

# AMR132x

360°, Ultra-Low Power, Omnipolar Switch Sensor

#### Description

The AMR132x is an omnipolar magnetic switch integrated with anisotropic magnetoresistance (AMR) magnetic sensor and CMOS circuitry, which is able to detect the change of magnetic field and output high and low voltage signals for high accuracy position detection.

The AMR132x series switch can detect magnetic fields from all directions in the plane, enabling  $360^{\circ}$  sensing. It provides 100 Hz sampling frequency, 1  $\mu$ A power consumption, and a wide range of operating voltages from 1.8 V to 5.5 V. It has excellent thermal stability and immunity to stray field interference.

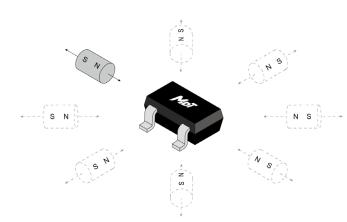
The AMR132x available in the compact SOT23-3 package.

#### **Features and Benefits**

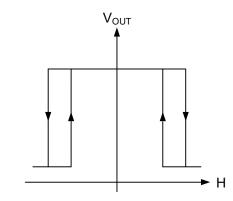
- Anisotropic magnetoresistance (AMR) technology
- Low power consumption at 1 μA
- Fast internal switching frequency at 100 Hz
- Omnipolar operation
- High sensitivity
- Wide range supply voltages: 1.8 V to 5.5V
- CMOS output
- Excellent temperature stability
- High tolerance to external magnetic field interference
- RoHS & REACH compliant

#### Applications

- Utility meters: water, gas, and heat meters
- Proximity switches
- Speed sensing
- · Linear and rotary position sensing
- · Wake up switches



SOT23-3







### **Selection Guide**

Part Number	Supply Current	Switching Frequency	Operating Ambient Temperature	Operating Point	Release Point	Package	Packing Form
AMR1320S	1 µA	30 Hz	-40 °C to 125 °C	±17 Gs	±12 Gs	SOT23-3	Tape & Reel
AMR1321S	3 μΑ	100 Hz	-40 °C to 125 °C	±25 Gs	±20 Gs	SOT23-3	Tape & Reel
Note: Please contact MultiDimension Technology local sales for customizing operating and release points.							

# Catalogue

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#### 1. Functional Block Diagram

The AMR132x series switches are composed of AMR sensors and signal processing circuits. The AMR sensor detects external magnetic field, generates an analog voltage signal, and outputs a logical switch level after processing by the circuit as shown in Figure 1.

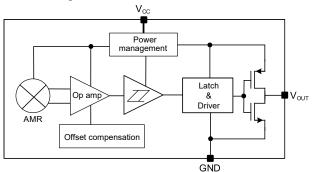


Figure 1. Block diagram

#### 2. Switching Characteristics

Figure 2 shows the sensing direction is parallel to the laser mark surface of the package as shown by the arrows in the X-Y plane.

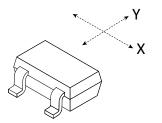


Figure 2. Sensing direction

The output is "High", when power is on at zero magnetic field. B is the external magnetic field along the sensing direction,  $B_{OPS}$  ( $B_{OPN}$ ) is the operating point,  $B_{RPS}$  ( $B_{RPN}$ ) is the release point, and hysteresis  $B_{H}$  is define as the difference between  $B_{OPS}$  and  $B_{RPS}$  ( $B_{OPN}$  and  $B_{RPN}$ ).

The sensor outputs a high level, when the magnetic field along the sensing axis exceed the operating point  $B_{OPS}$  ( $B_{OPN}$ ), and the device outputs a low level, when the magnetic field is reduced below the release point  $B_{RPS}$  ( $B_{RPN}$ ) as shown in Figure 3.

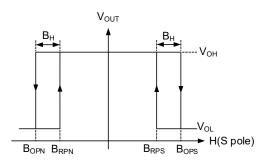


Figure 3. Switching characteristics

## 3. Pin Configuration

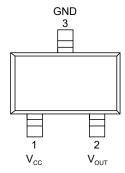


Figure 4. Pin configuration (SOT23-3)

Pin Number	Name	Function	
1	V <sub>cc</sub>	Power supply	
2	V <sub>OUT</sub>	Output	
3	GND	Ground	





#### 4. Absolute Maximum Ratings

Parameters	Symbol	Min.	Max.	Unit
Supply voltage	V <sub>cc</sub>	-0.3	7	V
Output current	I <sub>SINK</sub> , I <sub>SOURCE</sub> <sup>1)</sup>	-	9	mA
Magnetic flux density	В	-	4000	Gs
ESD performance (HBM)	V <sub>ESD</sub>	-	4	kV
Operating ambient temperature	T <sub>A</sub>	-40	125	٦°
Storage ambient temperature	T <sub>STG</sub>	-50	150	°C

1)  $I_{SINK}$  is the current flowing through the pin of switch, when the output is turned on.  $I_{SOURCE}$  is the current flowing through the pin of the switch, when the output is turned off.

#### 5. Electrical Specifications

 $V_{\text{CC}}$  = 3 V,  $T_{\text{A}}$  = 25 °C, a 0.1  $\mu\text{F}$  capacitor is connected between  $V_{\text{CC}}$  and GND unless specified otherwise

Parameter	Symbol	Condition	Min.	Тур.	Max.	Unit	Applicable Part Number
Supply voltage	$V_{cc}$	Operating	1.8	3.0	5.5	V	All parts
Output high voltage	V <sub>OH</sub>	RP	V <sub>cc</sub> - 0.3	-	V <sub>cc</sub>	V	All parts
Output low voltage	V <sub>OL</sub>	OP	0	-	0.2	V	All parts
Supply current		OP/RP	-	1.0	-	μA	AMR1320S
	I <sub>CC</sub>	UF/RF	-	3.0	5.0	μA	AMR1321S
Switching frequency	F	-	-	30	- Hz AMR1320S	AMR1320S	
	r -	-	-	100	-	Hz	AMR1321S

#### 6. Magnetic Specifications

 $V_{cc}$  = 3 V,  $T_A$  = 25 °C, a 0.1 µF capacitor is connected between  $V_{cc}$  and GND unless specified otherwise AMR1320S

Parameter	Symbol	Min.	Тур.	Max.	Unit
Operate point	B <sub>OPS</sub>	10	17	25	Gs
	B <sub>OPN</sub>	-25	-17	-10	Gs
Release point	B <sub>RPS</sub>	8	12	20	Gs
	B <sub>RPN</sub>	-20	-12	-8	Gs
Hysteresis	B <sub>H</sub>	-	5	-	Gs

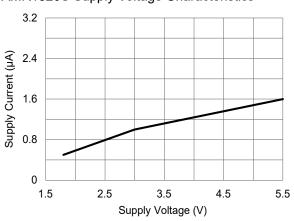
AMR1321S

Parameter	Symbol	Min.	Тур.	Max.	Unit
Operate point	B <sub>OPS</sub>	10	25	40	Gs
	B <sub>OPN</sub>	-40	-25	-10	Gs
Release point	B <sub>RPS</sub>	8	20	35	Gs
	B <sub>RPN</sub>	-35	-20	-8	Gs
Hysteresis	B <sub>H</sub>	2	5	10	Gs



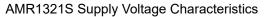


#### 7. Typical Supply Voltage Characteristics



AMR1320S Supply Voltage Characteristics





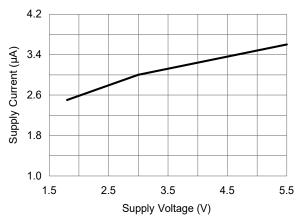


Figure 7. Supply current versus supply voltage ( $T_A=25^{\circ}C$ )

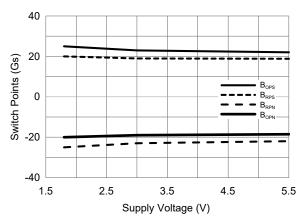


Figure 6. Switch points versus supply voltage ( $T_A=25^{\circ}C$ )

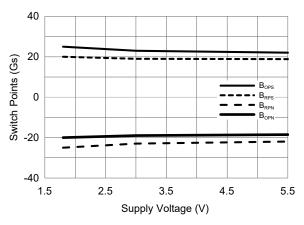
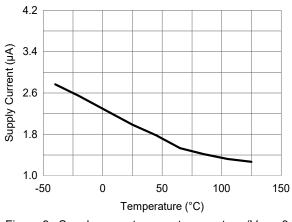


Figure 8. Switch points versus supply voltage ( $T_A=25^{\circ}C$ )

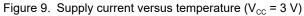




#### 8. Typical Temperature Characteristics



AMR1320S Temperature Characteristics



#### AMR1321S Temperature Characteristics

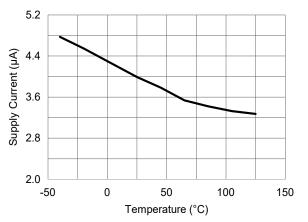


Figure 11. Supply current versus temperature ( $V_{CC}$  = 3 V)

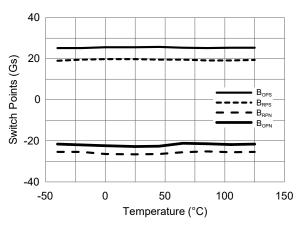


Figure 10. Switch points versus temperature (V<sub>cc</sub> = 3 V)

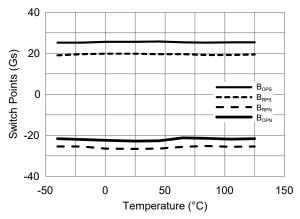


Figure 12. Switch points versus temperature ( $V_{CC}$  = 3 V)





#### 9. Application Information

It is recommended to add a filter capacitor with the typical value of 0.1  $\mu$ F between the switch power supply and ground (close to the sensor) to reduce external noise as shown in Figure 13.

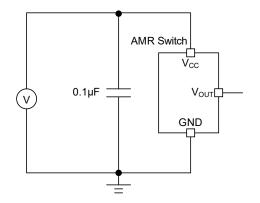


Figure 13. Application circuit diagram

The AMR132x is not suitable for driving power loads. Figure 14 illustrates the general method of improving the drive capability is utilizing the output voltage of  $V_{OUT}$  pin as a signal to input the MCU or drive a triode or MOS.

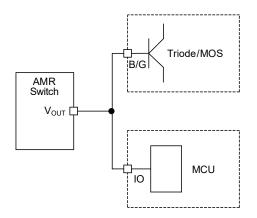


Figure 14. Application diagram for driving power load

Common failure conditions:

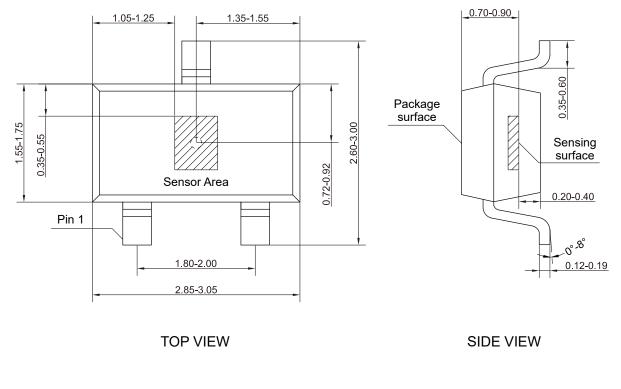
- The supply voltage exceeds the limit of absolute maximum ratings
- Absence of matching filter capacitor to power supply when the power supply is unstable, which can cause the product to restart repeatedly
- Using switch output V<sub>OUT</sub> to control high-power relays, etc., and cause I<sub>SINK</sub>, I<sub>SOURCE</sub> exceeding the limit of absolute maximum ratings
- The external magnetic field exceeds the limit of absolute maximum ratings
- Operating in a humid environment for a long time, causing vapor penetration and increased power consumption
- Overheating when soldering
- Over bending of pins

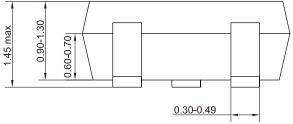




#### 10. Dimensions

#### SOT23-3 Package





SIDE VIEW





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