| | | | | |
|---|---------------|----|---|--------------|
| 1 | 8 | 1 | 8 | 1 |
| S | Slave address | Wr | A | Command 0x9x |
| | | | | A |

| | | | | |
|----|---------------|----|---|----------------|
| 1 | 8 | 1 | 8 | 1 |
| Sr | Slave address | Rd | A | Byte count = x |
| | | | | A |

| | | | | | | | | |
|--------|---|------|---|--------|---|-----|--------|---|
| 8 | 1 | 8 | 1 | 8 | 1 | 8 | 1 | 1 |
| Byte_1 | A | Byte | A | Byte_x | A | PEC | No-Ack | P |

Mfr_ID (0x99): Manufacturer in ASCII – 6 characters maximum,

OmniOn Power Electric – Critical Power represented as, OmniOn Power-CP

Mfr_model (0x9A): Manufacturer model-number in ASCII – 16 characters, for this unit: CC3500AC52TEFBxx

Mfr_revision (0x9B): Total 8 bytes, this is the product series taking the form X:YZ. Each byte is in ASCII format. The series number is read from left to right, scanned from the series number bar code on the power supply. Unused characters are filled at the end with null

Mfr_serial (0x9E): Product serial number includes the manufacturing date, manufacturing location in up to 16 characters. For example:

13KZ51018193xxx, is decoded as; 13 – year of manufacture, 2013

KZ – manufacturing location, in this case Matamoros
51 – week of manufacture

018193xxx – serial #, mfr choice

Technical Specifications (continued)

Manufacturer-Specific PMBus™ Commands

Many of the manufacturer-specific commands read back more than two bytes. If more than two bytes of data are returned, the standard SMBus™ Block read is utilized. In this process, the Master issues a Write command followed by the data transfer from the rectifier. The first byte of the Block Read data field sends back in hex format the number of data bytes, exclusive of the PEC number, that follows. Analog data is always transmitted LSB followed by MSB. A No-ack following the PEC byte signifies that the transmission is complete and is being terminated by the 'host'.

Mfr_Specific Status and alarm registers: The content and partitioning of these registers is significantly different than the standard register set in the PMBus™ specification. More information is provided by these registers and they are either accessed rapidly, at once, using the 'multi parameter' read back scheme of this document, or in batches of two STATUS and two ALARM registers.

Status_summary (0xD0) : This 'manufacturer specific' command is the basic read back returning STATUS and ALARM register data, output voltage, output current, and internal temperature data in a single read. Internal temperature should return the temperature that is closest to a shutdown level.

| | | | | |
|---|---------------|----|---|--------------|
| 1 | 8 | 1 | 8 | 1 |
| S | Slave address | Wr | A | Command Code |

| | | | | |
|----|---------------|----|---|-----------------|
| 1 | 8 | 1 | 8 | 1 |
| Sr | Slave address | Rd | A | Byte count = 11 |

| | | | | | | | |
|----------|---|----------|---|---------|---|---------|---|
| 8 | 1 | 8 | 1 | 8 | 1 | 8 | 1 |
| Status-2 | A | Status-1 | A | Alarm-3 | A | Alarm-2 | A |

| | | | | | |
|---------|---|-------------|---|-------------|---|
| 8 | 1 | 8 | 1 | 8 | 1 |
| Alarm-1 | A | Voltage LSB | A | Voltage MSB | A |

| | | | |
|-------------|---|-------------|---|
| 8 | 1 | 8 | 1 |
| Current-LSB | A | Current-MSB | A |

| | | | |
|-----------------|---|-----------------|---|
| 8 | 1 | 8 | 1 |
| Temperature-LSB | A | Temperature-MSB | A |

| | | |
|-----|--------|---|
| 8 | 1 | 1 |
| PEC | No-Ack | P |

Status_unit(0xD1): This command returns the STATUS -2 and STATUS-1 register values using the standard 'read' format.

| Bit Position | Flag | Default Value |
|--------------|------------------------|---------------|
| 7 | PEC Error | 0 |
| 6 | OC [hiccup=1,latch=0] | 1 |
| 5 | Invalid_Instruction | 0 |
| 4 | | x |
| 3 | OR'ing Test Failed | 0 |
| 2 | n/a | 0 |
| 1 | Data_out_of_range | 0 |
| 0 | Remote ON/OFF [HI = 1] | x |

Status 2

Oring fault: Triggered either by the host driven or'ing test or by the repetitive testing of this feature within the rectifier. A destructive fault would cause an internal shutdown. Success of the host driven test depends on whether the system is N+1 configured. Thus a non- destructive or'ing fault does not trigger a shutdown.

| Bit Position | Flag | Default Value |
|--------------|------------------------|---------------|
| 7 | OT [Hiccup=1, latch=0] | 1 |
| 6 | OR'ing_Test_OK | 0 |
| 5 | Internal_Fault | 0 |
| 4 | Shutdown | 0 |
| 3 | Service LED ON | 0 |
| 2 | External_Fault | 0 |
| 1 | LEDs_Test_ON | 0 |
| 0 | Output ON (ON = 1) | x |

Status 1

Status_alarm (0xD2): This command returns the ALARM-3 - ALARM-1 register values.

| Bit Position | Flag | Default Value |
|--------------|--|---------------|
| 7 | Interlock open | 0 |
| 6 | Fuse fail | 0 |
| 5 | PFC-DC communications fault | 0 |
| 4 | DC-I ² C communications fault | 0 |
| 3 | AC monitor communications fault | 0 |
| 2 | x | 0 |
| 1 | x | 0 |
| 0 | Or'ing fault | 0 |

Alarm 3

| Bit Position | Flag | Default Value |
|--------------|-------------------------------|---------------|
| 7 | FAN_Fault | 0 |
| 6 | No_Primary | 0 |
| 5 | Primary_OT | 0 |
| 4 | DC/DC_OT | 0 |
| 3 | V _o lower than BUS | 0 |
| 2 | Thermal sensor failed | 0 |
| 1 | Stby_out_of_limits | 0 |
| 0 | Power_Delivery | 0 |

Alarm 2

Technical Specifications (continued)

Manufacturer-Specific PMBus™ Commands

Power Delivery: If the internal sourced current to the current share current is > 10A, a fault is issued.

| Bit Position | Flag | Default Value |
|--------------|---------------------|---------------|
| 7 | POWER LIMIT | 0 |
| 6 | PRIMARY Fault | 0 |
| 5 | OT_Shutdown | 0 |
| 4 | OT_Warning | 0 |
| 3 | IN_OVERCURRENT | 0 |
| 2 | OV_Shutdown | 0 |
| 1 | VOOUT_out_of_limits | 0 |
| 0 | VIN_out_of_limits | 0 |

Alarm 1

Read input string (0xD4): Reads back the input voltage and input power consumed by the power supply.

| | | | | |
|---|---------------|----|---|-------------------|
| 1 | 7 | 1 | 1 | 8 |
| S | Slave address | Wr | A | Command Code 0xDC |

| | | | | |
|---|----|---------------|----|---|
| 1 | 1 | 7 | 1 | 1 |
| A | Sr | Slave Address | Rd | A |

| | | | | | |
|----------------|---|---------------|---|---------------|---|
| 8 | 1 | 8 | 1 | 8 | 1 |
| Byte Count = 4 | A | Voltage - LSB | A | Voltage - MSB | A |

| | | | | | | |
|-------------|---|-------------|---|-----|--------|---|
| 8 | 1 | 8 | 1 | 8 | 1 | 1 |
| Power - LSB | A | Power - MSB | A | PEC | No-ack | P |

Read_firmware_rev [0 x D5]: Reads back the firmware revision of all three μC in the Rectifier.

| | | | | | |
|---|---------------|----|---|-------------------|---|
| 1 | 7 | 1 | 1 | 8 | 1 |
| S | Slave address | Wr | A | Command Code 0xDD | A |

| | | | | | | |
|---|----|---------------|----|---|----------------|---|
| 1 | 1 | 7 | 1 | 1 | 8 | 1 |
| A | Sr | Slave Address | Rd | A | Byte Count = 6 | A |

| | | | |
|-------------------|---|-------------------|---|
| 8 | 1 | 8 | 1 |
| Primary major rev | A | Primary minor rev | A |

| | | | |
|---------------------|---|---------------------|---|
| 8 | 1 | 8 | 1 |
| Secondary major rev | A | Secondary minor rev | A |

| | | | | | | |
|----------------------------|---|---------------------------|---|-----|--------|---|
| 8 | 1 | 8 | 1 | 8 | 1 | 1 |
| I ² C major rev | A | I ² C revision | A | PEC | No-ack | P |

Read_run_timer [0xD6]: This command reads back the recorded operational ON state of the power supply in hours. The operational ON state is accumulated from the time the power supply is initially programmed at the factory. The power supply is in the operational ON state both when in standby and when it delivers main output power. Recorded capacity is approximately 10 years of operational state.

| | | | | | |
|---|---------------|----|---|-------------------|---|
| 1 | 7 | 1 | 1 | 8 | 1 |
| S | Slave address | Wr | A | Command Code 0xDE | A |

| | | | | | |
|----|---------------|----|---|----------------|---|
| 1 | 7 | 1 | 1 | 8 | 1 |
| Sr | Slave Address | Rd | A | Byte count = 3 | A |

| | | | | | |
|------------|---|------|---|------------|---|
| 8 | 1 | 8 | 1 | 8 | 1 |
| Time - LSB | A | Time | A | Time - MSB | A |

| | | |
|-----|--------|---|
| 8 | 1 | 1 |
| PEC | No-ack | P |

EEPROM record (0xD9): The μC contains 128 bytes of reserved EEPROM space for customer use. After the command code, the starting memory location must be entered followed by a block write, and terminated by the PEC number;

| | | | | | |
|---|---------------|----|---|-------------------|---|
| 1 | 7 | 1 | 1 | 8 | 1 |
| S | Slave address | Wr | A | Command Code 0xD9 | A |

| | | | |
|----------------|---|------------|---|
| 8 | 1 | 8 | 1 |
| Start location | A | Byte count | A |

| | | | |
|------------|---|-------|-------------|
| 8 | 1 | 8 | 1 |
| First_byte | A | | last - byte |
| | | | A |

| | | |
|-----|---|---|
| 8 | 1 | 1 |
| PEC | A | P |

To read contents from the EEPROM space

| | | | | | |
|---|---------------|----|---|--------------|---|
| 1 | 7 | 1 | 1 | 8 | 1 |
| S | Slave address | Wr | A | Command 0xD9 | A |

| | | | |
|-----------------|---|-----------------|---|
| 8 | 1 | 8 | 1 |
| Memory location | A | Byte count ≤ 32 | A |

| | | | |
|----|---------------|----|---|
| 1 | 7 | 1 | 1 |
| Sr | Slave address | Rd | A |

| | | | |
|--------|---|-------|-----------|
| 8 | 1 | 8 | 1 |
| Byte_1 | A | | Byte ≤ 32 |
| | | | A |

| | | |
|-----|--------|---|
| 8 | 1 | 1 |
| PEC | No ack | P |

Technical Specifications (continued)

Manufacturer-Specific PMBus™ Commands (continued)

Test Function (0xDF)

| Bit | Function | State |
|-------|------------------------------|---------------|
| 7 | 25ms stretch for factory use | 1= stretch ON |
| 5 - 6 | reserved | |
| 4 | Or'ing test | 1=ON, 0=OFF |
| 2 - 3 | reserved | |
| 1 | Service LED | 1=ON, 0=OFF |
| 0 | LED test | 1=ON, 0=OFF |

LEDS test ON: Will turn-ON simultaneously the front panel LEDs of the Rectifier sequentially 7 seconds ON and 2 seconds OFF until instructed to turn OFF. The intent of this function is to provide visual identification of the rectifier being talked to and also to visually verify that the LEDs operate and driven properly by the micro controller

LEDS test OFF: Will turn-OFF simultaneously the four front panel LEDs of the Rectifier.

Service LED ON: Requests the rectifier to **flash**-ON the Service (ok-to-remove) LED. The **flash** sequence is approximately 0.5 seconds ON and 0.5 seconds OFF

Service LED OFF: Requests the rectifier to turn OFF the Service (ok-to-remove) LED.

OR'ing Test: This command verifies functioning of output OR'ing. At least two paralleled rectifiers are required. The host should verify that N+1 redundancy is established. If N+1 redundancy is not established the test can fail. Only one rectifier should be tested at a time.

Verifying test completion should be delayed for approximately 30 seconds to allow the rectifier sufficient time to properly execute the test.

Failure of the isolation test is not considered a rectifier FAULT because the N+1 redundancy requirement cannot be verified. The user must determine whether a true isolation fault indeed exists.

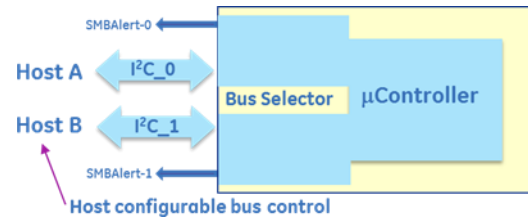
Dual Master Control:

Two independent I²C lines and Alert# signals provide true communications redundancy allowing two independent controllers to sequentially control the rectifier.

A short or an open connection in one of the I²C lines does not affect communications capability on the other I²C line. Failure of a 'master' controller does not

affect the rectifiers and the second 'master' can take over control at any time when the bus is idle.

The Alert# line exiting the rectifier combines the Alert# functions of rectifier control and dual_bus_control.



Conceptual representation of the dual I²C bus system.

Status_bus (0xD7): Bus_Status is a single byte read back. The command can be executed by either master at any time independent of who has control.

The μC may issue a clock stretch, as it can for any other instruction, if it requires a delay because it is busy with other activities.

Automatically resetting into the default state requires the removal of bias supply from the controllers.

| Bit | Flag | Default Value |
|-----|-----------------------------|---------------|
| 7 | Bus 1 command error | 0 |
| 6 | Bus 1 Alert# enabled | 0 |
| 5 | Bus 1 requested control | 0 |
| 4 | Bus 1 has control of the PS | 0 |
| 3 | Bus 0 command error | 0 |
| 2 | Bus 0 Alert# enabled | 0 |
| 1 | Bus 0 requested control | 0 |
| 0 | Bus 0 has control of the PS | 1 |

Command Execution: The master not in control can issue two commands on the bus, take_over_bus_control and clear_faults

Take_over_Bus_Control(0xD8): This command instructs the internal μC to switch command control over to the 'master' that initiated the request.

Actual transfer is controlled by the I²C selector section of the μC. A bus transfer only occurs during an idle state when the 'master' currently in control (in the execution process of a control command) has released the bus by issuing a STOP command. Control can be transferred at any time if the 'master' being released is executing a read instruction that does not affect the transfer of command control. Note; The μC can handle read instructions from both busses simultaneously.

The command follows PMBus™ standards and it is not executed until the trailing PEC is validated.

Technical Specifications (continued)

Dual Master Control: (continued)

Status Notifications: Once control is transferred both Alert# lines should get asserted by the I²C selector section of the μ C. The released 'master' is notified that a STATUS change occurred and he is no longer in control. The connected 'master' is notified that he is in control and he can issue commands to the rectifier. Each master must issue a clear_faults command to clear his Alert# signal.

If the Alert# signal was actually triggered by the rectifier and not the I²C selector section of the μ C, then only the 'master' in control can clear the rectifier registers.

Incomplete transmissions should not occur on either bus.

General performance descriptions

Default state: Rectifiers are programmed in the default state to automatically restart after a shutdown has occurred. The default state can be reconfigured by changing non-volatile memory (Store_user_code).

Delayed overcurrent shutdown during startup:

Rectifiers are programmed to stay in a constant current state for up to 20 seconds during power up. This delay has been introduced to permit the orderly application of input power to a subset of paralleled rectifiers during power up. If the overload persists beyond the 20 second delay, the rectifier will revert back into its programmed state of overload protection.

Unit in Power Limit or in Current Limit: When output voltage is $> 36V_{DC}$ the Output LED will continue blinking. When output voltage is $< 36V_{DC}$, if the unit is in the RESTART mode, it goes into hiccup. When the unit is ON the output LED is ON, when the unit is OFF the output LED is OFF.

When the unit is in latched shutdown the output LED is OFF.

Restart after a latchoff: PMBus™ fault_response commands can be configured to direct the rectifier to remain latched off for over_voltage, over_temperature and over_current.

To restart after a latch off either of five restart mechanisms are available.

1. The hardware pin **ON/OFF** may be cycled OFF and then ON.
2. The unit may be commanded to restart via i²c through the Operation command by cycling the output OFF followed by ON.
3. Remove and reinsert the unit.
4. Turn OFF and then turn ON AC power to the unit.
5. Changing firmware from **latch off to restart**.

Each of these commands must keep the rectifier in the OFF state for at least 2 seconds, with the exception of changing to restart.

A successful restart shall clear all alarm registers, set the

restarted successful bit of the **Status_2** register.

A power system that is comprised of a number of rectifiers could have difficulty restarting after a shutdown event because of the non-synchronized behavior of the individual rectifiers. Implementing the latch-off mechanism permits a synchronized restart that guarantees the simultaneous restart of the entire system.

A synchronous restart can be implemented by;

1. Issuing a GLOBAL OFF and then ON command to all rectifiers,
2. Toggling Off and then ON the ON/OFF (ENABLE) signal
3. Removing and reapplying input commercial power to the entire system.

The rectifiers should be turned OFF for at least 20 – 30 seconds in order to discharge all internal bias supplies and reset the soft start circuitry of the individual rectifiers.

Auto_restart: Auto-restart is the default configuration for over-current and over-temperature shutdowns. These features are configured by the PMBus™ fault_response commands

An overvoltage shutdown is followed by three attempted restarts, each restart delayed 1 second, within a 1 minute window. If within the 1 minute window three attempted restarts failed, the unit will latch OFF. If within the 1 minute less than 3 shutdowns occurred then the count for latch OFF resets and the 1 minute window starts all over again

Technical Specifications (continued)

Fault Management

The rectifier recognizes that certain transitional states can occur before a final state is reached. The STATUS and ALARM registers will not be frozen into a notification state until the final state is reached. Once a final state is reached the Alert# signal is set and the STATUS and ALARM registers will not get reinstated until a clear_faults is issued by the master. The only exception is that additional state changes may be added to the original list if further changes are noted.

The rectifier differentiates between **internal faults** that are within the rectifier and **external faults** that the rectifier protects itself from, such as overload or input voltage out of limits. The FAULT LED, FAULT PIN or i2c alarm is not asserted for EXTERNAL FAULTS. Every attempt is made to announce External Faults. Some of these annunciations can be observed by looking at the input LEDs. These fault categorizations are predictive in nature and therefore there is a likelihood that a categorization may not have been made correctly.

Input voltage out of range: The Input LED will continue blinking as long as sufficient power is available to power the LED. If the input voltage is completely gone the Input LED is OFF.

State Change Definition

A **state_change** is an indication that an event has occurred that the MASTER should be aware of. The following events shall trigger a **state_change**;

- Initial power-up of the system when AC gets turned ON . This is the indication from the rectifier that it has been turned ON. Note that the master needs to read the status of each rectifier to reset the system_interrupt.
- Any changes in the bit pattern of either the PMBus standard STATUS or the mfr_specific STATUS registers should trigger the Alert# signal.

Smart Hot plug

The wide output capability of this rectifier requires special controls when the rectifier gets plugged into a live backplane.

During hot plug the rectifier attempts to configure itself into the bus voltage setting of a working system. When inserted into the system the output of the rectifier will be off.

- Prior to turning ON the main output, the rectifier reads the voltage present on the bus. If the bus voltage is $\geq 18V$ the rectifier will check whether Vmargin and the bus voltage are in agreement with each other.
- If there is agreement between Vmargin and the bus voltage, the rectifier will proceed to turn ON its output utilizing the delayed overcurrent shutdown during turn- ON.
- If there is no agreement between Vmargin and the bus voltage, the rectifier recognizes that the bus voltage is being controlled externally. In this case the rectifier will keep its output OFF and will wait for the controller based output voltage command. Once such a command is received from the controller, the rectifier will proceed with normal turn-ON utilizing the delayed overcurrent shutdown.
- The rectifier continues to monitor Vmargin and the bus voltage. If no command is received from the controller, and if Vmargin and the bus voltage should agree at a later time, then the rectifier will normally turn ON its output utilizing the delayed overcurrent shutdown.
- If the bus voltage is $< 18V$, the rectifier proceeds with normal turn-ON into either its default voltage level or the voltage level commanded externally by Vmargin.

Failure Predictions

Alarm warnings that do not cause a shutdown are indicators of potential future failures of the rectifier. For example, if a thermal sensor failed, a warning is issued but an immediate shutdown of the rectifier is not warranted.

The goal is to identify problems early before a protective shutdown would occur that would take the rectifier out of service.

Information only alarms: The following alarms are for information only, they do not cause a shutdown

- Over temperature warning
- V_{out} out-of-limits
- Output voltage lower than bus
- Unit in Power Limit
- Thermal sensor failed
- Or'ing (Isolation) test failure
- Power delivery
- Stby out of limits
- Communication errors

Technical Specifications (continued)

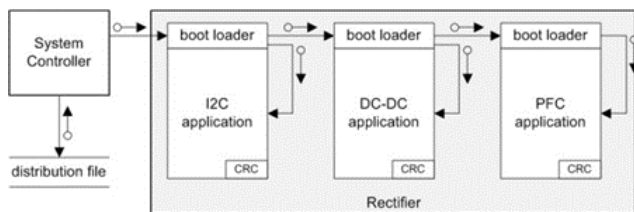
Remote upgrade

This section describes at a high-level the recommended re-programming process for the three internal micro controllers inside the rectifier when the re-programming is implemented in live, running, systems.

The process has been implemented in visual basic by OmniOn Power Critical Power for controller based systems positioned primarily for the telecommunications industry. OmniOn Power Critical Power will share its development with customers who are interested to deploy the re-programming capability into their own controllers.

For some customers internal system re-programming is either not feasible or not desired. These customers may obtain a re-programming kit from OmniOn Power Critical Power. This kit contains a turn-key package with the re-program firmware.

Conceptual Description: The rectifier contains three independent μ Controllers. The boost (PFC) section is controlled by the primary μ Controller. The secondary DC-DC converter is controlled by the secondary μ Controller, and I²C communications are being handled by the I²C Interface μ Controller.



Each of the μ Controllers contains a **boot loader** section and an **application** section in memory. The purpose of the boot loader section is to facilitate the upgrading capability described here. All the commands for upgrading and memory space required for incrementally changing the application code are in this section. The application section contains the running code of the rectifier.

The system controller receives the upgrade package. It should first check whether an upgrade is required followed by upgrading those processors, one at a time, that are required to be upgraded. Each processor upgrade needs to be validated and once the upgrade is successfully completed the boot loader within each processor will permit the application to run after a reset. If the validation fails the boot loader will stay in its section. The system controller can attempt another upgrade session to see if it would complete successfully.

The Upgrade Package: This package contains the following files;

- **Manifest.txt** - The manifest describes the contents of the upgrade package and any incidental information that may be useful, for example, what this upgrade contains or why is this upgrade necessary. This file contains the version number and the compatibility code of the upgraded program for each of the three processors
- **Program.bin** - The upgraded program contents are located here. Each processor to be upgraded will have its own file.

Below is an example of an upgrade package

- Contents of the upgrade are in a zip file
CC3x00AC52FB.zip
- Unzipping the contents shows the following files
CC3x00AC52FB.pfc.bin
CC3x00AC52FB.sec.bin
manifest.txt

- Opening manifest.txt shows the following

```
# Upgrade manifest file
# Targets: CC3x00AC52FB PFC and SEC
# Date: Tue 01/14/2014 14:25:09.37
```

- # Notes:

```
Program contents
>p,CC3x00AC52TE_P01, CC3x00AC52FB
_PFC.bin,1.18
>s, CC3x00AC52TE _S01, CC3x00AC52FB
_SEC.bin,1.1
```

Compatibility code, New Program Revision number

Upgrade Status Indication: The FAULT LED is utilized for indicating the status of the re-programming process.

| Status | Fault LED | Description |
|---------------|------------|----------------------------|
| Idle | OFF | Normal state |
| In boot block | Wink | Application is good |
| Upgrading | Fast blink | Application is erased or |
| Fault | ON | Erase or re-program failed |

Wink: 0.25 seconds ON, 0.75 seconds OFF

Fast Blink: 0.25 seconds ON. 0.25 seconds OFF

Technical Specifications (continued)

Upgrade procedure

1. Initialization: To execute the re-programming/ upgrade in the system, the rectifier to be re-programmed must first be taken OFF-line prior to executing the upgrade. If the rectifier is not taken OFF-line by the system controller, the boot loader will turn OFF the output prior to continuing with the re-programming operation.

Note: Make sure that sufficient power is provided by the remaining on-line rectifiers so that system functionality is not jeopardized.

2. Unzip the distribution file
3. Unlock upgrade execution protection by issuing the command below;

Password(0xE0): This command unlocks the upgrade commands feature of the rectifier by sending the characters 'UPGD'.

| | | | | | | |
|---|------------|----|---|------------|---|----------------|
| 1 | 8 | 1 | 8 | 1 | 8 | 1 |
| S | Slave addr | Wr | A | Cmd - 0xE0 | A | Byte count - 4 |

| | | | | | | |
|------------|---|-------|------------|---|-----|---|
| 8 | 1 | 8 | 1 | 8 | 1 | 1 |
| Byte 0 - U | A | | Byte 4 - D | A | PEC | P |

4. Obtain a list of upgradable processors (optional)

Target list(0xE1) : This command returns the upgradable processors within the rectifier. The byte word is the ASCII character of the processor (p, s, and i). The command is optional to the user for information only.

| | | | | |
|---|------------|----|---|------------|
| 1 | 8 | 1 | 8 | 1 |
| S | Slave addr | Wr | A | Cmd - 0xE1 |

| | | | | |
|---|------------|----|---|----------------|
| 1 | 8 | 1 | 8 | 1 |
| S | Slave addr | Rd | A | Byte count - n |

| | | | | | | |
|--------|---|-------|----------|---|--------|---|
| 8 | 1 | 8 | 1 | 8 | 1 | |
| Byte 0 | A | | Byte - n | A | PEC | |
| | | | | | No-Ack | P |

Potential target processors are the following:

- p – primary (PFC)
- s – secondary (DC-DC)
- i – I²C

Verify upgrade compatibility by matching the upgrade compatibility code in the manifest.txt file to the rectifier compatibility code of the target processor.

Compatibility code (0xE2): This read command consists of up to 32 characters defining the hardware configuration:

| | | | | |
|---|------------|----|---|------------|
| 1 | 8 | 1 | 8 | 8 |
| S | Slave addr | Wr | A | Cmd - 0xE2 |
| | | | | Target - x |

| | | | | | | |
|---|------------|----|---|---------------|---|--------|
| 1 | 8 | 1 | 8 | 1 | 8 | 1 |
| S | Slave addr | Rd | A | Byte count=32 | A | Byte 0 |
| | | | | | | A |

| | | | | | |
|-------|-----------|---|-----|--------|---|
| 8 | 1 | 8 | 8 | 1 | |
| | Byte - 31 | A | PEC | No-Ack | P |

Where Target-x is an ASCII character pointing to the processor to be updated;

- p – primary (PFC)
- s – secondary (DC-DC)
- i – I²C

6. Check the software revision number of the target processor in the rectifier and compare it to the revision in the upgrade. If the revision numbers are the same, or the rectifier has a higher revision number then no upgrade is required for the target processor.

Software revision(0xE3): This command returns the software revision of the target.

| | | | | | | |
|---|------------|----|---|------------|---|------------|
| 1 | 8 | 1 | 8 | 1 | 8 | 1 |
| S | Slave addr | Wr | A | Cmd - 0xE3 | A | Target - x |
| | | | | | | A |

| | | | | | | |
|----|------------|----|---|--------------|---|----------------|
| 1 | 8 | 1 | 8 | 1 | 8 | 1 |
| Sr | Slave addr | Rd | A | Byte count=7 | A | Major revision |
| | | | | | | A |

| | | | | | | | |
|----------------|---|-------|---|-----|---|-------------------|---|
| 8 | 1 | 8 | 1 | 8 | 1 | 8 | 1 |
| Minor revision | A | month | A | day | A | year ₂ | A |

| | | | | | | |
|-----|---|-----|---|-----|--------|---|
| 8 | 1 | 8 | 1 | 8 | 1 | 1 |
| hrs | A | min | A | PEC | No-Ack | P |

7. Verify the capability of each processor

Memory capability (0xE4): Provides the specifics of the capability of the device to be reprogrammed

Technical Specifications (continued)

Upgrade procedure (continued)

| | | | | | | | |
|---|------------|----|---|------------|---|------------|---|
| 1 | 8 | 1 | 8 | 1 | 8 | 1 | |
| S | Slave addr | Wr | A | Cmd - 0xE2 | A | Target - x | A |

| | | | | | | | |
|----|------------|----|---|----------------|---|-----------|---|
| 1 | 8 | 1 | 8 | 1 | 8 | 1 | |
| Sr | Slave addr | Rd | A | Byte count = 7 | A | Max Bytes | A |

| | | | | | | | |
|----------|---|----------|---|----------|---|----------|---|
| 8 | 1 | 8 | 1 | 8 | 1 | 8 | 1 |
| ET - LSB | A | EI - MSB | A | BI - LSB | A | BT - MSB | A |

| | | | | | | |
|-------------|---|-------------|---|-----|-----|---|
| 8 | 1 | 8 | 1 | 8 | 1 | 1 |
| App_CRC_LSB | A | App_CRC_MSB | A | PEC | No- | P |

Where the fields definition are shown as below

| | |
|------------------|--|
| Max Bytes | Maximum number of bytes in a data packet |
| ET | Erase time for entire application space (in mS) |
| BT | Data packet write execution time (uS) |
| APP_CRC | Application CRC-16 – returns the application CRC-16 calculation. Reading these register values, if the application upload CRC-16 calculation returns an invalid, provides the mismatch information to the host program. (See application status(0xE5) command) |

This information should be used by the host processor to determine the max data packet size and add appropriate delays between commands.

- Verify availability: The Application status command is used to verify the present state of the boot loader.

Application status (0xE5): Returns the Boot Loader's present status

| | | | | | | | |
|---|------------|----|---|------------|---|------------|---|
| 1 | 8 | 1 | 8 | 1 | 8 | 1 | |
| S | Slave addr | Wr | A | Cmd - 0xE5 | A | Target - x | A |

| | | | | | | | | |
|----|------------|----|---|--------|---|-----|---------|---|
| 1 | 8 | 1 | 8 | 1 | 8 | 8 | 1 | |
| Sr | Slave addr | Rd | A | Status | A | PEC | No- Ack | P |

Status bits

| | | | |
|------|------------------------|------|-----------------------|
| 0x00 | Processor is available | 0x10 | Reserved |
| 0x01 | Application erased | 0x20 | Reserved |
| 0x02 | CRC-16 invalid | 0x40 | Manages downstream μC |
| 0x04 | Sequence out of order | 0x80 | In boot loader |
| 0x08 | Address out of range | | |

Status of the application should be checked after the execution of successive commands to verify that the commands have been properly executed.

¹⁸ The 'exit boot block' command is only successful if all applications are valid, otherwise, control remains in the boot block

- Issue a Boot Loader command with the enter boot block instruction

Boot loader (0xE6): This command manages the upgrade process starting with entering the sector, erasing the present application, indicating completion of the upload and finally exiting from the boot sector, thereby turning over control to the uploaded application.

| | | | | | | | |
|---|------------|----|---|------------|---|------------|---|
| 1 | 7 | 7 | 7 | 8 | 1 | 8 | 1 |
| S | Slave addr | Wr | A | Cmd - 0xE6 | A | Target - x | A |

| | | | | |
|------|---|-----|---|---|
| 8 | 1 | 8 | 1 | 1 |
| Data | A | PEC | A | P |

Data:

1=enter boot block (software reboot)

2=erase

3=done

4=exit¹⁸ boot block (watchdog reboot)

Note: The target μC field is ignored for enter and exit commands. During this process if the output of the rectifier was not turned OFF the boot loader will turn OFF the output

- Erase and program each μC using the Boot Loader command, starting with the PFC.
- Wait at least 1 second after issuing an erase command to allow the μC to complete its task.
- Use command 0xE5 to verify that the PFC μC is erased. The returned status byte should be 0x81.
- Use the Data Transfer command to update the application of the target μC.

Data transfer (0xE7): The process starts with uploading data packets with the first sequence number (0x0000).

| | | | | | | | |
|---|------------|----|---|------------|---|------------|---|
| 1 | 8 | 1 | 8 | 1 | 8 | 1 | |
| S | Slave addr | Wr | A | Cmd - 0xE7 | A | Target - x | A |

| | | | | | |
|-----------|---|-----------|---|----------------|---|
| 8 | 1 | 8 | 1 | 8 | 1 |
| Seq - LSB | A | Seq - MSB | A | Byte Count = n | A |

| | | | | | | | |
|--------|---|-------|------------|---|-----|---|---|
| 8 | 1 | 8 | 1 | 8 | 1 | 1 | |
| Byte 0 | A | | Byte - n-1 | A | PEC | A | P |

Technical Specifications (continued)

Upgrade procedure (continued)

After completion of the first data packet upload the Boot loader increments the sequence number. A subsequent read to the boot loader will return the incremented sequence number and a STATUS byte. This is a validity check to ensure that the sequence number is properly kept. The returned STATUS byte is the same as the application status response. It is appended here automatically to save the execution of another command. It should be checked to ensure that no errors are flagged by the boot loader during the download. If an error occurred, terminate the download load and attempt to reprogram again.

| | | | | | | |
|---|------------|----|---|------------|--|---|
| 1 | 8 | | 1 | 8 | | 1 |
| S | Slave addr | Wr | A | Cmd – 0xE4 | | A |

| | | | | | | |
|----|------------|----|---|----------------|--|---|
| 1 | 8 | | 1 | 8 | | 1 |
| Sr | Slave addr | Rd | A | Byte count = 3 | | A |

| | | | | | | | | |
|---------|---|---------|---|--------|---|-----|-----|---|
| 1 | 8 | 8 | 1 | 8 | 1 | 8 | 1 | 1 |
| Seq-LSB | A | Seq-MSB | A | Status | A | PEC | No- | P |

Sequence number validation takes place after each data block transfer. The next data block transfer starts with the sequence number received from the boot loader.

The host keeps track of the upload and knows when the upload is completed.

- Execute a Boot loader command to tell the PFC μ C that the transfer is done.

At the completion signal, the PFC μ C should calculate the PEC value of the entire application. The last two bytes of the loaded application were the CRC-16 based PEC calculation.

Wait for at least 1 second to allow time for the PFC μ C to calculate the error checking value.

- Execute an Application status command to verify that the error check is valid. The returned status should be 0x80.
- Execute a Boot loader command to exit boot block. Upon receipt of the command the PFC μ C will transfer to the uploaded application code.
- Wait for at least 1 second.
- Use command 0xE1 to verify that the PFC μ C is now in the application code. The returned status data bte should be 0x00
- Repeat the program upgrade for the Secondary and I²C μ C's, if included in the upgrade package.

Product Ordering code

Although the Ordering code number is not required for the upgrade process in its present form, it may be useful when upgrading multiple version of the same product in order to differentiate product upgrade requirements.

Product comcode (0 X E8):

| | | | | | | |
|---|------------|----|---|------------|--|---|
| 1 | 8 | | 1 | 8 | | 1 |
| S | Slave addr | Wr | A | Cmd – 0xE8 | | A |

| | | | | | | |
|---|------------|----|---|---------------|--|---|
| 1 | 8 | | 1 | 8 | | 1 |
| S | Slave addr | Rd | A | Byte count=11 | | A |

| | | | | | | |
|--------|---|-------|---------|---|-----|--------|
| 8 | 1 | 8 | 1 | 8 | 8 | 1 |
| Byte 0 | A | | Byte 10 | A | PEC | No-Ack |
| | | | | | | P |

Error handling: The Boot loader will not start the application if errors occurred during the re-program stage. The controlling program could restart the upgrade process or terminate the upgrade and remove the offending rectifier from service.

Black box

Contents of the black box and more detailed information about the specifics of the feature are described in a separate document. The intent here is to provide a high level summary This feature includes the following;

- A rolling event Recorder
- Operational Use Statistics

The rolling event recorder

The purpose of the black box is to provide operational statistics as well as fault retention for diagnostics following either recoverable or non-recoverable fault events. Sufficient memory exists to store up to 5 time-stamped snapshot records (pages) that include the state of the status and alarm registers and numerous internal measurement points within the rectifier. Each record is stored into nonvolatile memory at the time when a black box trigger event occurs. Once five records are stored, additional records over-write the oldest record.

The memory locations will be cleared, when the product is shipped from the OmniOn Power factory.

Technical Specifications (continued)

Black Box (continued)

Operational use statistics

This feature of the black box includes information on the repetition and duration of certain events in order to understand the long-term operational state of the rectifier. The events are placed into defined buckets for further analysis. For example; the rectifier records how long was the output current provided in certain load ranges.

Accessing the event records

The event records are accessed by uploading the entire contents of the black box of the rectifier into a folder assigned by the user. Within the I²C protocol this upload is accomplished by the upload_black_box (0xF0) command described below. OmniOn Power provides a Graphical User Interface (GUI) that decodes the contents of the black box into a set of records that can be reviewed by the user.

Upload black box(0xF0): This command executes the upload from the rectifier to a file of the user's choice.

The 100ms delay prior to the restart is mandatory to provide enough time for the rectifier to gather the

required data from the secondary DSP controller.

If a transmission error occurs, or if the uC did not receive the data from the DSP, the uC may set the length to 0, issue a PEC and terminate the transmission.

The data array supported by rev 1.3 of the OmniOn Power Interface Adapter is 32 x 64 comprising 2048 bytes of data.

```

Start
Address 0 ..... Byte ..... 31
0000h
0020h
0040h
.
.
.
.
.
.
.
.
07E0h
    
```

| | | | | |
|---|------------|----|---|------------|
| 1 | 8 | 1 | 8 | 1 |
| S | Slave addr | Wr | A | Cmd – 0xF0 |

| | | | |
|---------------------|---|---------------------|---|
| 8 | 1 | 8 | 1 |
| Start address - msb | A | Start address - lsb | A |

| | |
|------------------|---|
| 8 | 1 |
| Length = N (≤32) | A |

..... delay 100ms

| | | | | | | |
|----|------------|----|---|-------------|---|--------|
| 1 | 8 | 1 | 8 | 1 | 8 | 1 |
| Sr | Slave addr | Rd | A | Length ≤ 32 | A | Byte 0 |

| | | | | |
|----------|---|-----|--------|---|
| 8 | 1 | 8 | 8 | 1 |
| Byte N-1 | A | PEC | No-Ack | P |

.....

Technical Specifications (continued)

PMBus Command Summary

| Command | Hex Code | Data Field | Non- Volatile Memory Storage ¹⁹ / Default |
|--------------------------------------|----------|------------|--|
| Operation | 0x01 | 1 | Yes/80 |
| Clear_Faults | 0x03 | - | |
| Write_Protect | 0x10 | 1 | Yes/00 |
| Restore_default_all | 0x12 | - | |
| Restore_user_all | 0x16 | - | |
| Store_user_code | 0x17 | 1 | yes |
| Restore_user_code | 0x18 | 1 | |
| Vout_mode | 0x20 | 1 | |
| Vout_command | 0x21 | 2 | Yes/** |
| Vin_ON | 0x35 | 2 | |
| Vin_OFF | 0x36 | 2 | |
| Vout_OV_fault_limit | 0x40 | 2 | Yes / ** |
| Vout_OV_fault_response | 0x41 | 1 | No / 80 |
| Vout_OV_warn_limit | 0x42 | 2 | Yes / ** |
| Vout_UV_warn_limit | 0x43 | 2 | Yes / ** |
| Vout_UV_fault_limit | 0x44 | 2 | Yes / ** |
| Vout_UV_fault_response | 0x45 | 1 | No / C0 |
| Iout_OC_fault_limit | 0x46 | 2 | Yes / ** |
| Iout_OC_fault_response ²⁰ | 0x47 | 1 | Yes / F8 |
| Iout_OC_LV_fault_limit | 0x48 | 2 | Yes / ** |
| Iout_OC_warn_limit | 0x4A | 2 | Yes / ** |
| OT_fault_limit | 0x4F | 2 | Yes / ** |
| OT_fault_response ²¹ | 0x50 | 1 | Yes / C0 |
| OT_warn_limit | 0x51 | 2 | Yes / ** |
| Vin_OV_fault_limit | 0x55 | 2 | No / ** |
| Vin_OV_fault_response | 0x56 | 1 | No / C0 |
| Vin_OV_warn_limit | 0x57 | 2 | Yes / ** |
| Vin_UV_warn_limit ²² | 0x58 | 2 | Yes / ** |
| Vin_UV_fault_limit ²³ | 0x59 | 2 | No / ** |
| Vin_UV_fault_response | 0x5A | 1 | No / C0 |
| Status_byte | 0x78 | 1 | |
| Status_word (+ byte) | 0x79 | 1 | |
| Status_Vout | 0x7A | 1 | |
| Status_Iout | 0x7B | 1 | |
| Status_Input | 0x7C | 1 | |
| Status_temperature | 0x7D | 1 | |
| Status_CML | 0x7E | 1 | |

| Command | Hex Code | Data Field | Non- Volatile Memory Storage ¹⁹ / Default |
|--------------------------|----------|------------|--|
| Read_Vin | 0x88 | 2 | |
| Read_Iin | 0x89 | 2 | |
| Read_Vout | 0x8B | 2 | |
| Read_Iout | 0x8C | 2 | |
| Read_temp_PFC | 0x8D | 2 | |
| Read_temp_dc_pri | 0x8E | 2 | |
| Read_temp_dc_sec | 0x8F | 2 | |
| Read_Pin | 0x97 | 2 | |
| Mfr_ID | 0x99 | 6 | |
| Mfr_model | 0x9A | 16 | |
| Mfr_revision | 0x9B | 8 | |
| Mfr_serial | 0x9E | 16 | |
| Status_summary | 0xD0 | 12 | |
| Status_unit | 0xD1 | 2 | |
| Status_alarm | 0xD2 | 4 | |
| Read_input | 0xD4 | 5 | |
| Read_firmware_rev | 0xD5 | 7 | |
| Read_run_timer | 0xD6 | 4 | |
| Status_bus | 0xD7 | 1 | |
| Take_over_bus_control | 0xD8 | | yes |
| EEPROM Record | 0xD9 | 128 | yes |
| Read_temp_exhaust | 0xDA | 2 | |
| Read_temp_inlet | 0xDB | 2 | |
| Reserved for factory use | 0XDC | | |
| Reserved for factory use | 0XDD | | |
| Reserved for factory use | 0XDE | | |
| Test_Function | 0XDF | 1 | |
| Upgrade commands | | | |
| Password | 0xE0 | 4 | |
| Target_list | 0xE1 | 4 | |
| Compatibility_code | 0xE2 | 32 | |
| Software_version | 0xE3 | 7 | |
| Memory_capability | 0xE4 | 7 | |
| Application_status | 0xE5 | 1 | |
| Boot_loader | 0xE6 | 1 | |
| Data_transfer | 0xE7 | ≤32 | |
| Product comcode | 0xE8 | 11 | |
| Upload_black_box | 0xF0 | ≤32 | |

** See "Adjustment Ranges" table on previous page

¹⁹ Yes – new value can be saved permanently using Store_user_code

²⁰ Only latched (0xC0) or hiccup (0xF8) are supported

²¹ Only latched (0x80) or restart (0xC0) are supported

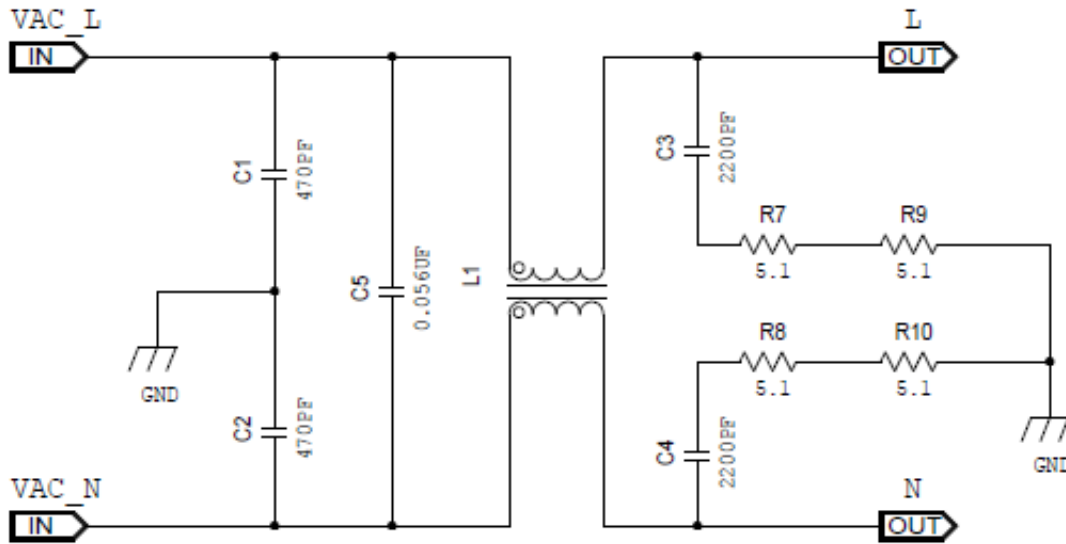
²² Recovery set at 90V

²³ Recovery set at 86V

Technical Specifications (continued)

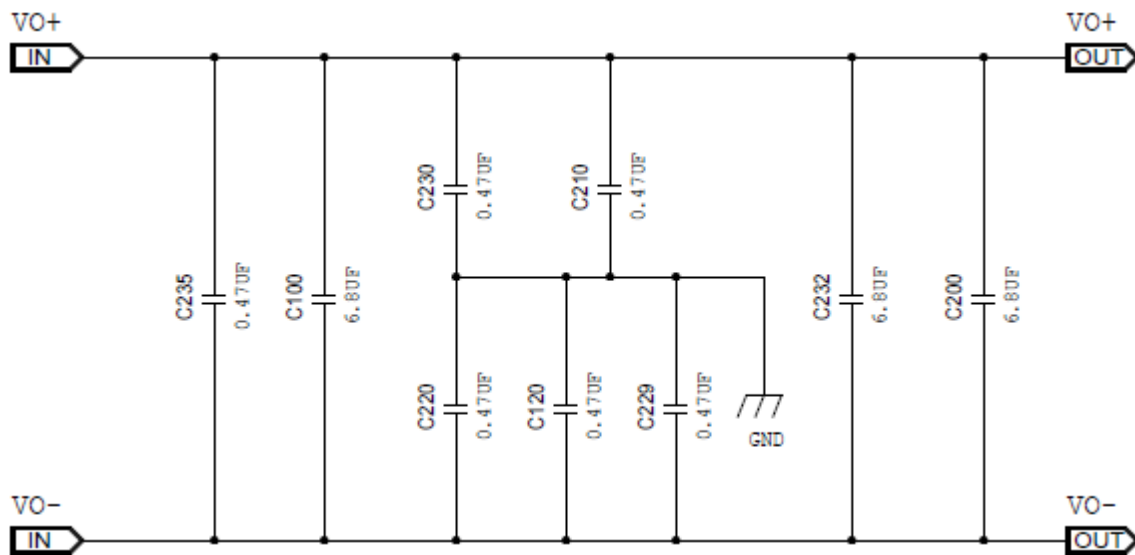
External EMI filter reference design for blind-mate connector version:

Input EMI filter circuit:



L1: 1.35uH, 3 TURNS, TWO CORES CSC CK270060

Output EMI filter circuit:



Technical Specifications (continued)

Table 1: Alarm and LED state summary

| Condition | Rectifier LED State | | | | Monitoring Signals | | | |
|--|---------------------|-------------|---------------|-----------|--------------------|-----|----------------------|----------------|
| | AC OK Green | DC OK Green | Service Amber | Fault Red | Fault | OTW | PG | Module Present |
| OK | 1 | 1 | 0 | 0 | HI | HI | HI | LO |
| Thermal Alarm (5C before shutdown) | 1 | 1 | 1 | 0 | HI | LO | HI | LO |
| Thermal Shutdown | 1 | 0 | 1 | 1 | LO | LO | LO | LO |
| Blown AC Fuse in Unit | 1 | 0 | 0 | 1 | LO | HI | LO | LO |
| AC Present but not within limits | Blinks | 0 | 0 | 0 | HI | HI | LO | LO |
| AC not present ¹ | 0 | 0 | 0 | 0 | HI | HI | LO | LO |
| Boost Stage Failure | 1 | 0 | 0 | 1 | LO | HI | LO | LO |
| Over Voltage Latched Shutdown | 1 | 0 | 0 | 1 | LO | HI | LO | LO |
| Over Current | 1 | Blinks | 0 | 0 | HI | HI | Pulsing ⁴ | LO |
| Non-catastrophic Internal Failure ² | 1 | 1 | 0 | 1 | LO | HI | HI | LO |
| Standby (remote) | 1 | 0 | 0 | 0 | HI | HI | LO | LO |
| Service Request (PMBus mode) | 1 | 1 | Blinks | 0 | HI | HI | HI | LO |
| Communications Fault (RS485 mode) | 1 | 1 | 0 | Blinks | HI | HI | HI | LO |

¹ This signal is correct if the rectifier is back biased from other rectifiers in the shelf.

² Any detectable fault condition that does not cause a shutting down. For example, ORing FET failure, boost section out of regulation, etc.

³ Signal transition from HI to LO is output load dependent

⁴ Pulsing at a duty cycle of 1ms as long as the unit is in overload.

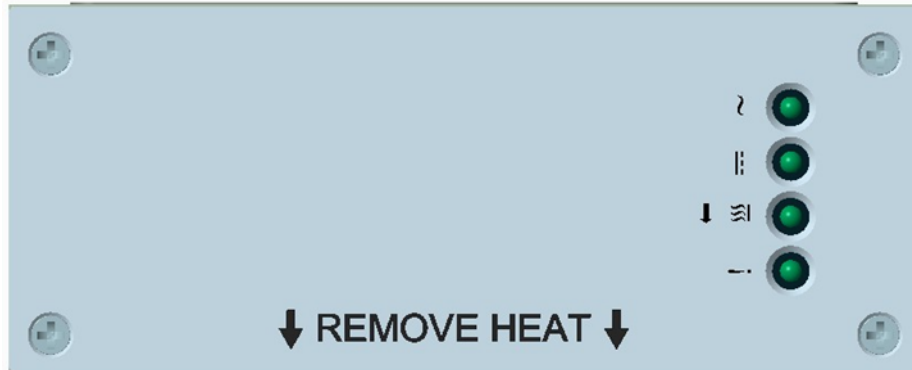
Table 2 : Signal Definitions

All hardware alarm signals (Fault#, PG#, OTW#) are open drain FETs. These signals need to be pulled HI to either 3.3V or 5V. Maximum sink current 5mA. An active LO signal (< 0.4V_{DC}) state. All signals are referenced to LGND unless otherwise stated.

| Label | Function | Type | Description |
|-------------------|----------------------------|-----------|---|
| 5VA | Standby power | Output | 5V at 2A provided for external use; return is LGND |
| 8V_INT | Back bias | Bi-direct | Used to back bias the DSP from operating Rectifiers. Ref: V _{out} (-). |
| Alert#_0/Alert#_1 | I ² C Interrupt | Output | Active LO. |
| Fault# | Rectifier Fault | Output | An open drain FET; normally HI, changes to LO. |
| Interlock | Interlock | Input | Short pin, controls main output during hot-insertion and extraction of the blind-mate connector. Not used for the -EC & -ES versions. Ref: V _{out} (-) |
| Ishare | Current Share | Bi-direct | A single wire active-current-share interconnect between rectifiers Ref: V _{out} (-) |
| LGND | Logic Ground | Input | Return for all signals unless V _{out} (-) is indicated in description |
| MOD_PRES | Module Present | Output | Short pin, see Status and Control description for further information on this signal. |
| ON/OFF | Output control | Input | If shorted to LGND main output is ON in Analog or PMBus mode. |
| OTW# | Over-Temperature Warning | Output | Open drain FET; normally HI, changes to LO 5°C prior to thermal shutdown. |
| PG# | Power Good Warning | Output | Open drain FET; Changes to LO if an imminent loss of the main output may occur. |
| Protocol | Protocol select | Input | Selects communications mode. No-connect for Analog/PMBus; 1 to 5kΩ for RS485. Ref: V _{out} (-) |
| Rack_ID | I ² C address | Input | Second of 2 voltage levels selecting the A3 – A0 bits of the address byte |
| RS_485+ | RS485 Line | Bi-direct | RS485 line +; Ref: V _{out} (-) |
| RS_485- | RS485 Line | Bi-direct | RS485 line -; Ref: V _{out} (-) |
| SCL_0/1 | I ² C Line 0/1 | Input | PMBus line 0/1 |
| SDA_0/1 | I ² C Line 0/1 | Bi-direct | PMBus line 0/1 |
| Shelf_ID | RS485 address | Input | Ref: V _{out} (-) |
| Slot_ID | RS485 address | Input | Requires ≤100 kΩ to enable output (internal for -EC & -ES). Ref: V _{out} (-) |
| Unit_ID | I ² C address | Input | First of 2 voltage levels selecting the A3 - A0 bits of the address byte |
| V_OUT(-) | Power output low side | Input | Signal return where indicated in description; 2.5A max on this pin |
| V _{prog} | Margining | Input | Changes the set point of the main output |

Technical Specifications (continued)

Front Panel LEDs

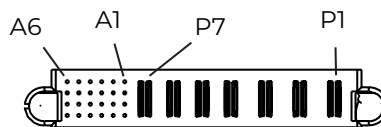


| | Analog Mode | I ² C Mode | RS485 Mode |
|------------------------------|-------------------------------------|---|--|
| <input type="checkbox"/> ~ | ← | ON: Input ok Blinking: Input out of limits | → |
| <input type="checkbox"/> ≡ | ← | ON: Output ok Blinking: Overload | → |
| <input type="checkbox"/> ⚡ * | ON: Over-temperature Warning | ON: Over-temperature Warning Blinking: Service | ON: Over-temperature Warning |
| <input type="checkbox"/> ! | ← ON: Fault → | | ON: Fault Blinking: Not communicating |

*Arrow next to "hot" symbol points to the cooling side, where heat should be removed.

Blind-Mate Output Connector TE: 3-6450832-8, or FCI: 10106262-7006001LF

Mating Connector: right angle PWB mate – all pins: **TE** – 1-6450872-6, **FCI** – 10106264-7006001LF;
right angle PWB mate except pass-thru input power: **TE** – 6450874-3, **FCI** – 10106265-70CB001LF



| | SIGNAL | | | | | | OUTPUT POWER | | | | INPUT POWER | | |
|---|--------|----------|----------|-----------|-----------|----------|--------------|-------|-------|-------|-------------|-----------|--------|
| | 6 | 5 | 4 | 3 | 2 | 1 | P7 | P6 | P5 | P4 | P3 | P2 | P1 |
| A | SCL_0 | MOD_PRES | PG# | LOGIC_GRD | RS_485+ | Slot_ID | | | | | EARTH (GND) | | |
| B | SCL_1 | OTW# | Alert#_0 | Alert#_1 | RS_485- | 8V_INT | V_OUT | V_OUT | V_OUT | V_OUT | | LINE-2 | LINE-1 |
| C | SDA_0 | Vprog | ON/OFF | Rack_ID | Ishare | Protocol | (-) | (+) | (+) | (-) | | (Neutral) | (HOT) |
| D | SDA_1 | Fault# | 5VA | Unit_ID | Interlock | Shelf_ID | | | | | | | |

Note: Connector is viewed from the rear positioned inside the rectifier

Signal pins columns 1 and 2 are referenced to V_OUT(-). Slot_ID and Shelf_ID are used only with RS485 communications.

Signal pins columns 3 through 6 are referenced to Logic GRD

Earth Last to make-first to break shortest pin

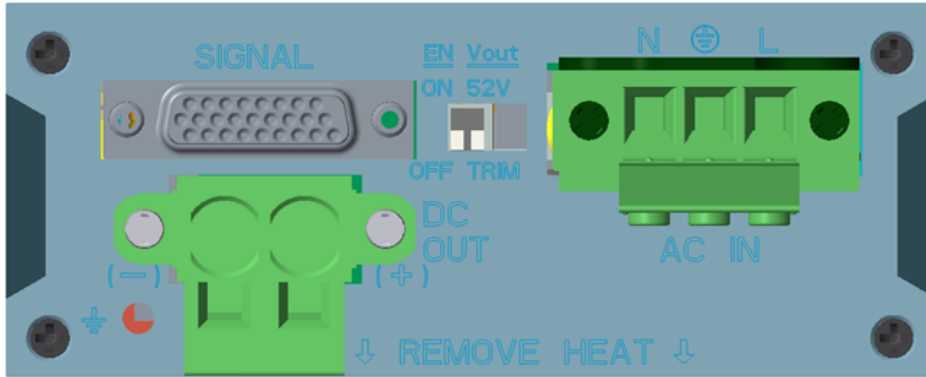
Earth First make-last to break longest pin implemented in the mating connector

Technical Specifications (continued)

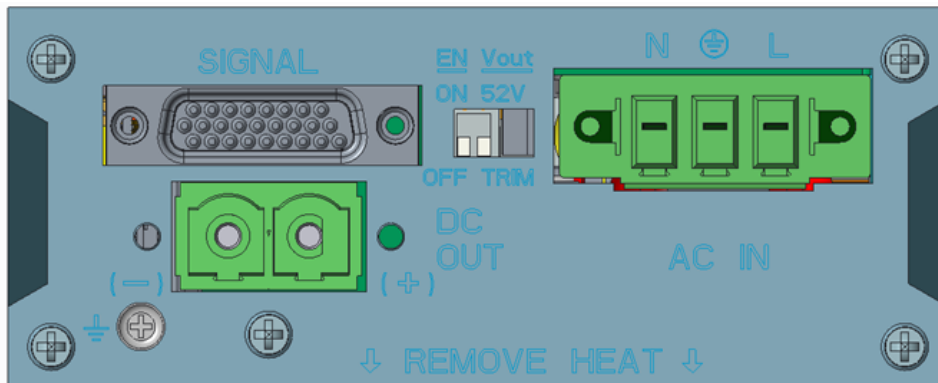
Screw-Terminal AC Connector (-ES)

Installed ac connector is Phoenix 1720806; mating screw-terminal plug is Phoenix 1778188.

AS delivered , with plugs installed:

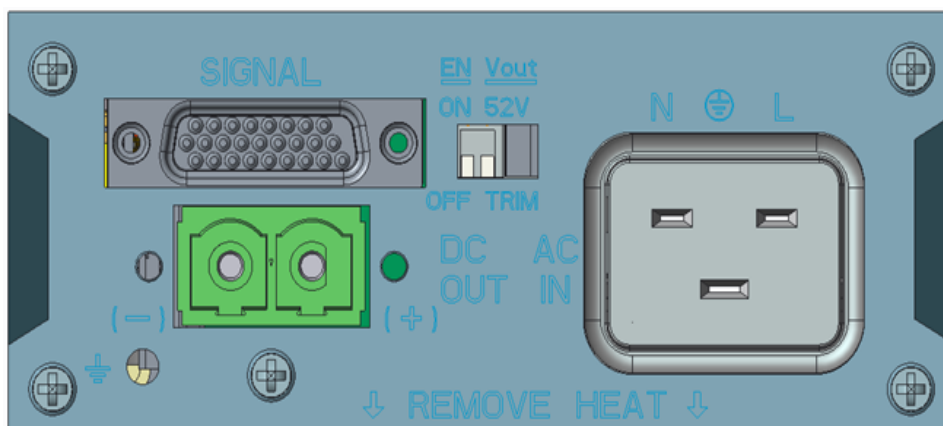


With plugs removed:

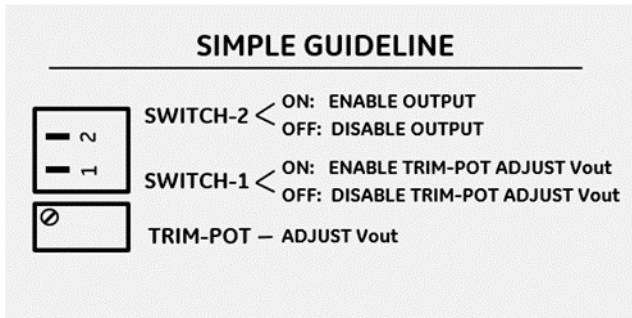


C19 AC Connector (-EC)

Installed ac connector is GSP4.0107.11; example mating connector is ??.



Technical Specifications (continued)



Signal Connector for Extension (-EC & -ES)

Example devices to mate with installed Amphenol FCI ICD26S13E4GV00LF (26-Position High Density D-Sub Receptacle with Female Sockets and female UNC 4-40 screw locks):

- FCI 10090769-P264ALF (straight plug with solder cups), with FCI 8630CH15UNCLF (plastic shell size A)
- FCI 10090930-P260ALF (male crimp housing) with FCI 10090932-P2448LF (male crimp contacts, AWG#24)
- FCI 10090926-P264XLF (right angle, through-hole for PCB mount)

[Inverted view to correspond to rear labels]



Signal Pinout

| Pin No: | | | | | | | Pin No: | | | | |
|---------|-----------|---------|----------|---------|-------------|----------|---------|----------|--------|----|--|
| 19 | SDA-1 | SCL_1 | Alert#_1 | ON/OFF | LGND | 5VA | | MOD_PRES | 26 | | |
| 10 | SAD_0 | SCL_0 | Alert#_0 | Unit_ID | Rack_ID | Vprog | PG# | OTW# | Fault# | 18 | |
| 1 | Sahelf_ID | Slot_ID | RS_485- | Rs_485+ | VOUT(-) | Protocol | 8V_INT | Ishare | | 9 | |

Viewed from back of rectifier,

Signal pins 1-9 (bottom row) are referenced to $V_{out(-)}$

Signal pins 10-26 are referenced to LGND

Slot_ID & Shelf_ID are used only with RS485 communications

Technical Specifications (continued)

Appendix

Bus transfer reporting:

| | The events below concentrate on what happens when a clear_faults is issued. The system controller needs to be intelligent enough to inquire the status of the power supply before issuing a clear_faults. Otherwise, it would lose whatever information may be in the status registers. | | | | | | |
|----|---|---------|---------|------------|-------------|------------|--|
| | operation | Alert#1 | Alert#0 | Status_bus | Status_word | Status_cml | |
| 1 | i2c1-command sent, not in control | 1 | 0 | 0xc1 | 0x0000 | 0x00 | |
| 2 | i2c1 issues a clear_faults | 0 | 0 | 0x01 | 0x0000 | 0x00 | |
| 3 | i2c0 in control, unit issues a fault | 1 | 1 | 0x01 | event1 | 0x00 | |
| 4 | i2c1 takes over control | 1 | 1 | 0x74 | event1 | 0x00 | |
| 5 | i2c1 read system status | 1 | 1 | 0x74 | event1 | 0x00 | |
| 6 | i2c1 issues a clear_faults | 0 | 1 | 0x14 | 0x0000 | 0x00 | controller needs to read status before clearing the registers. Assuming that the event has cleared |
| 7 | i2c0 reads system status | 0 | 1 | 0x14 | 0x0000 | 0x00 | |
| 8 | i2c0 issues clear faults | 0 | 0 | 0x10 | 0x0000 | 0x00 | the Alert remains because of status_bus, not because of unit fault |
| 9 | i2c0 in control, unit issues a fault | 1 | 1 | 0x01 | event1 | 0x00 | |
| 10 | i2c0 issues clear faults | 0 | 0 | 0x01 | 0x0000 | 0x00 | Assuming that the event has cleared |
| 11 | i2c1 in control | 0 | 0 | 0x10 | 0x0000 | 0x00 | |
| 12 | i2c0 takes over control | 1 | 1 | 0x47 | 0x0000 | 0x00 | |
| 13 | i2c0 issues a clear_faults | 1 | 0 | 0x41 | 0x0000 | 0x00 | |
| 14 | i2c1 issues a clear_faults | 0 | 0 | 0x01 | 0x0000 | 0x00 | |
| 15 | i2c1 in control | 0 | 0 | 0x10 | 0x0000 | 0x00 | |
| 16 | i2c0 issues a command | 0 | 1 | 0x1C | 0x0000 | 0x00 | the command is rejected because i2c0 is not in control |
| 17 | i2c0 issues a clear_faults | 0 | 0 | 0x10 | 0x0000 | 0x00 | |
| 18 | i2c1 issues a bad command | 1 | 0 | 0x10 | 0x0002 | 0x80 | |
| 19 | i2c1 issues a clear_faults | 0 | 0 | 0x10 | 0x0000 | 0x00 | |
| | Rules: Side in control is the only one that can clear the Status registers. The side in control cannot clear the alert of the side not in control A power supply alarm should not set the status_bus registers | | | | | | |

Latched status states until cleared

The following bits are sticky until cleared by the customer

Or'ing test failed or passed: I cannot see how it could be otherwise. The customer needs to delete the information (clear_faults) thus indicating that he received the information.

Restarted_ok: this bit has been removed from the requirements. PMBus latched states replace this bit.

Shutdown: must be sticky – it tells the customer that the rectifier output has been turned OFF

OV, UV, OC, input, unknown warnings & faults, CML Errors, Internal or External Fault: must be sticky

OC and OT response registers are in their own confined state. The only way these should change is by commanding the change by the controller. So theoretically they are sticky because a clear_faults should never change them.

The way to look at this is, all fault information is sticky (if the fault still persists after a clear_faults has been issued then the fault state will reassert), all operational state information is not sticky.

Technical Specifications (continued)

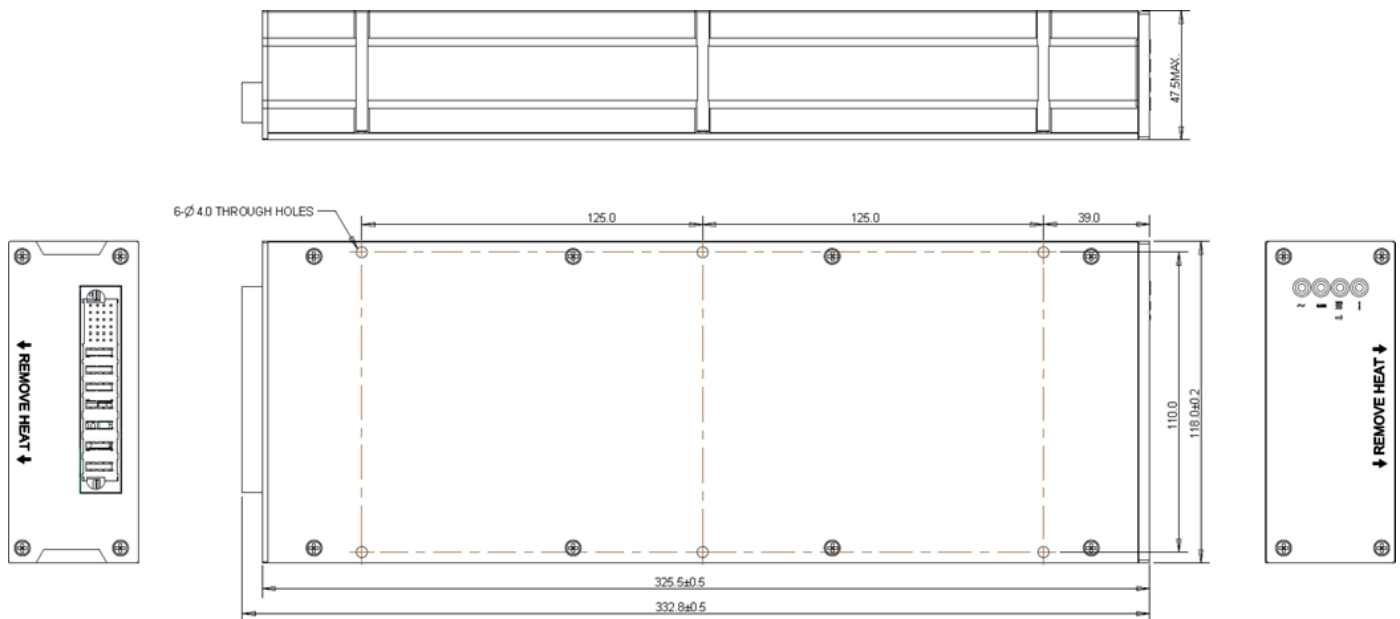
Mechanical Outline (Preliminary)

Flatness of cooling surface ± 0.25 mm

Rectifier with Blind-Mate Connector

Outer dimensions (including protruding connector): 333 x 118 x 47.5 mm (13.10 x 4.65 x 1.87 in) [201805 update]

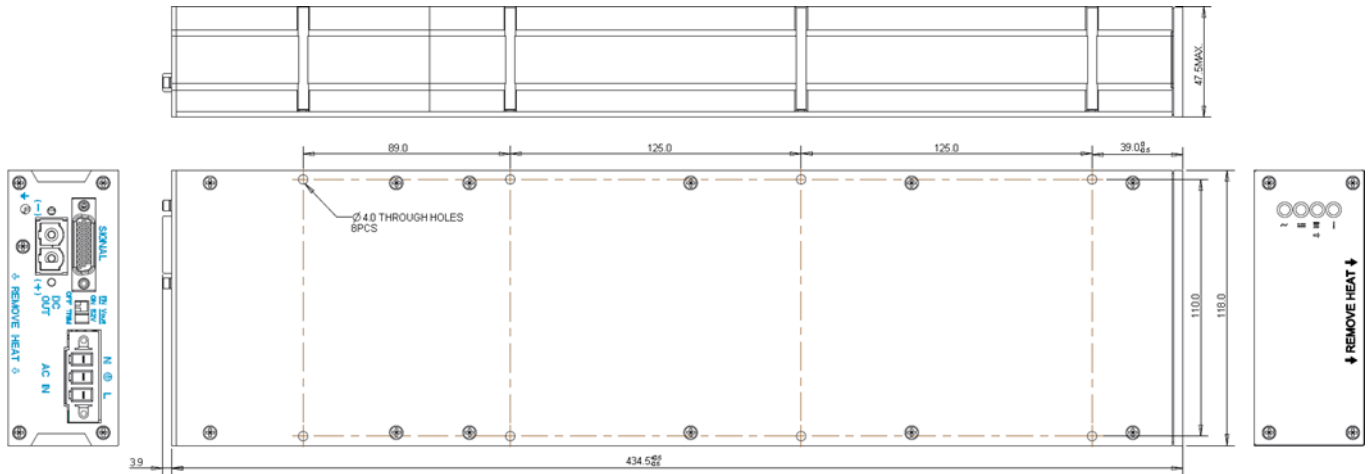
“Cooling side” (for heat transfer) is the large surface shown in the bottom row below, (opposite the label; closest to the Fault light (!); farthest from the blind-mate connector). The cooling device (cold plate, warm wall or heat sink) should be placed in good thermal contact with the entire cooling surface by using thermal grease or a thermal interface pad between them.



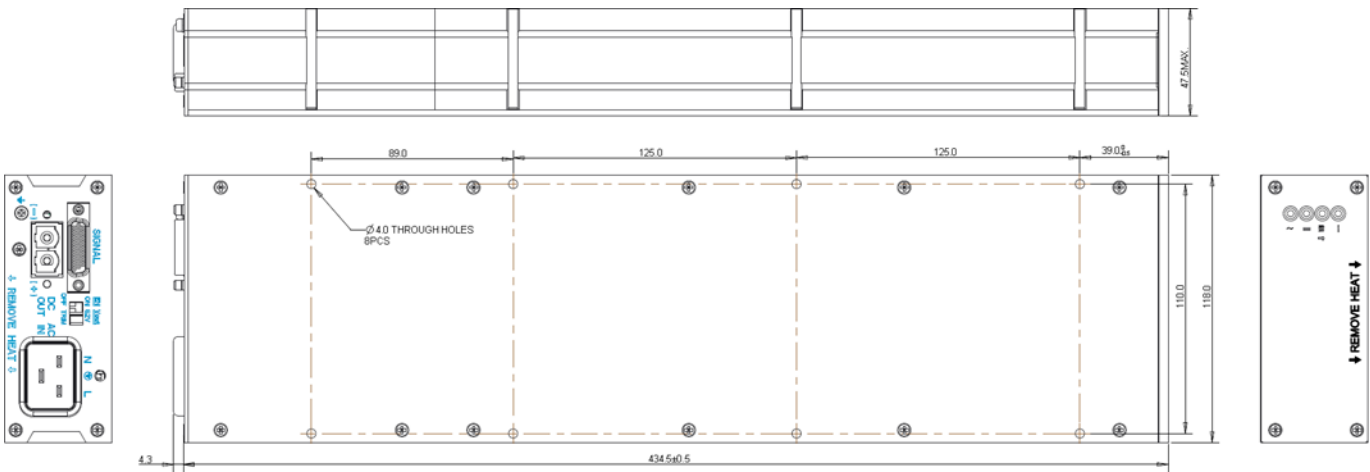
Technical Specifications (continued)

Rectifier with Extension for Filters & Non-Blind-Mate Connectors (-EC & -ES versions)

Outer dimensions (including protruding connector): 438.5 x 118 x 47.5 mm (17.26x 4.65 x 1.87 inch) [201805 update]



Outline Drawing -ES version



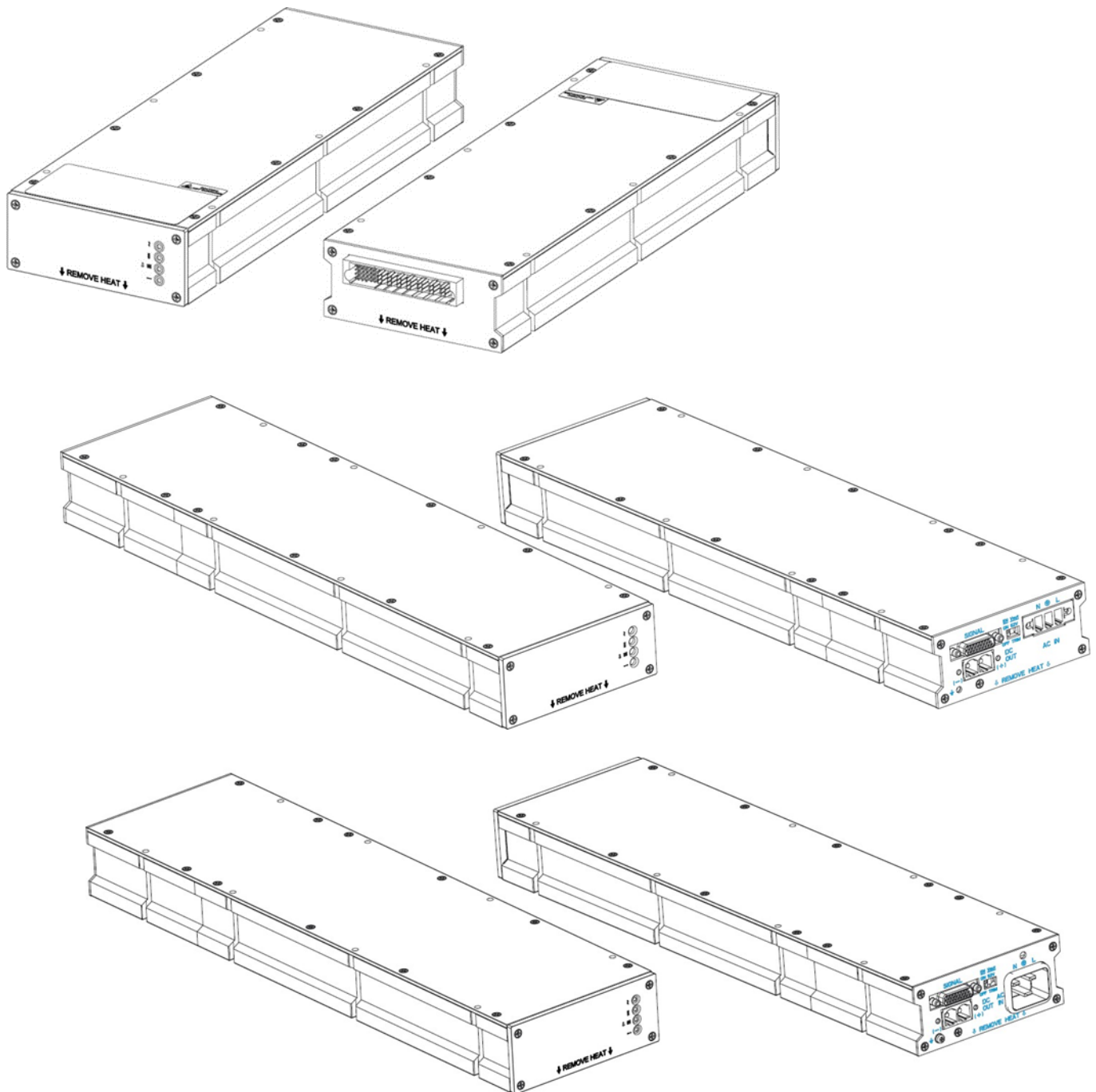
Outline Drawing -EC version

The cooling device (cold plate, warm wall or heat sink) should be placed in good thermal contact with the entire “cooling side” (lower view above) but not necessarily the extension. This may be done by using thermal grease or a thermal interface pad between them

Technical Specifications (continued)

Application Notes:

Be notice that there are “REMOVE HEAT” AND ARROWS silkscreen on both front and rear panel to show the surface to contact with cold plate/heatsink.



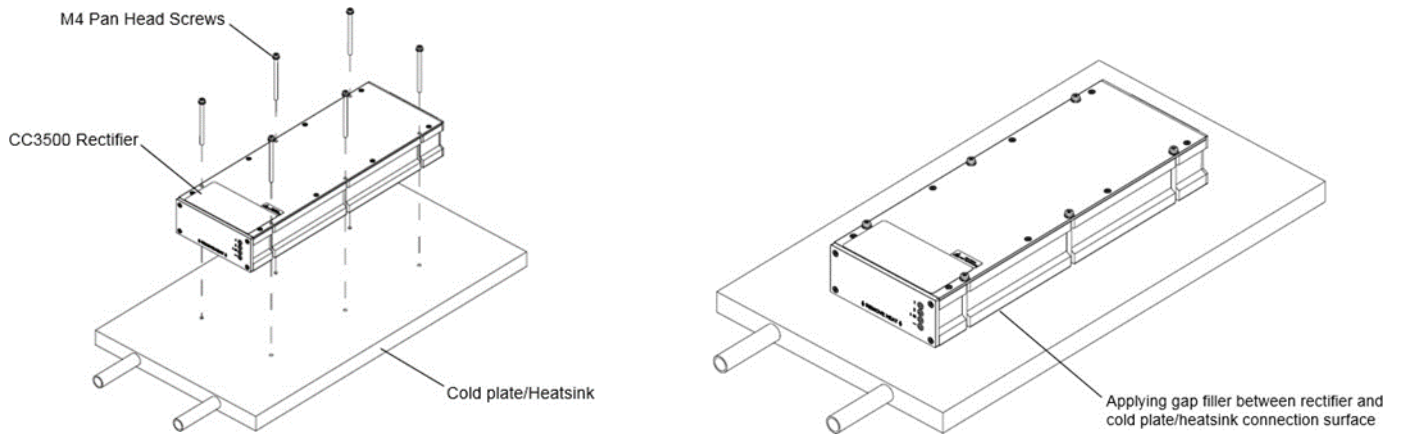
Technical Specifications (continued)

There are 2 options for installing the module with cold plate/Heatsink:

Option 1:

Install the module to the cold plate/heatsink with 6 M4 pan head screw from the module top, Torque to be 1.5Nm
 Apply gap filler, Laird T-putty 504, or other equivalent material, Thermal Conductivity is no less than 1.8 W/mK
 between the unit and cold plate/heatsink

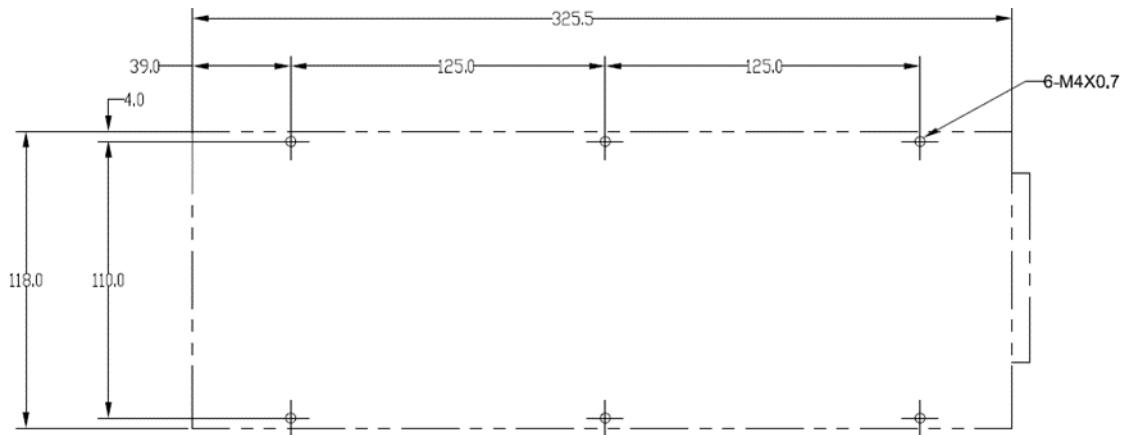
Amount is 1.15 cubic inch approx. thickness is 0.02inch approx.



(upon figure as a reference)

For Rectifier with Blind-Mate Connector:

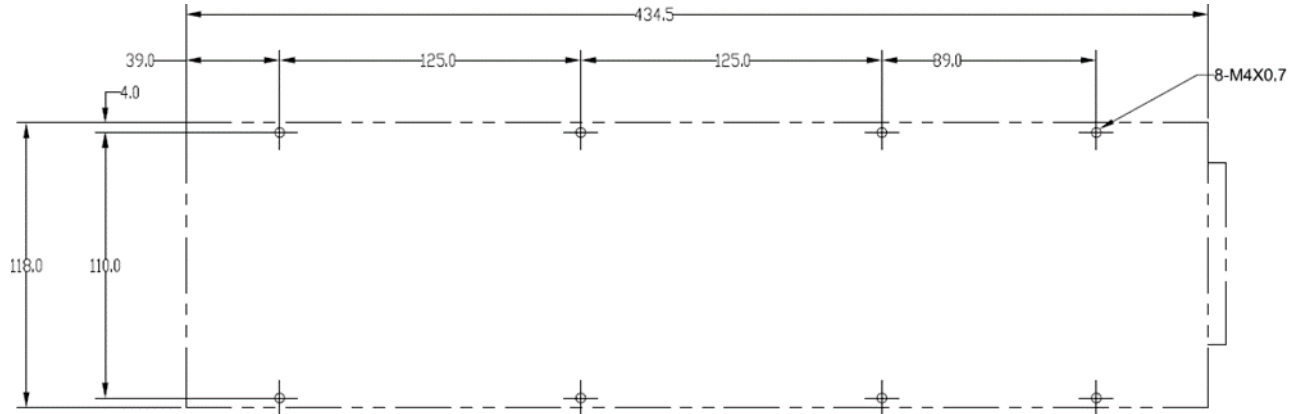
Drill 6 M4X0.7 thread holes on cold plate/heatsink as the following drawing for installing the module.



Technical Specifications (continued)

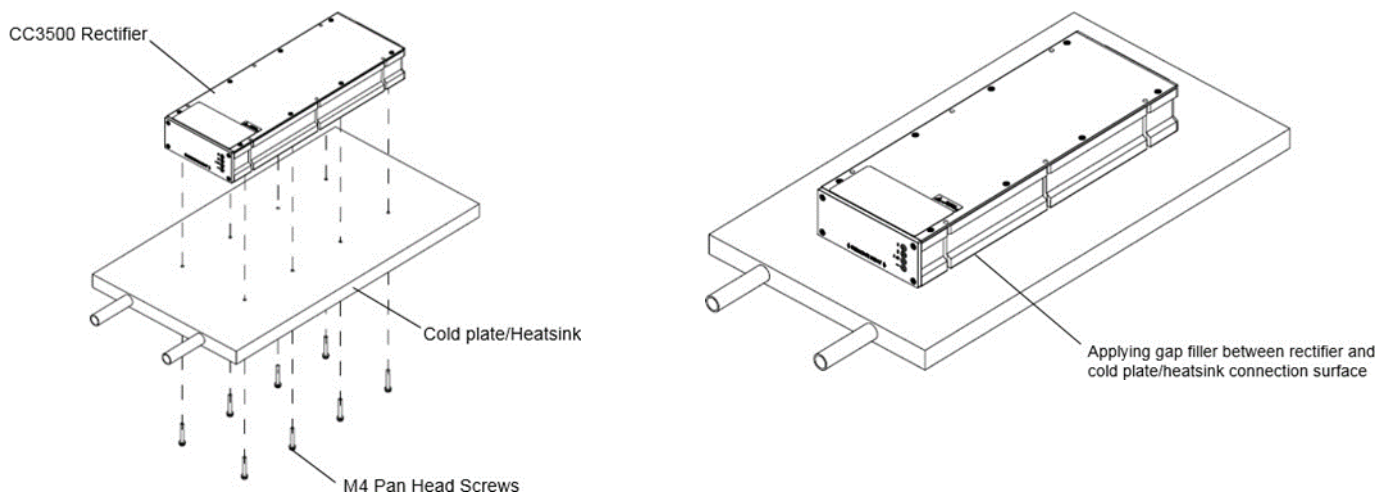
For Rectifier with Extension for Filters & Non-Blind-Mate Connectors (-EC & -ES versions):

Drill 8 M4X0.7 thread holes on cold plate/heatsink as the following drawing for installing the module.



Option 2:

Install the module to the cold plate/heatsink with 8 M4 pan head screw from cold plate /heatsink bottom

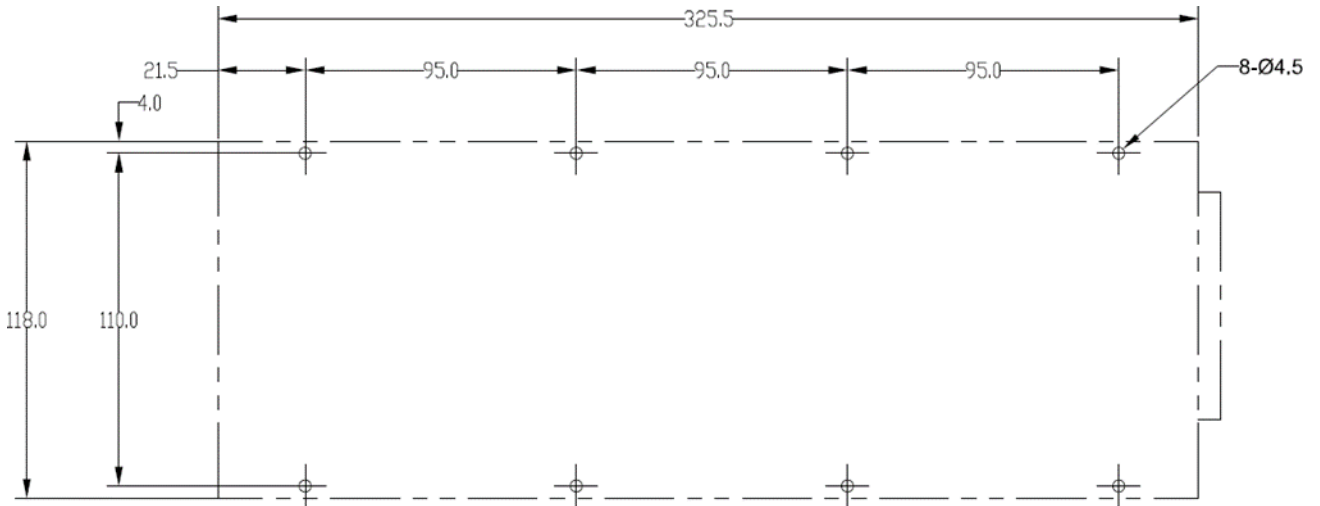


(upon figure as a reference)

Technical Specifications (continued)

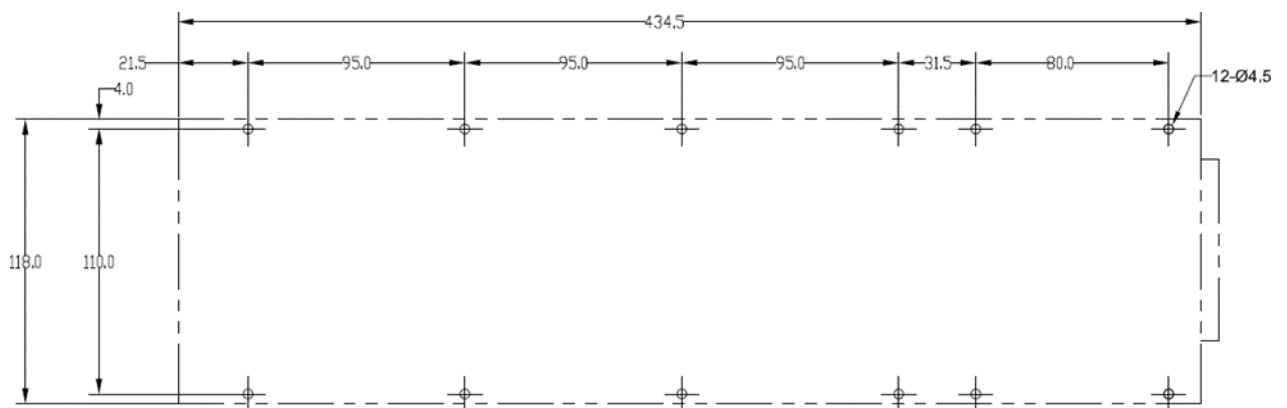
For Rectifier with Blind-Mate Connector:

Drill 8 ϕ 4.5mm through holes on cold plate/heatsink as the following drawing for installing the module.



For Rectifier with Extension for Filters & Non-Blind-Mate Connectors (-EC & -ES versions):

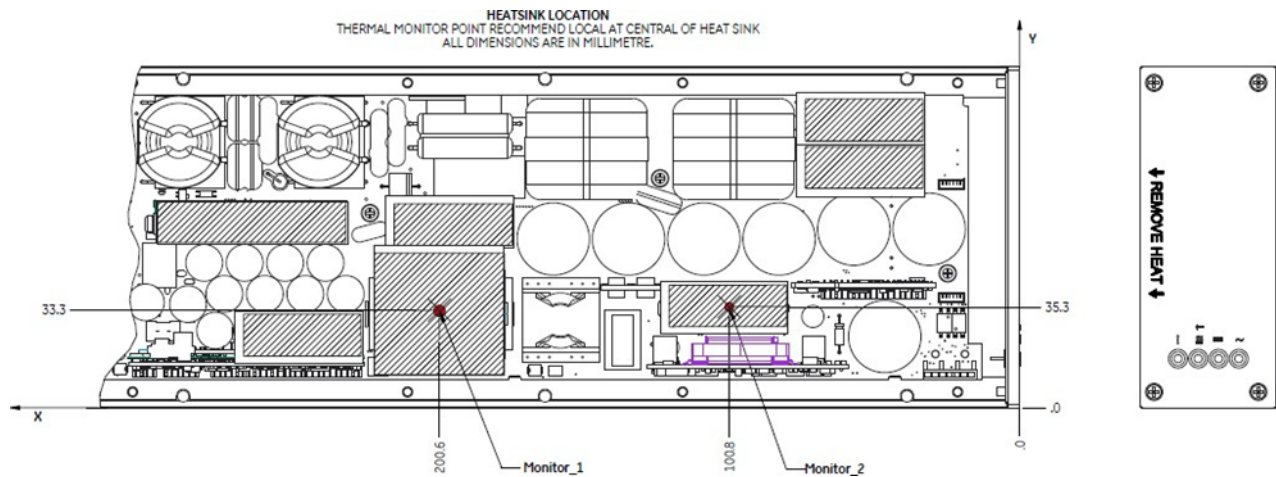
Drill 12 ϕ 4.5mm through holes on cold plate/heatsink as the following drawing for installing the module.



Technical Specifications (continued)

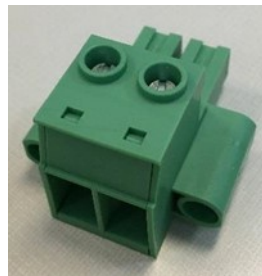
Temperature Monitoring Location

The following graphic shows the heatsink location, and heatsinks are the hot spots, should maintain the surface temperature above these hot spots at the recommended operating temperature or below. normally, the HS_1 (monitor_1) the and the HS_2 (monitor_2) are the hottest spot, so can assume these two hot spots surface temperature (cold plate side) as the case temperature.



DC Output Connector

A 2-pin Phoenix Contact 1998784 header is provided on the back of the unit, delivered with the removable Phoenix 1711378 screw-terminal plug installed.



Selected plug ratings (from Phoenix Contact):

- Wire sizes: AWG# 18-6
- Stripping length: 12 mm
- Torque: 1.7-1.8 Nm

* UL is a registered trademark of Underwriters Laboratories, Inc.

† CSA is a registered trademark of Canadian Standards Association.

‡ VDE is a trademark of Verband Deutscher Elektrotechniker e.V.

§ This product is intended for integration into end-user equipment. All CE marking procedures of end-user equipment should be followed. (The CE mark is placed on selected products.)

** ISO is a registered trademark of the International Organization of Standards

+ The PMBus name and logo are registered trademarks of the System Management Interface Forum (SMIF)

¹ At output voltages exceeding 52V_{DC}

Technical Specifications (continued)

Accessories

| Item | Description | Part number |
|---|---|-------------------------------|
|  | Single-unit cable assembly that mates with rectifier Blind-Mate connector. (sold as a component; equipment containing this harness requires safety certification), it is for 150052312 CC3500AC52FB | 850045138 |
| Will add Picuture | AC input connector for 150052315 CC3500AC52FB-EC IEC C20 socket | CC848820317 or CC848847368 |
|  | AC input connector for 150052316 CC3500AC52FB-ES Phoenix 1778188 | 4600096713P |
|  | Output connector for 150052315 CC3500AC52FB-EC & 150052316 CC3500AC52FB-ES Phoenix 1711378 | 4600096670P |
| Will add Picuture | Signal cable assembly for 150052315 CC3500AC52FB-EC & 150052316 CC3500AC52FB-ES | 8600096719P |
|  | 1u_CC3500_interface; Rectifier interface board. This debug tool can be used to evaluate the performance of the rectifier. The input interface is a standard IEC 320 C20 type socket. Outputs are connected via standard 0.25 fast-ons. It is for use with rectifier 1600158240A and 150052312 only | 150039572 |
|  | Isolated Interface Adapter Kit – interface between a USB port and the I ² C connector on the rectifier interface board. Includes a cable set to the PC and to the 1u_CC3500_interface board above. | 150036482 |
|  | <p>The site below downloads the OmniOn Power Digital Power Insight™ software tools, including the pro_GUI. When the download is complete, icons for the various utilities will appear on the desktop. Click on pro_GUI.exe to start the program after the download is complete.</p> <p>http://powertalk.campaigns.omnionpower.com/DigitalPowerInsight.html</p> <p>Graphical User Interface Manual; The GUI download created a  directory In that directory start the DPI_manual.pdf file.</p> | Free download |

Technical Specifications (continued)

Ordering Information

Please contact your OmniOn Power Sales Representative for pricing, availability and optional features.

| Item | Description | Ordering code |
|------------------|--|---------------|
| CC3500AC52FB | Rectifier with blind-mate connector (short model); VO range 18-53V | 150052312 |
| CC3500AC52FB-EC | Rectifier with extension for screw-terminal dc connector & IEC C19 ac connector; VO range 18-53V | 150052315 |
| CC3500AC52FB-ES | Rectifier with extension for screw-terminal dc & ac connectors; VO range 18-53V | 150052316 |
| CC3500AC52FB2 | Rectifier with blind-mate connector (short model); VO range 18-58V | 1600158240A |
| CC3500AC52FB2-EC | Rectifier with extension for screw-terminal dc connector & IEC C19 ac connector; VO range 18-58V | 1600158241A |
| CC3500AC52FB2-ES | Rectifier with extension for screw-terminal dc & ac connectors; VO range 18-58V | 1600158242A |

Table 4: Device Codes

Contact Us

For more information, call us at

1-877-546-3243 (US)

1-972-244-9288 (Int'l)

Change History (excludes grammar & clarifications)

| Revision | Date | Description of the change |
|----------|------------|--------------------------------------|
| 7.3 | 12/23/2021 | Updated as per template |
| 7.4 | 06/27/2023 | Correction in characteristics curves |
| 7.5 | 11/02/2023 | Updated as per OmniOn template |

OmniOn Power Inc.

601 Shiloh Rd.
Plano, TX USA

omnionpower.com

We reserve the right to make technical changes or modify the contents of this document without prior notice. OmniOn Power does not accept any responsibility for errors or lack of information in this document and makes no warranty with respect to and assumes no liability as a result of any use of information in this document.

We reserve all rights in this document and in the subject matter and illustrations contained therein. Any reproduction, disclosure to third parties or utilization of its contents – in whole or in parts – is forbidden without prior written consent of OmniOn Power. This document does not convey license to any patent or any intellectual property right. Copyright© 2023 OmniOn Power Inc. All rights reserved.