

# S-93C46B/56B/66B

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# 3-WIRE SERIAL E<sup>2</sup>PROM

Rev.8.1 02

The S-93C46B/56B/66B is a high speed, low current consumption, 3-wire serial E<sup>2</sup>PROM with a wide operating voltage range. The S-93C46B/56B/66B has the capacity of 1 K-bit, 2 K-bit and 4 K-bit, and the organization is 64-word × 16-bit, 128-word × 16-bit and 256-word × 16-bit. It is capable of sequential read, at which time addresses are automatically incremented in 16-bit blocks.

The communication method is by the Microwire bus.

# Features

- Operating voltage range: Read 1.8 V to 5.5 V
- Write 2.7 V to 5.5 V • Operation frequency: 2.0 MHz ( $V_{CC}$  = 4.5 V to 5.5 V) 8.0 ms max.
- Write time:
- Sequential read capable
- Write protect function during the low power supply voltage
- Function to protect against write due to erroneous instruction recognition
- $10^6$  cycles / word<sup>\*1</sup> (Ta = +85°C) • Endurance: • Data retention: 100 years (Ta =  $+25^{\circ}C$ ) 20 years (Ta =  $+85^{\circ}C$ ) • Memory capacity: S-93C46B 1 K-bit S-93C56B 2 K-bit S-93C66B 4 K-bit • Initial delivery state: FFFFh • Operation temperature range: Ta =  $-40^{\circ}$ C to  $+85^{\circ}$ C
- Lead-free, Sn 100%, halogen-free\*2

\*1. For each address (Word: 16-bit)

\*2. Refer to "
Product Name Structure" for details.

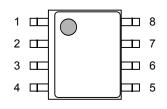
# Packages

- 8-Pin SOP (JEDEC)
- 8-Pin TSSOP
- TMSOP-8
- SNT-8A
- Caution This product is intended to use in general electronic devices such as consumer electronics, office equipment, and communications devices. Before using the product in medical equipment or automobile equipment including car audio, keyless entry and engine control unit, contact to ABLIC Inc. is indispensable.

# ■ Pin Configurations

# 1. 8-Pin SOP (JEDEC)

8-Pin SOP (JEDEC) Top view



### Figure 1

S-93C46BD0I-J8T1x S-93C56BD0I-J8T1x S-93C66BD0I-J8T1x

#### 8-Pin SOP (JEDEC) (Rotated) Top view

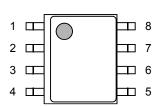


Figure 2

S-93C46BR0I-J8T1x S-93C56BR0I-J8T1x S-93C66BR0I-J8T1x Table 1

Pin No.	Symbol	Description				
1	CS	Chip select input				
2	SK	Serial clock input				
3	DI	Serial data input				
4	DO	Serial data output				
5	GND	Ground				
6	TEST <sup>*1</sup>	Test				
7	NC	No connection				
8	VCC	Power supply				

\*1. Connect to GND or  $V_{CC}$ .

Even if this pin is not connected, performance is not affected so long as the absolute maximum rating is not exceeded.

#### Table 2

Pin No.	Symbol	Description
1	NC	No connection
2	VCC	Power supply
3	CS	Chip select input
4	SK	Serial clock input
5	DI	Serial data input
6	DO	Serial data output
7	GND	Ground
8	TEST <sup>*1</sup>	Test

\*1. Connect to GND or  $V_{\text{CC}}.$ 

Even if this pin is not connected, performance is not affected so long as the absolute maximum rating is not exceeded.

Remark 1. Refer to the "package drawings" for the details.

2. x: G or U

**3.** Please select products of environmental code = U for Sn 100%, halogen-free products.

Description

8-Pin TSSOP Top view

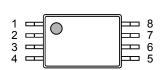
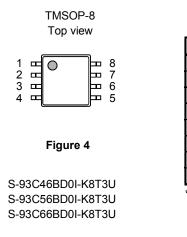


Figure 3

S-93C46BD0I-T8T1x S-93C56BD0I-T8T1x S-93C66BD0I-T8T1x

# 3. TMSOP-8



1	CS	Chip select input						
2	SK	Serial clock input						
3	DI	Serial data input						
4	DO	Serial data output						
5	GND	Ground						
6	TEST <sup>*1</sup>	Test						
7	NC	No connection						
8	VCC	Power supply						
1. Connect to G	Connect to GND or V <sub>CC</sub> .							

Even if this pin is not connected, performance is not affected so long as the absolute maximum rating is not exceeded.

Table 4

Pin No.	Symbol	Description
1	CS	Chip select input
2	SK	Serial clock input
3	DI	Serial data input
4	DO	Serial data output
5	GND	Ground
6	TEST <sup>*1</sup>	Test
7	NC	No connection
8	VCC	Power supply
*1. Connect to (	GND or V <sub>CC</sub> .	

Even if this pin is not connected, performance is not affected so long as the absolute maximum rating is not exceeded.

Remark 1. Refer to the "package drawings" for the details.

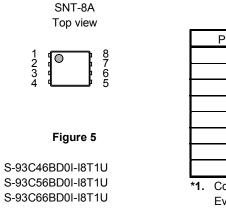
2. x: G or U

3. Please select products of environmental code = U for Sn 100%, halogen-free products.

Pin No.

Symbol

# 4. SNT-8A



Symbol	Description
CS	Chip select input
SK	Serial clock input
DI	Serial data input
DO	Serial data output
GND	Ground
TEST <sup>*1</sup>	Test
NC	No connection
VCC	Power supply
	CS SK DI DO GND TEST <sup>*1</sup> NC

Table 5

**\*1.** Connect to GND or  $V_{CC}$ .

Even if this pin is not connected, performance is not affected so long as the absolute maximum rating is not exceeded.

Remark Refer to the "package drawings" for the details.

# Block Diagram

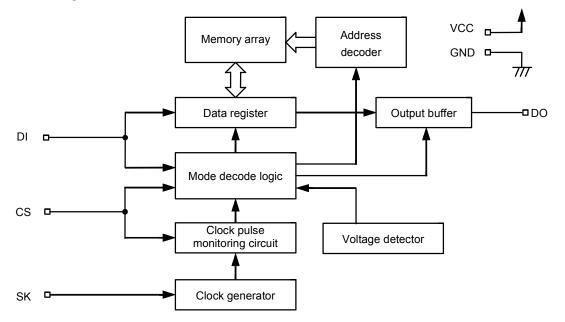


Figure 6

# Instruction Sets

# 1. S-93C46B

Table 6												
Instruction	Start Bit		ation de		Address				Data			
SK input clock	1	2	3	4	5	6	7	8	9	10 to 25		
READ (Read data)	1	1	0	A5	A4	A3	A2	A1	A0	D15 to D0 Output <sup>*1</sup>		
WRITE (Write data)	1	0	1	A5	A4	A3	A2	A1	A0	D15 to D0 Input		
ERASE (Erase data)	1	1	1	A5	A4	A3	A2	A1	A0	_		
WRAL (Write all)	1	0	0	0	1	Х	Х	х	х	D15 to D0 Input		
ERAL (Erase all)	1	0	0	1	0	х	х	х	х	_		
EWEN (Write enable)	1	0	0	1	1	х	х	х	х	—		
EWDS (Write disable)	1	0	0	0	0	х	х	х	х	—		

\*1. When the 16-bit data in the specified address has been output, the data in the next address is output.

Remark x: Don't care

# 2. S-93C56B

Table 7												
Instruction	Start Bit	Opera Cod					Addre	ess				Data
SK input clock	1	2	3	4	5	6	7	8	9	10	11	12 to 27
READ (Read data)	1	1	0	х	A6	A5	A4	A3	A2	A1	A0	D15 to D0 Output <sup>*1</sup>
WRITE (Write data)	1	0	1	х	A6	A5	A4	A3	A2	A1	A0	D15 to D0 Input
ERASE (Erase data)	1	1	1	х	A6	A5	A4	A3	A2	A1	A0	_
WRAL (Write all)	1	0	0	0	1	х	х	х	х	Х	Х	D15 to D0 Input
ERAL (Erase all)	1	0	0	1	0	х	х	х	х	х	Х	—
EWEN (Write enable)	1	0	0	1	1	х	х	х	х	Х	Х	—
EWDS (Write disable)	1	0	0	0	0	Х	Х	Х	Х	Х	х	—

\*1. When the 16-bit data in the specified address has been output, the data in the next address is output.

Remark x: Don't care

#### 3. S-93C66B

Table 8

Instruction	Start Bit	Opera Coc					Addre	ess				Data
SK input clock	1	2	3	4	5	6	7	8	9	10	11	12 to 27
READ (Read data)	1	1	0	A7	A6	A5	A4	A3	A2	A1	A0	D15 to D0 Output <sup>*1</sup>
WRITE (Write data)	1	0	1	A7	A6	A5	A4	A3	A2	A1	A0	D15 to D0 Input
ERASE (Erase data)	1	1	1	A7	A6	A5	A4	A3	A2	A1	A0	
WRAL (Write all)	1	0	0	0	1	х	х	х	Х	х	х	D15 to D0 Input
ERAL (Erase all)	1	0	0	1	0	х	х	х	х	х	Х	
EWEN (Write enable)	1	0	0	1	1	х	х	х	х	Х	Х	_
EWDS (Write disable)	1	0	0	0	0	х	Х	Х	Х	х	Х	

\*1. When the 16-bit data in the specified address has been output, the data in the next address is output.

Remark x: Don't care

# ■ Absolute Maximum Ratings

### Table 9

Item	Symbol	Ratings	Unit
Power supply voltage	V <sub>cc</sub>	-0.3 to +7.0	V
Input voltage	V <sub>IN</sub>	–0.3 to V <sub>CC</sub> + 0.3	V
Output voltage	V <sub>OUT</sub>	-0.3 to V <sub>CC</sub>	V
Operation ambient temperature	T <sub>opr</sub>	-40 to +105	°C
Storage temperature	T <sub>sta</sub>	–65 to +150	°C

Caution The absolute maximum ratings are rated values exceeding which the product could suffer physical damage. These values must therefore not be exceeded under any conditions.

# Recommended Operating Conditions

Table 10									
ltom	Cumbal	Conditions	Ta = -40°	C to +85°C	Linit				
Item	Symbol	Conditions	Min.	Max.	Unit				
		READ, EWDS	1.8	5.5	V				
Power supply voltage	V <sub>cc</sub>	WRITE, ERASE, WRAL, ERAL, EWEN	2.7	5.5	V				
		$V_{CC}$ = 4.5 V to 5.5 V	2.0	V <sub>cc</sub>	V				
High level input voltage	V <sub>IH</sub>	$V_{CC}$ = 2.7 V to 4.5 V	$0.8 \times V_{CC}$	V <sub>CC</sub>	V				
		V <sub>CC</sub> = 1.8 V to 2.7 V	$0.8 \times V_{CC}$	V <sub>CC</sub>	V				
		V <sub>CC</sub> = 4.5 V to 5.5 V	0.0	0.8	V				
Low level input voltage	V <sub>IL</sub>	$V_{CC}$ = 2.7 V to 4.5 V	0.0	$0.2\times V_{CC}$	V				
		V <sub>CC</sub> = 1.8 V to 2.7 V	0.0	$0.15 \times V_{CC}$	V				

# ■ Pin Capacitance

#### Table 11

			(Ta = +25°C, f	= 1.0 MHz, V <sub>CC</sub>	; = 5.0 V)
Item	Symbol	Conditions	Min.	Max.	Unit
Input Capacitance	C <sub>IN</sub>	$V_{IN} = 0 V$	_	8	pF
Output Capacitance	C <sub>OUT</sub>	$V_{OUT} = 0 V$		10	pF

# Endurance

Table 12

Item	Symbol	Operation Ambient Temperature	Min.	Max.	Unit
Endurance	Nw	Ta = –40°C to +85°C	10 <sup>6</sup>		cycles / word*1

**\*1.** For each address (Word: 16-bit)

# Data Retention

Table 13

Item	Symbol	Operation Ambient Temperature	Min.	Max.	Unit
Data retention	-	Ta = +25°C	100		year
		Ta = –40°C to +85°C	20		year

# ■ DC Electrical Characteristics

Table 14										
		Conditions	Ta = -40°C to +85°C							
Item	Symbol		V <sub>cc</sub> = 4.5 V to 5.5 V		V <sub>CC</sub> = 2.5 V to 4.5 V		V <sub>CC</sub> = 1.8 V to 2.5 V		Unit	
			Min.	Max.	Min.	Max.	Min.	Max.		
Current consumption (READ)	I <sub>CC1</sub>	DO no load		0.8		0.5		0.4	mA	

Table 15										
		Conditions	Ta = -40°C to +85°C							
Item	Symbol		$V_{\rm CC} = 4.5$	V to 5.5 V	$V_{CC}$ = 2.7 V to 4.5 V		Unit			
			Min.	Max.	Min.	Max.				
Current consumption (WRITE)	I <sub>CC2</sub>	DO no load	_	2.0	_	1.5	mA			

Table 16									
			Ta = -40°C to +85°C						
Item	Symbol	Conditions	V <sub>CC</sub> =		V <sub>cc</sub>		V <sub>CC</sub> =		Unit
nom	Cymbol	Conditions	4.5 V to	5.5 V	2.5 V to	4.5 V	1.8 V to	2.5 V	Onic
			Min.	Max.	Min.	Max.	Min.	Max.	
Standby current consumption	I <sub>SB</sub>	CS = GND, DO = Open, Other inputs to $V_{CC}$ or GND		1.5	_	1.5	_	1.5	μA
Input leakage current	I <sub>LI</sub>	$V_{IN}$ = GND to $V_{CC}$		1.0	_	1.0		1.0	μ <b>A</b>
Output leakage current	I <sub>LO</sub>	$V_{OUT}$ = GND to $V_{CC}$		1.0	_	1.0	_	1.0	μA
Low level output	N/	I <sub>OL</sub> = 2.1 mA	_	0.4	_	_	_	_	V
voltage	V <sub>OL</sub>	I <sub>OL</sub> = 100 μA	_	0.1	_	0.1	_	0.1	V
		I <sub>OH</sub> = –400 μA	2.4	_			_	_	V
High level output	V <sub>OH</sub>	I <sub>OH</sub> = –100 μA	V <sub>CC</sub> – 0.3		$V_{CC} - 0.3$		_	_	V
voltage		I <sub>OH</sub> = –10 μA	V <sub>CC</sub> -0.2	_	V <sub>CC</sub> -0.2		V <sub>CC</sub> -0.2	_	V
Data hold voltage of write enable latch	V <sub>DH</sub>	Only program disable mode	1.5	_	1.5		1.5	_	V

# ■ AC Electrical Characteristics

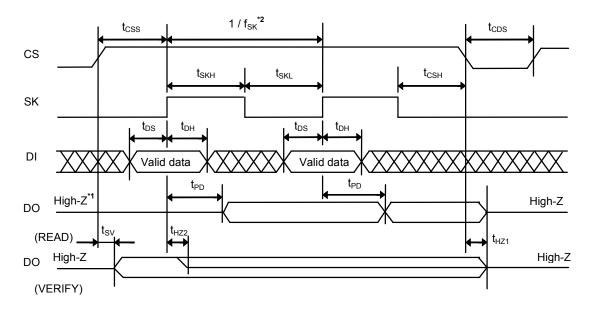
Input pulse voltage	$0.1 \times V_{CC}$ to $0.9 \times V_{CC}$
Output reference voltage	$0.5  imes V_{CC}$
Output load	100 pF

			Ta = -40°C to +85°C							
Item	Symbol	V <sub>CC</sub> = 4.5	V to 5.5 V	V <sub>CC</sub> = 2.5	V to 4.5 V	V <sub>CC</sub> = 1.8	V to 2.5 V	Unit		
		Min.	Max.	Min.	Max.	Min.	Max.			
CS setup time	t <sub>css</sub>	0.2		0.4		1.0		μS		
CS hold time	t <sub>CSH</sub>	0	_	0	_	0		μs		
CS deselect time	t <sub>CDS</sub>	0.2	_	0.2	_	0.4		μS		
Data setup time	t <sub>DS</sub>	0.1	_	0.2		0.4		μs		
Data hold time	t <sub>DH</sub>	0.1	_	0.2		0.4		μs		
Output delay time	t <sub>PD</sub>		0.4		0.8		2.0	μs		
Clock frequency <sup>*1</sup>	f <sub>SK</sub>	0	2.0	0	0.5	0	0.25	MHz		
SK clock time "L"*1	t <sub>SKL</sub>	0.1	_	0.5	_	1.0		μS		
SK clock time "H"*1	t <sub>sкн</sub>	0.1	_	0.5		1.0		μS		
Output disable time	$t_{HZ1}, t_{HZ2}$	0	0.15	0	0.5	0	1.0	μS		
Output enable time	t <sub>sv</sub>	0	0.15	0	0.5	0	1.0	μS		

\*1. The clock cycle of the SK clock (frequency:  $f_{SK}$ ) is 1 /  $f_{SK}$  µs. This clock cycle is determined by a combination of several AC characteristics, so be aware that even if the SK clock cycle time is minimized, the clock cycle (1 /  $f_{SK}$ ) cannot be made equal to  $t_{SKL}$  (min.) +  $t_{SKH}$  (min.).

Table 19								
		Ta =	–40°C to +85°C					
Item	Symbol	$V_{CC}$ = 2.7 V to 5.5 V						
		Min.	Тур.	Max.				
Write time	t <sub>PR</sub>		4.0	8.0	ms			

Table 18



- \*1. Indicates high impedance.
- \*2. 1 /  $f_{SK}$  is the SK clock cycle. This clock cycle is determined by a combination of several AC characteristics, so be aware that even if the SK clock cycle time is minimized, the clock cycle (1 /  $f_{SK}$ ) cannot be made equal to  $t_{SKL}$  (min.) +  $t_{SKH}$  (min.).



# Initial Delivery State

Initial delivery state of all addresses is "FFFFh".

# Operation

All instructions are executed by inputting DI in synchronization with the rising edge of SK after CS goes high. An instruction set is input in the order of start bit, instruction, address, and data.

Instruction input finishes when CS goes low. A low level must be input to CS between commands during  $t_{CDS}$ . While a low level is being input to CS, the S-93C46B/56B/66B is in standby mode, so the SK and DI inputs are invalid and no instructions are allowed.

# Start Bit

A start bit is recognized when the DI pin goes high at the rise of SK after CS goes high. After CS goes high, a start bit is not recognized even if the SK pulse is input as long as the DI pin is low.

### 1. Dummy clock

SK clocks input while the DI pin is low before a start bit is input are called dummy clocks. Dummy clocks are effective when aligning the number of instruction sets (clocks) sent by the CPU with those required for serial memory operation. For example, when a CPU instruction set is 16 bits, the number of instruction set clocks can be adjusted by inserting a 7-bit dummy clock for the S-93C46B and a 5-bit dummy clock for the S-93C56B/66B.

### 2. Start bit input failure

- When the output status of the DO pin is high during the verify period after a write operation, if a high level is input to the DI pin at the rising edge of SK, the S-93C46B/56B/66B recognizes that a start bit has been input. To prevent this failure, input a low level to the DI pin during the verify operation period (refer to "4. 1 Verify operation").
- When a 3-wire interface is configured by connecting the DI input pin and DO output pin, a period in which the data output from the CPU and the serial memory collide may be generated, preventing successful input of the start bit. Take the measures described in "■ 3-Wire Interface (Direct Connection between DI and DO)".

### 3. Reading (READ)

The READ instruction reads data from a specified address.

After CS has gone high, input an instruction in the order of the start bit, read instruction, and address. Since the last input address ( $A_0$ ) has been latched, the output status of the DO pin changes from high impedance (High-Z) to low, which is held until the next rise of SK. 16-bit data starts to be output in synchronization with the next rise of SK.

#### 3.1 Sequential read

After the 16-bit data at the specified address has been output, inputting SK while CS is high automatically increments the address, and causes the 16-bit data at the next address to be output sequentially. The above method makes it possible to read the data in the whole memory space. The last address ( $A_n \bullet \bullet A_1 A_0 = 1 \bullet \bullet \bullet 11$ ) rolls over to the top address ( $A_n \bullet \bullet \bullet A_1 A_0 = 0 \bullet \bullet \bullet 00$ ).

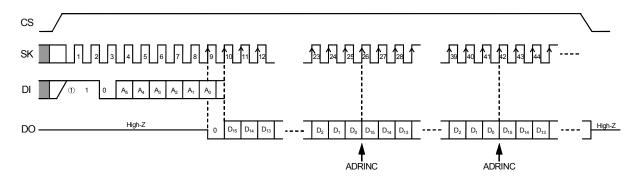


Figure 8 Read Timing (S-93C46B)

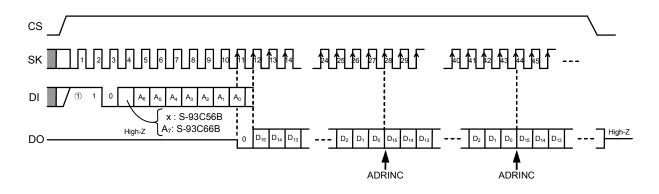


Figure 9 Read Timing (S-93C56B, S-93C66B)

# 4. Writing (WRITE, ERASE, WRAL, ERAL)

A write operation includes four write instructions: data write (WRITE), data erase (ERASE), chip write (WRAL), and chip erase (ERAL).

A write instruction (WRITE, ERASE, WRAL, ERAL) starts a write operation to the memory cell when a low level is input to CS after a specified number of clocks have been input. The SK and DI inputs are invalid during the write period, so do not input an instruction.

Input an instruction while the output status of the DO pin is high or high impedance (High-Z).

A write operation is valid only in program enable mode (refer to "5. Write enable (EWEN) and write disable (EWDS)").

#### 4.1 Verify operation

A write operation executed by any instruction is completed within 8 ms (write time  $t_{PR}$ : typically 4 ms), so if the completion of the write operation is recognized, the write cycle can be minimized. A sequential operation to confirm the status of a write operation is called a verify operation.

### 4.1.1 Operation

After the write operation has started (CS = low), the status of the write operation can be verified by confirming the output status of the DO pin by inputting a high level to CS again. This sequence is called a verify operation, and the period that a high level is input to the CS pin after the write operation has started is called the verify operation period.

The relationship between the output status of the DO pin and the write operation during the verify operation period is as follows.

- DO pin = low: Writing in progress (busy)
- DO pin = high: Writing completed (ready)

### 4.1.2 Operation example

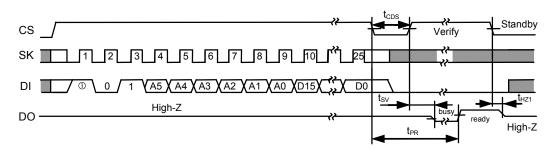
There are two methods to perform a verify operation: Waiting for a change in the output status of the DO pin while keeping CS high, or suspending the verify operation (CS = low) once and then performing it again to verify the output status of the DO pin. The latter method allows the CPU to perform other processing during the wait period, allowing an efficient system to be designed.

#### Caution 1. Input a low level to the DI pin during a verify operation.

2. If a high level is input to the DI pin at the rise of SK when the output status of the DO pin is high, the S-93C46B/56B/66B latches the instruction assuming that a start bit has been input. In this case, note that the DO pin immediately enters a high-impedance (High-Z) state.

#### 4. 2 Writing data (WRITE)

To write 16-bit data to a specified address, change CS to high and then input the WRITE instruction, address, and 16-bit data following the start bit. The write operation starts when CS goes low. There is no need to set the data to 1 before writing. If the clocks more than the specified number have been input, the clock pulse monitoring circuit cancels the WRITE instruction. For details of the clock pulse monitoring circuit, refer to "■ Function to Protect Against Write due to Erroneous Instruction Recognition".





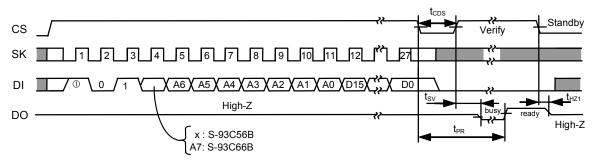


Figure 11 Data Write Timing (S-93C56B, S-93C66B)

### 4.3 Erasing data (ERASE)

To erase 16-bit data at a specified address, set all 16 bits of the data to 1, change CS to high, and then input the ERASE instruction and address following the start bit. There is no need to input data. The data erase operation starts when CS goes low. If the clocks more than the specified number have been input, the clock pulse monitoring circuit cancels the ERASE instruction. For details of the clock pulse monitoring circuit, refer to "■ Function to Protect Against Write due to Erroneous Instruction Recognition".

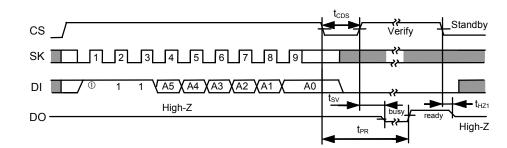
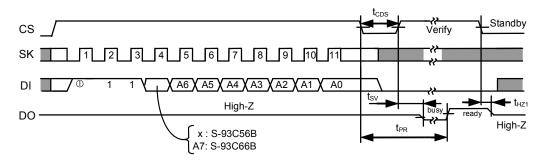


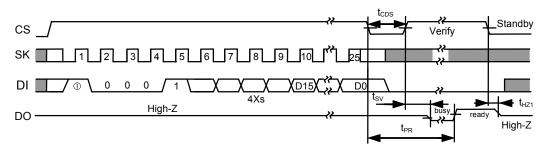
Figure 12 Data Erase Timing (S-93C46B)





#### 4.4 Writing to chip (WRAL)

To write the same 16-bit data to the entire memory address space, change CS to high, and then input the WRAL instruction, an address, and 16-bit data following the start bit. Any address can be input. The write operation starts when CS goes low. There is no need to set the data to 1 before writing. If the clocks more than the specified number have been input, the clock pulse monitoring circuit cancels the WRAL instruction. For details of the clock pulse monitoring circuit, refer to "■ Function to Protect Against Write due to Erroneous Instruction Recognition".





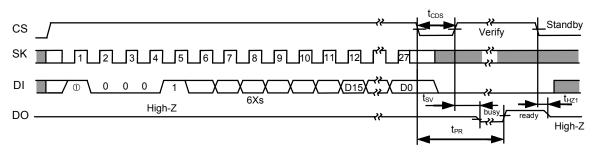
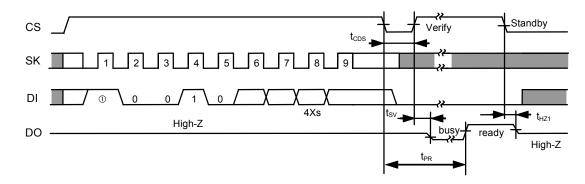


Figure 15 Chip Write Timing (S-93C56B, S-93C66B)

# Rev.8.1\_02

### 4.5 Erasing chip (ERAL)

To erase the data of the entire memory address space, set all the data to 1, change CS to high, and then input the ERAL instruction and an address following the start bit. Any address can be input. There is no need to input data. The chips erase operation starts when CS goes low. If the clocks more than the specified number have been input, the clock pulse monitoring circuit cancels the ERAL instruction. For details of the clock pulse monitoring circuit, refer to "■ Function to Protect Against Write due to Erroneous Instruction Recognition".





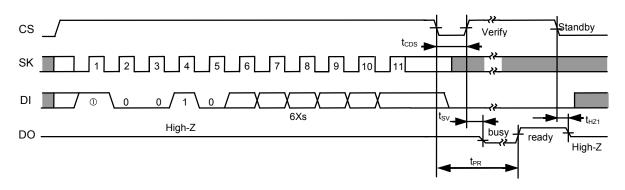


Figure 17 Chip Erase Timing (S-93C56B, S-93C66B)

#### 5. Write enable (EWEN) and write disable (EWDS)

The EWEN instruction is an instruction that enables a write operation. The status in which a write operation is enabled is called the program enable mode.

The EWDS instruction is an instruction that disables a write operation. The status in which a write operation is disabled is called the program disable mode.

After CS goes high, input an instruction in the order of the start bit, EWEN or EWDS instruction, and address (optional). Each mode becomes valid by inputting a low level to CS after the last address (optional) has been input.

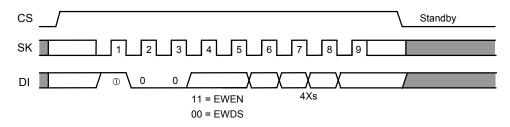


Figure 18 Write Enable / Disable Timing (S-93C46B)

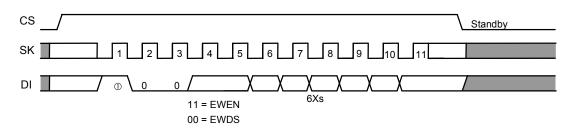


Figure 19 Write Enable / Disable Timing (S-93C56B, S-93C66B)

#### 5.1 Recommendation for write operation disable instruction

It is recommended to implement a design that prevents an incorrect write operation when a write instruction is erroneously recognized by executing the write operation disable instruction when executing instructions other than write instruction, and immediately after power-on and before power off.

# Rev.8.1\_02

# Write Protect Function during the Low Power Supply Voltage

The S-93C46B/56B/66B provides a built-in detector. When the power supply voltage is low or at power application, the write instructions (WRITE, ERASE, WRAL, ERAL) are cancelled, and the write disable state (EWDS) is automatically set. The detection voltage is 1.75 V typ., the release voltage is 2.05 V typ., and there is a hysteresis of about 0.3 V (refer to **Figure 20**). Therefore, when a write operation is performed after the power supply voltage has dropped and then risen again up to the level at which writing is possible, a write enable instruction (EWEN) must be sent before a write instruction (WRITE, ERASE, WRAL, ERAL) is executed.

When the power supply voltage drops during a write operation, the data being written to an address at that time is not guaranteed.

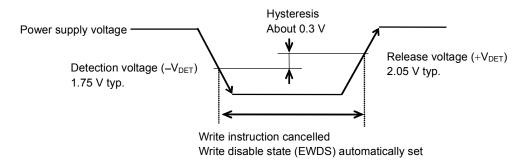


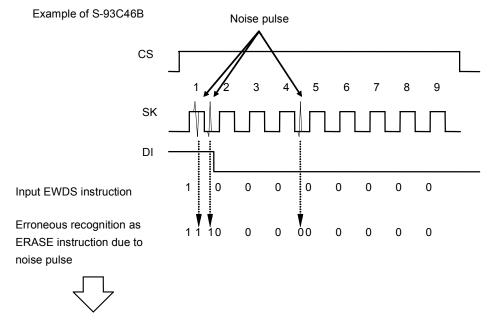
Figure 20 Operation during Low Power Supply Voltage

# ■ Function to Protect Against Write due to Erroneous Instruction Recognition

The S-93C46B/56B/66B provides a built-in clock pulse monitoring circuit which is used to prevent an erroneous write operation by canceling write instructions (WRITE, ERASE, WRAL, ERAL) recognized erroneously due to an erroneous clock count caused by the application of noise pulses or double counting of clocks.

Instructions are cancelled if a clock pulse more or less than specified number decided by each write operation (WRITE, ERASE, WRAL, ERAL) is detected.

#### <Example> Erroneous recognition of program disable instruction (EWDS) as erase instruction (ERASE)



In products that do not include a clock pulse monitoring circuit, FFFF is mistakenly written on address 00h. However the S-93C46B detects the overcount and cancels the instruction without performing a write operation.

#### Figure 21 Example of Clock Pulse Monitoring Circuit Operation

# 3-Wire Interface (Direct Connection between DI and DO)

There are two types of serial interface configurations: a 4-wire interface configured using the CS, SK, DI, and DO pins, and a 3-wire interface that connects the DI input pin and DO output pin.

When the 3-wire interface is employed, a period in which the data output from the CPU and the data output from the serial memory collide may occur, causing a malfunction. To prevent such a malfunction, connect the DI and DO pins of the S-93C46B/56B/66B via a resistor (10 k $\Omega$  to 100 k $\Omega$ ) so that the data output from the CPU takes precedence in being input to the DI pin (refer to "Figure 22 Connection of 3-Wire Interface").

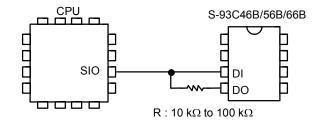


Figure 22 Connection of 3-Wire Interface

# ■ Input Pin and Output Pin

### 1. Connection of input pins

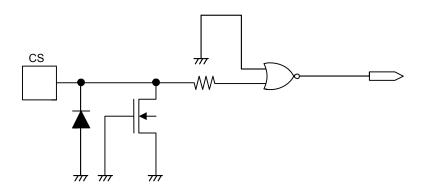
All the input pins of the S-93C46B/56B/66B employ a CMOS structure, so design the equipment so that high impedance will not be input while the S-93C46B/56B/66B is operating. Especially, deselect the CS input (a low level) when turning on / off power and during standby. When the CS pin is deselected (a low level), incorrect data writing will not occur. Connect the CS pin to GND via a resistor (10 k $\Omega$  to 100 k $\Omega$  pull-down resistor). To prevent malfunction, it is recommended to use equivalent pull-down resistors for pins other than the CS pin.

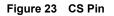
# 2. Equivalent circuit of input pin and output pin

The following shows the equivalent circuits of input pins of the S-93C46B/56B/66B. None of the input pins incorporate pull-up and pull-down elements, so special care must be taken when designing to prevent a floating status.

Output pins are high-level / low-level / high-impedance tri-state outputs. The TEST pin is disconnected from the internal circuit by a switching transistor during normal operation. As long as the absolute maximum rating is satisfied, the TEST pin and internal circuit will never be connected.

### 2.1 Input pin





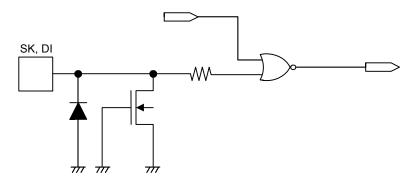


Figure 24 SK, DI Pin

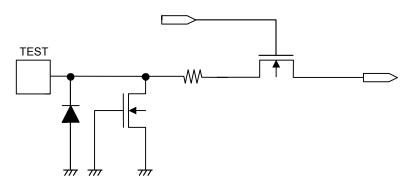


Figure 25 TEST Pin

### 2. 2 Output pin

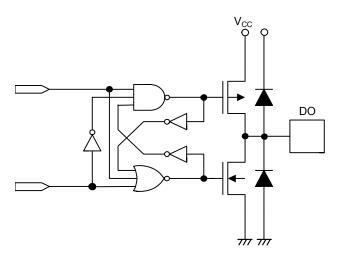


Figure 26 DO Pin

#### 3. Input pin noise elimination time

The S-93C46B/56B/66B includes a built-in low-pass filter to eliminate noise at the SK, DI, and CS pins. This means that if the supply voltage is 5.0 V (at room temperature), noise with a pulse width of 20 ns or less can be eliminated.

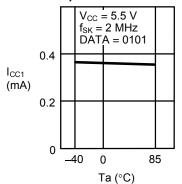
Note, therefore, the noise with a pulse width of more than 20 ns will be recognized as a pulse if the voltage exceeds  $V_{IH}$  /  $V_{IL}$ .

# Precaution

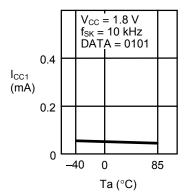
- Do not apply an electrostatic discharge to this IC that exceeds the performance ratings of the built-in electrostatic protection circuit.
- ABLIC Inc. claims no responsibility for any and all disputes arising out of or in connection with any infringement by products including this IC of patents owned by a third party.

# ■ Characteristics (Typical Data)

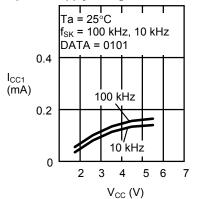
- 1. DC Characteristics
  - 1.1 Current consumption (READ) I<sub>CC1</sub> vs. ambient temperature Ta



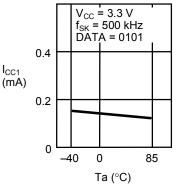
1.3 Current consumption (READ) I<sub>CC1</sub> vs. ambient temperature Ta



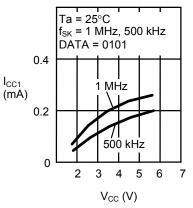
1.5 Current consumption (READ)  $I_{CC1}$  vs. power supply voltage  $V_{CC}$ 



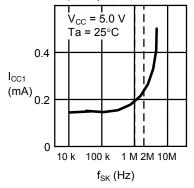
1.2 Current consumption (READ) I<sub>CC1</sub> vs. ambient temperature Ta



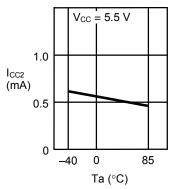
1.4 Current consumption (READ)  $I_{CC1}$  vs. power supply voltage  $V_{CC}$ 



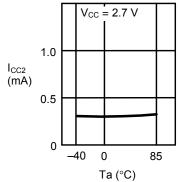
1. 6 Current consumption (READ) I<sub>CC1</sub> vs. Clock frequency f<sub>SK</sub>



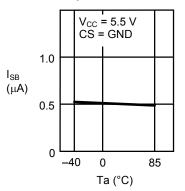
1.7 Current consumption (WRITE) I<sub>CC2</sub> vs. ambient temperature Ta



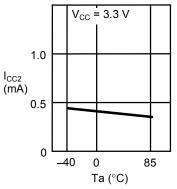
1.9 Current consumption (WRITE) I<sub>CC2</sub> vs. ambient temperature Ta



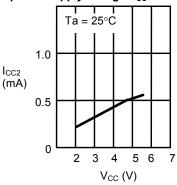
1. 11 Current consumption in standby mode I<sub>SB</sub> vs. ambient temperature Ta



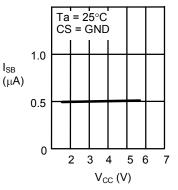
1.8 Current consumption (WRITE) I<sub>CC2</sub> vs. ambient temperature Ta



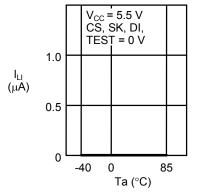
1.10 Current consumption (WRITE) I<sub>CC2</sub> vs. power supply voltage V<sub>CC</sub>



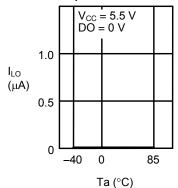
1. 12 Current consumption in standby mode  $I_{\rm SB}$  vs. power supply voltage  $V_{\rm CC}$ 



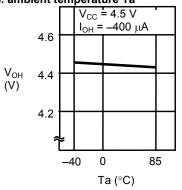
1. 13 Input leakage current I<sub>LI</sub> vs. ambient temperature Ta



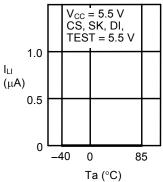
1.15 Output leakage current I<sub>LO</sub> vs. ambient temperature Ta



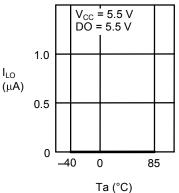
1. 17 High-level output voltage V<sub>OH</sub> vs. ambient temperature Ta



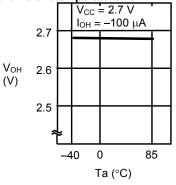
1.14 Input leakage current I<sub>LI</sub> vs. ambient temperature Ta

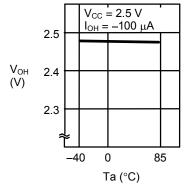


1.16 Output leakage current I<sub>LO</sub> vs. ambient temperature Ta

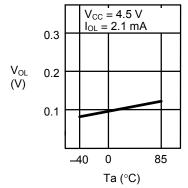


1. 18 High-level output voltage V<sub>OH</sub> vs. ambient temperature Ta

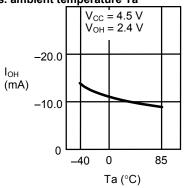




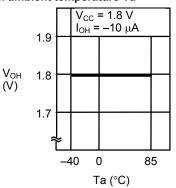
1. 21 Low-level output voltage V<sub>OL</sub> vs. ambient temperature Ta



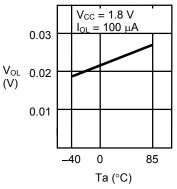
1. 23 High-level output current I<sub>OH</sub> vs. ambient temperature Ta



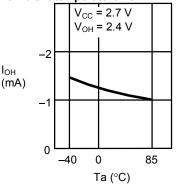
1. 20 High-level output voltage V<sub>OH</sub> vs. ambient temperature Ta



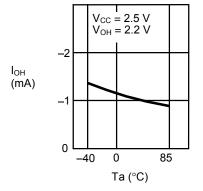
1. 22 Low-level output voltage V<sub>OL</sub> vs. ambient temperature Ta



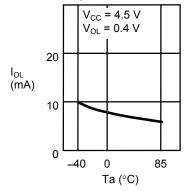
1. 24 High-level output current I<sub>OH</sub> vs. ambient temperature Ta



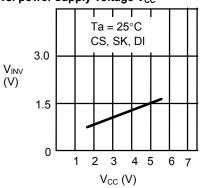
1. 25 High-level output current I<sub>OH</sub> vs. ambient temperature Ta



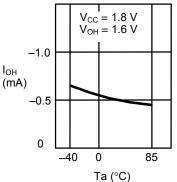
1.27 Low-level output current I<sub>OL</sub> vs. ambient temperature Ta



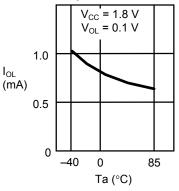
1. 29 Input inverted voltage V<sub>INV</sub> vs. power supply voltage V<sub>CC</sub>



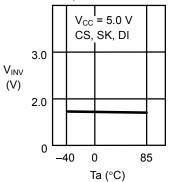
1.26 High-level output current I<sub>OH</sub> vs. ambient temperature Ta



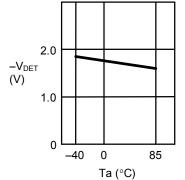
1.28 Low-level output current I<sub>OL</sub> vs. ambient temperature Ta



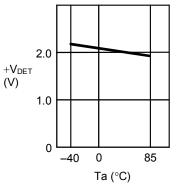
1. 30 Input inverted voltage V<sub>INV</sub> vs. ambient temperature Ta



1. 31 Low supply voltage detection voltage -V<sub>DET</sub> vs. ambient temperature Ta

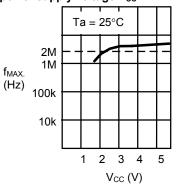


1. 32 Low supply voltage release voltage +V<sub>DET</sub> vs. ambient temperature Ta

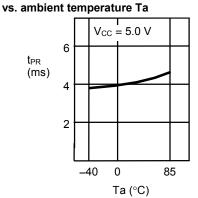


### 2. AC Characteristics

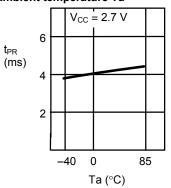
2.1 Maximum operating frequency f<sub>MAX.</sub> vs. power supply voltage V<sub>CC</sub>



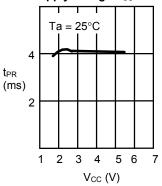
2.3 Write time t<sub>PR</sub>



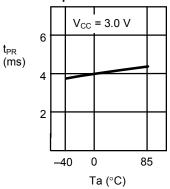
2. 5 Write time t<sub>PR</sub> vs. ambient temperature Ta



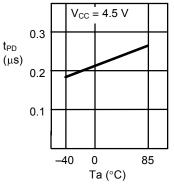
2. 2 Write time t<sub>PR</sub> vs. power supply voltage V<sub>cc</sub>



2.4 Write time t<sub>PR</sub> vs. ambient temperature Ta



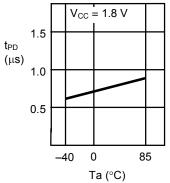
2. 6 Data output delay time t<sub>PD</sub> vs. ambient temperature Ta



vs. ambient temperature Ta  $v_{CC} = 2.7 V$   $v_{CC} = 2.7 V$ 

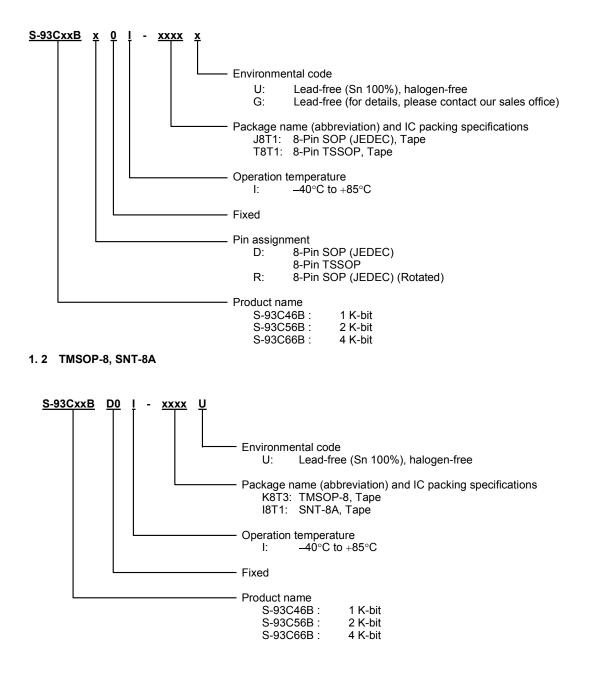
2.7 Data output delay time  $t_{PD}$ 

2.8 Data output delay time t<sub>PD</sub> vs. ambient temperature Ta



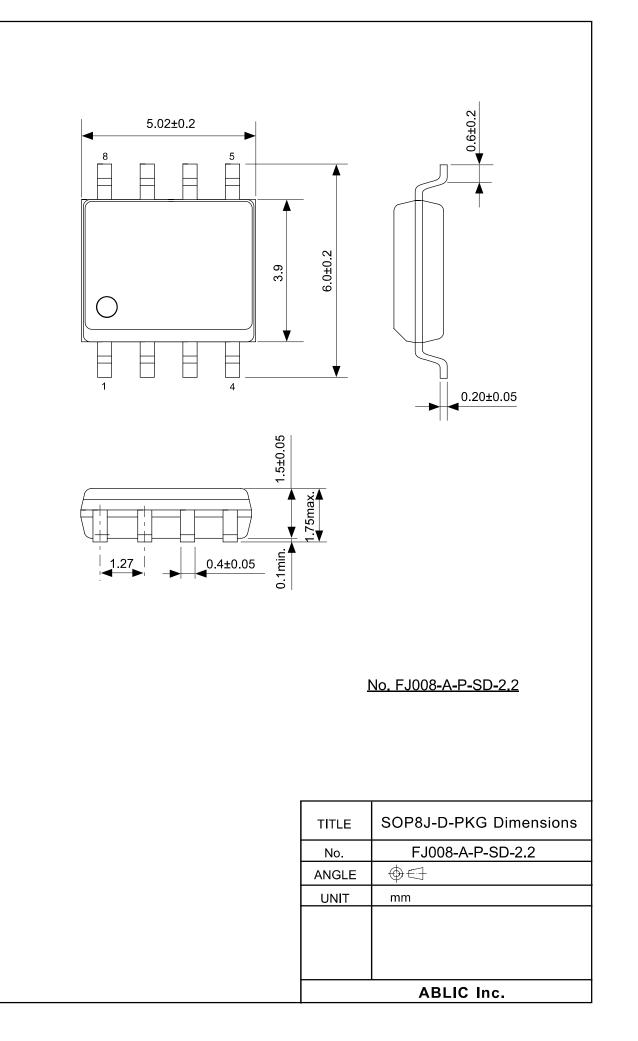
### Product Name Structure

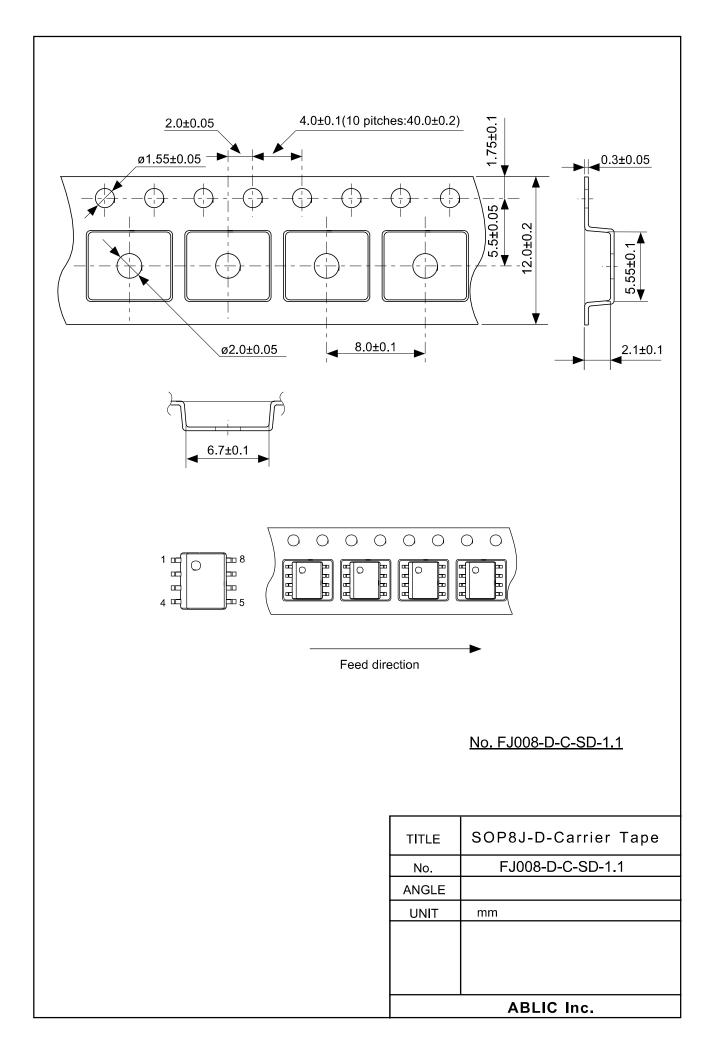
- 1. Product name
  - 1.1 8-Pin SOP (JEDEC), 8-Pin TSSOP

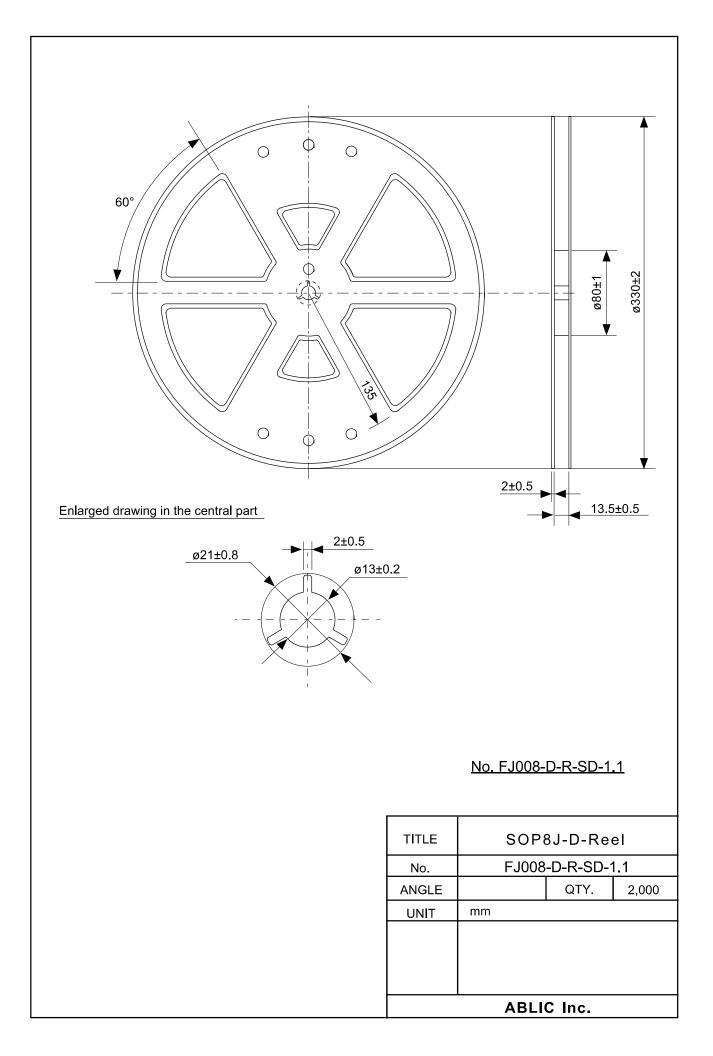


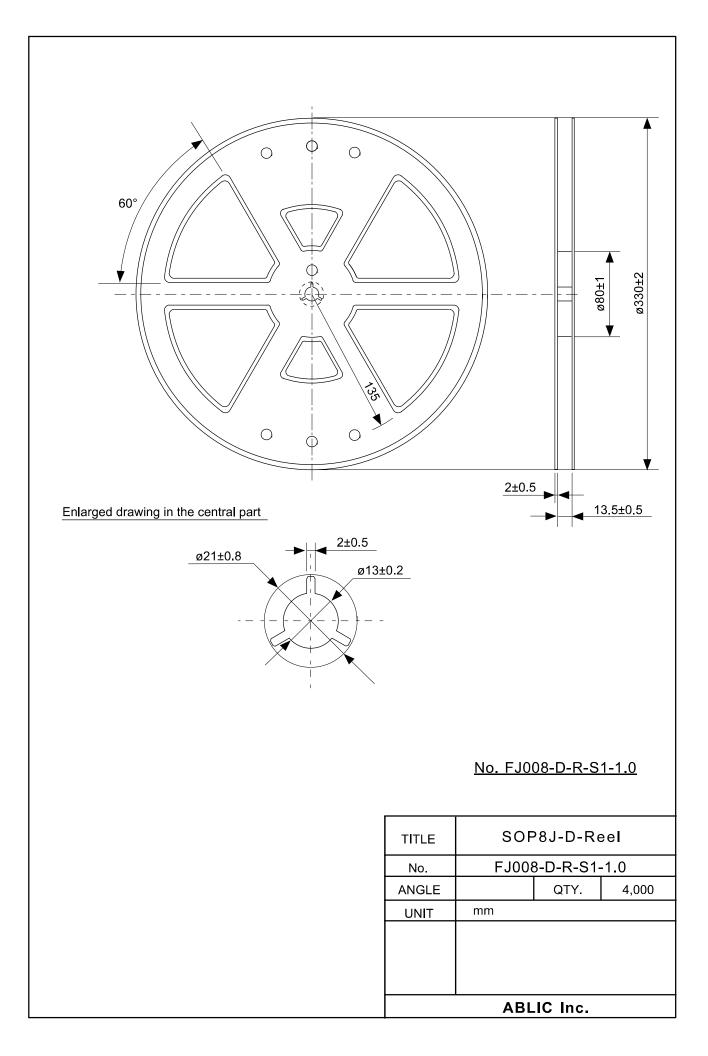
# 2. Packages

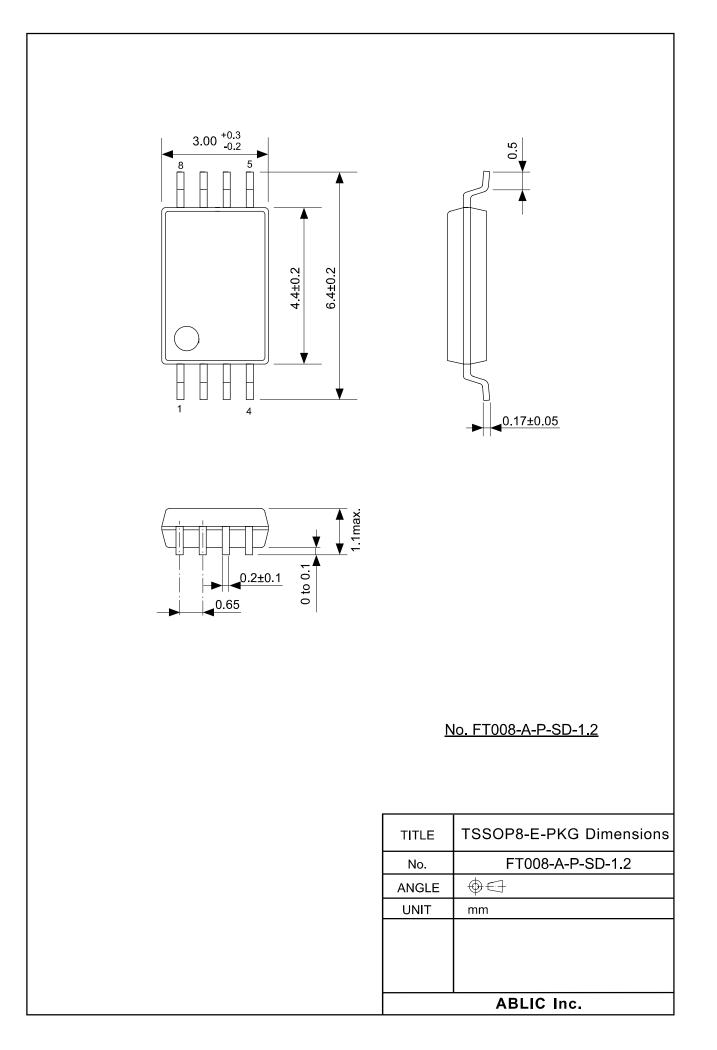
Package Name		Drawing Code						
		Package	Таре	Reel	Land			
8-Pin SOP	Environmental code = G	FJ008-A-P-SD	FJ008-D-C-SD	FJ008-D-R-SD				
(JEDEC)	Environmental code = U	FJ008-A-P-SD	FJ008-D-C-SD	FJ008-D-R-S1	_			
8-Pin TSSOP	Environmental code = G	FT008-A-P-SD	FT008-E-C-SD	FT008-E-R-SD				
8-PIN 1550P	Environmental code = U	FT008-A-P-SD	FT008-E-C-SD	FT008-E-R-S1	—			
TMSOP-8		FM008-A-P-SD	FM008-A-C-SD	FM008-A-R-SD				
SNT-8A		PH008-A-P-SD	PH008-A-C-SD	PH008-A-R-SD	PH008-A-L-SD			

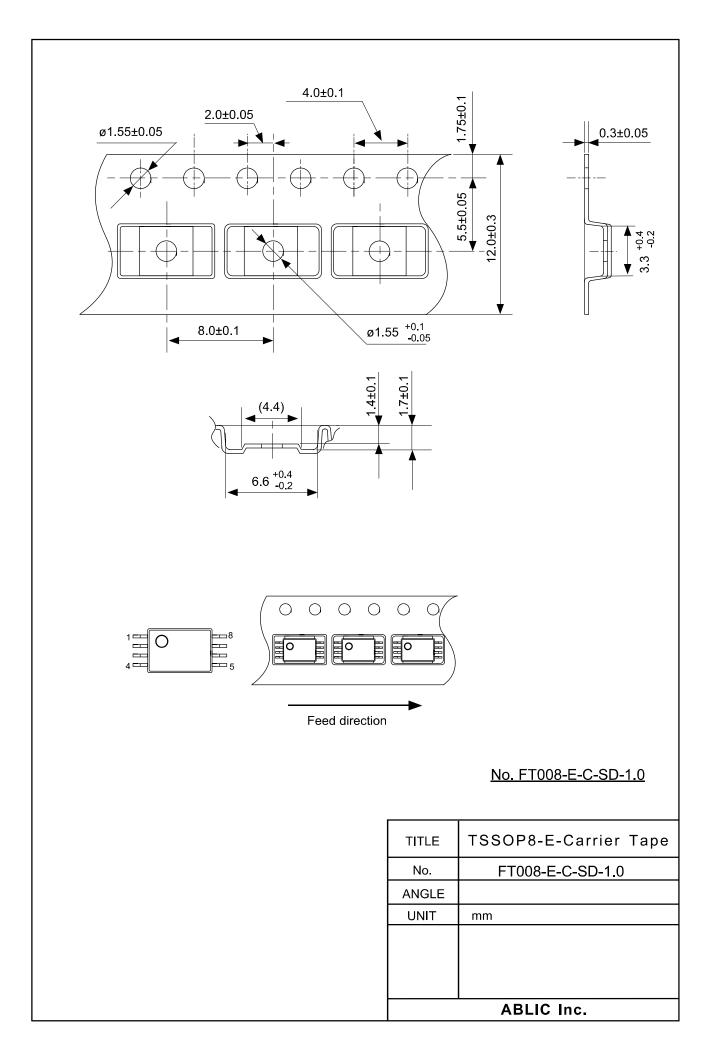


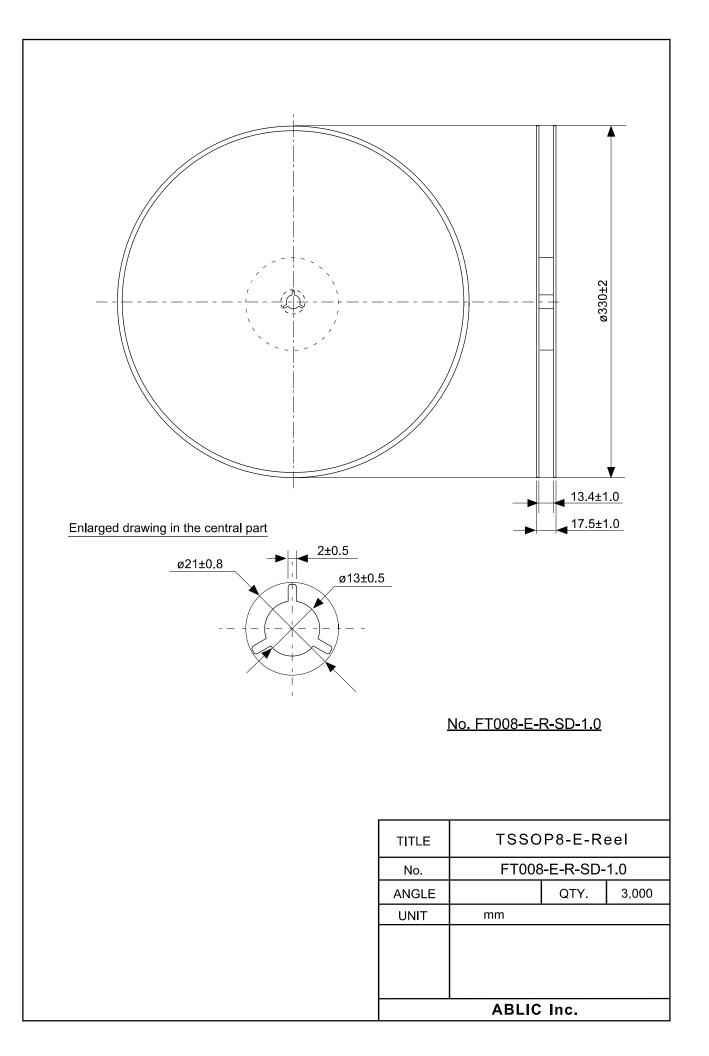


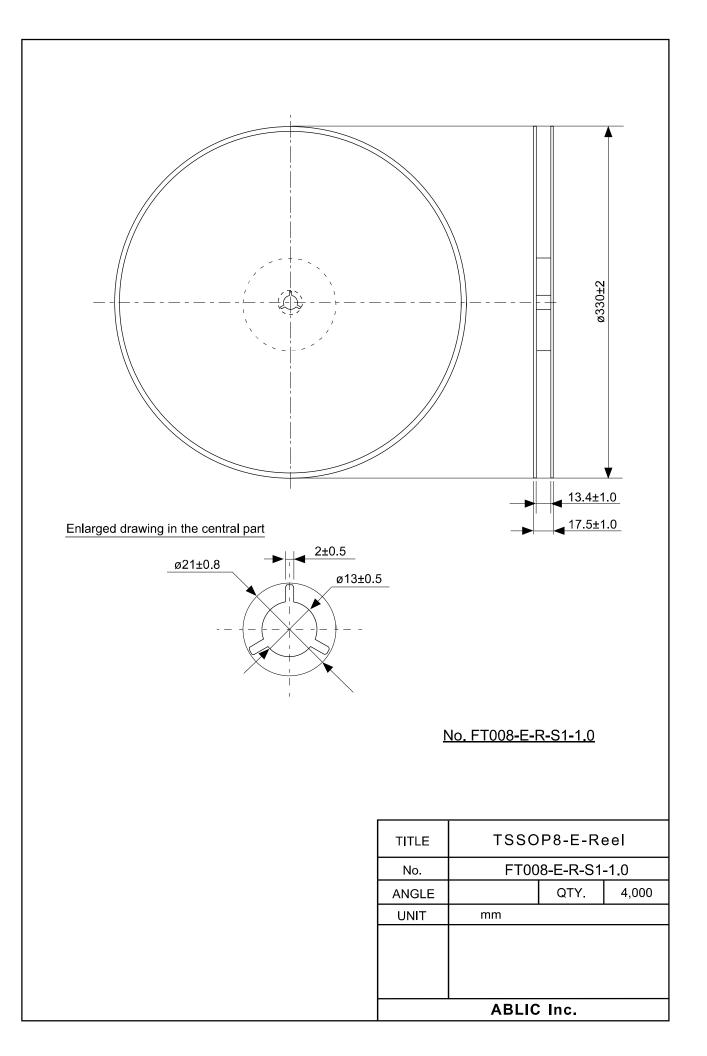


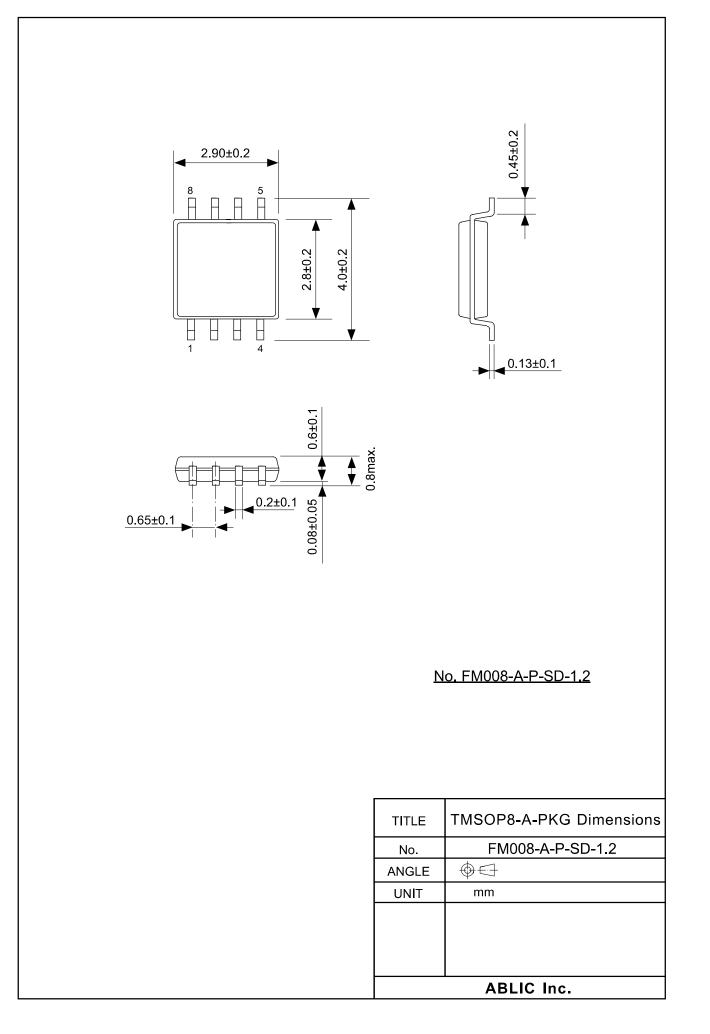


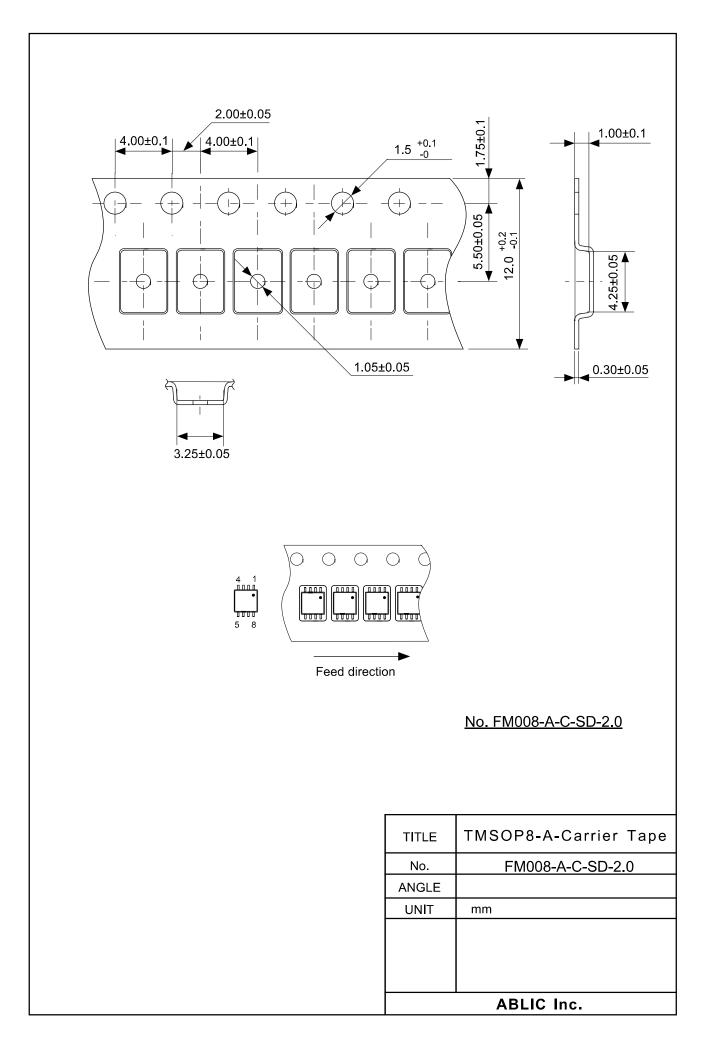


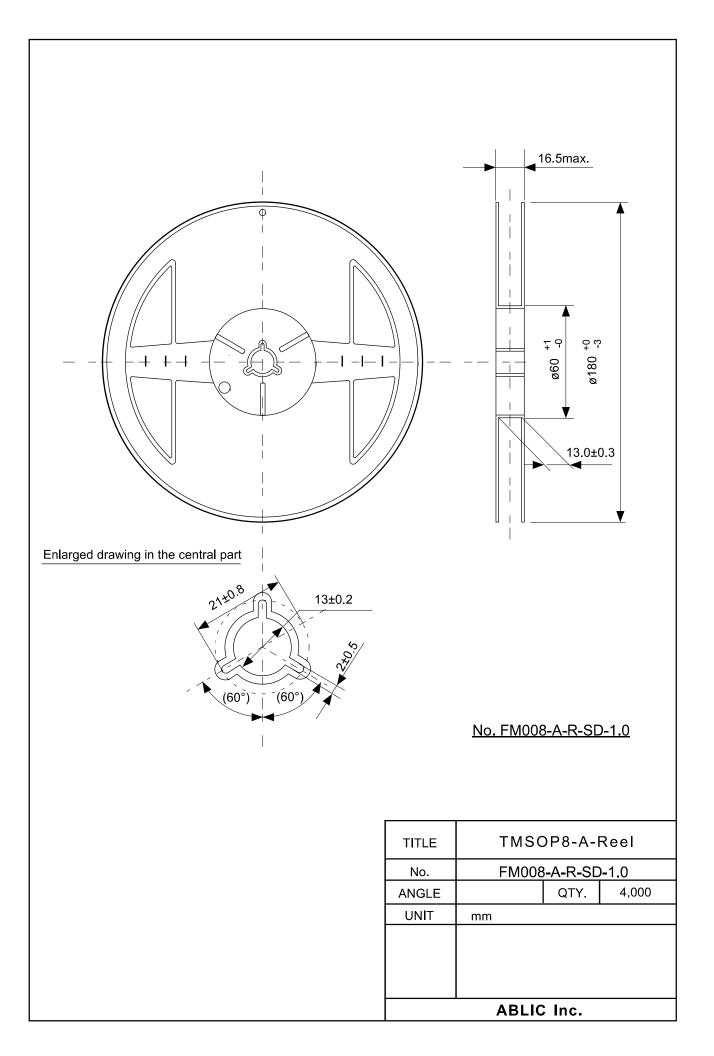


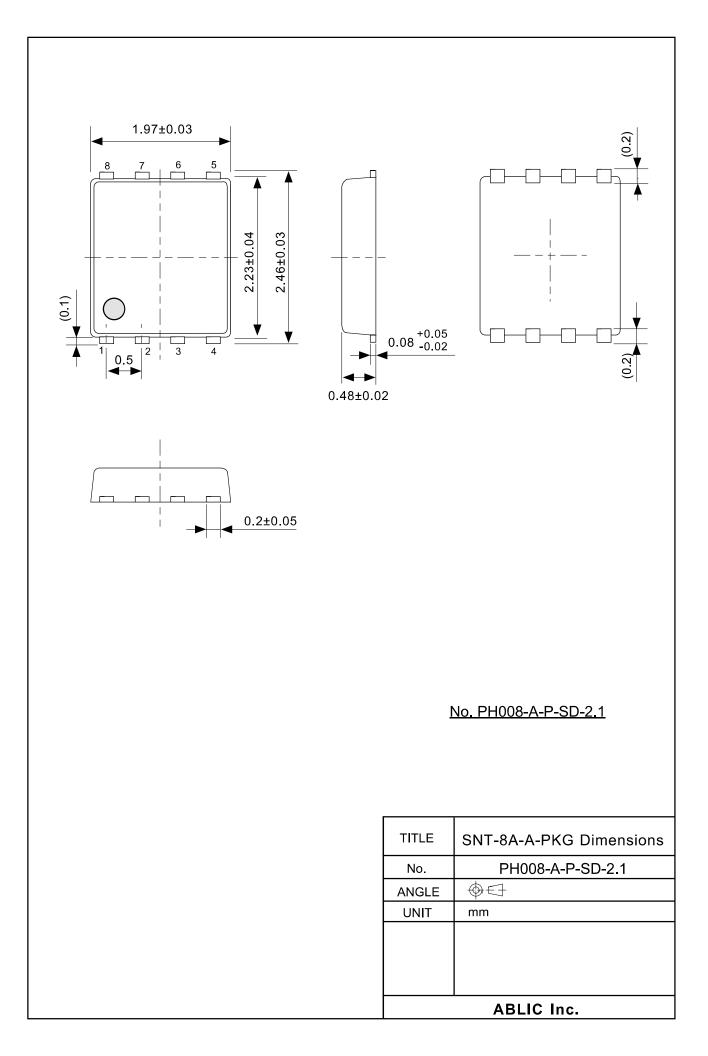


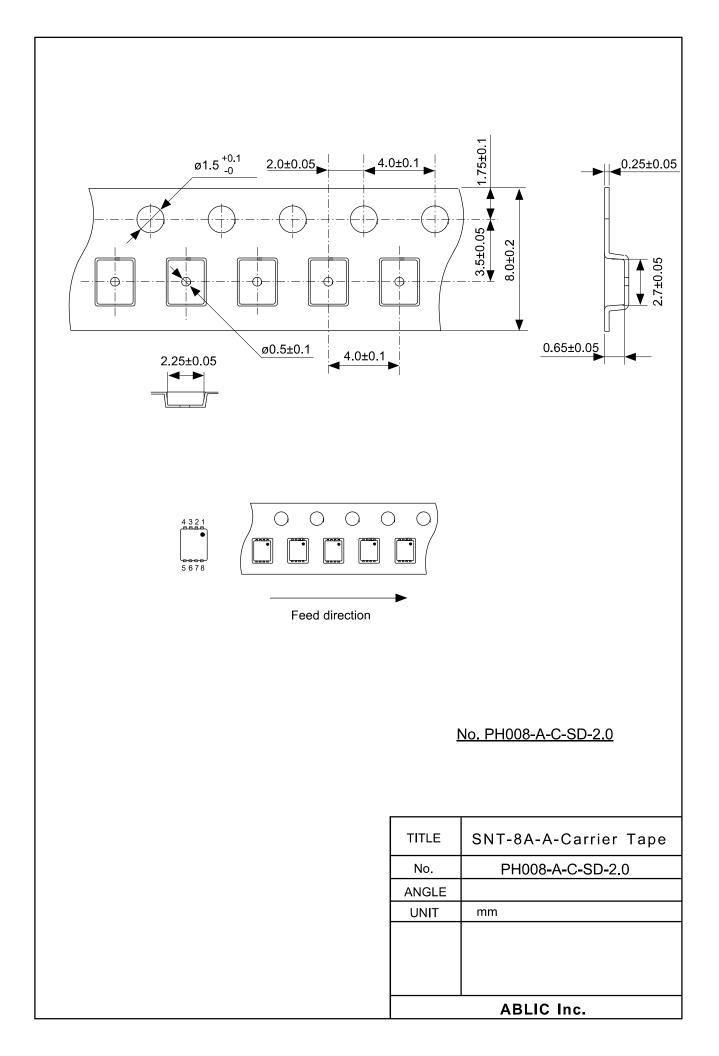


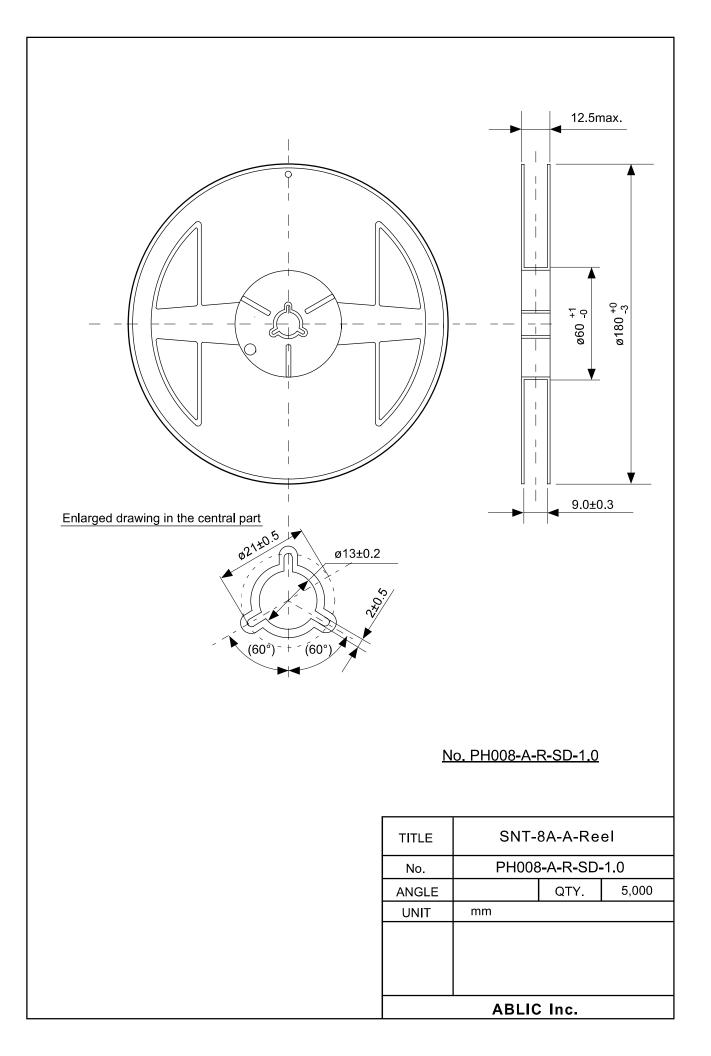


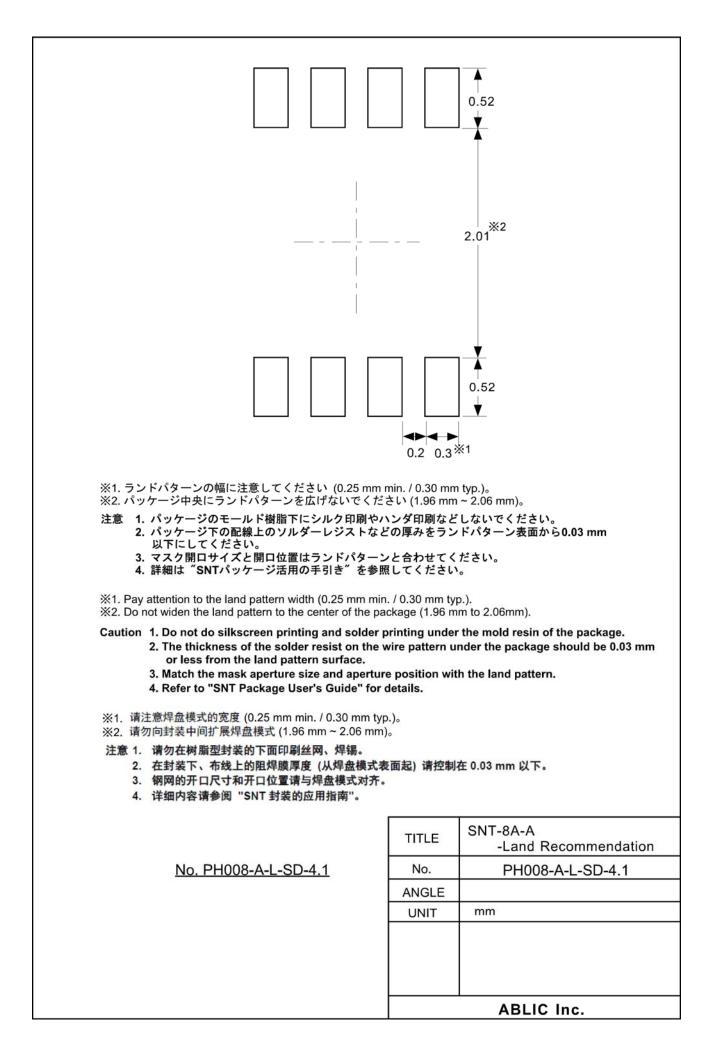












## **Disclaimers (Handling Precautions)**

- 1. All the information described herein (product data, specifications, figures, tables, programs, algorithms and application circuit examples, etc.) is current as of publishing date of this document and is subject to change without notice.
- The circuit examples and the usages described herein are for reference only, and do not guarantee the success of any specific mass-production design.
   ABLIC Inc. is not responsible for damages caused by the reasons other than the products described herein

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   ABLIC Inc. is not responsible for damages caused by failures and / or accidents, etc. that occur due to the use of the products outside their specified ranges.
- 5. When using the products, confirm their applications, and the laws and regulations of the region or country where they are used and verify suitability, safety and other factors for the intended use.
- 6. When exporting the products, comply with the Foreign Exchange and Foreign Trade Act and all other export-related laws, and follow the required procedures.
- 7. The products must not be used or provided (exported) for the purposes of the development of weapons of mass destruction or military use. ABLIC Inc. is not responsible for any provision (export) to those whose purpose is to develop, manufacture, use or store nuclear, biological or chemical weapons, missiles, or other military use.
- 8. The products are not designed to be used as part of any device or equipment that may affect the human body, human life, or assets (such as medical equipment, disaster prevention systems, security systems, combustion control systems, infrastructure control systems, vehicle equipment, traffic systems, in-vehicle equipment, aviation equipment, aerospace equipment, and nuclear-related equipment), excluding when specified for in-vehicle use or other uses. Do not apply the products to the above listed devices and equipments without prior written permission by ABLIC Inc. Especially, the products cannot be used for life support devices, devices implanted in the human body and devices that directly affect human life, etc.

Prior consultation with our sales office is required when considering the above uses.

ABLIC Inc. is not responsible for damages caused by unauthorized or unspecified use of our products.

9. Semiconductor products may fail or malfunction with some probability. The user of the products should therefore take responsibility to give thorough consideration to safety design including redundancy, fire spread prevention measures, and malfunction prevention to prevent accidents causing injury or death, fires and social damage, etc. that may ensue from the products' failure or malfunction. The entire system must be sufficiently evaluated and applied on customer's own responsibility.

- 10. The products are not designed to be radiation-proof. The necessary radiation measures should be taken in the product design by the customer depending on the intended use.
- 11. The products do not affect human health under normal use. However, they contain chemical substances and heavy metals and should therefore not be put in the mouth. The fracture surfaces of wafers and chips may be sharp. Be careful when handling these with the bare hands to prevent injuries, etc.
- 12. When disposing of the products, comply with the laws and ordinances of the country or region where they are used.
- 13. The information described herein contains copyright information and know-how of ABLIC Inc. The information described herein does not convey any license under any intellectual property rights or any other rights belonging to ABLIC Inc. or a third party. Reproduction or copying of the information from this document or any part of this document described herein for the purpose of disclosing it to a third-party without the express permission of ABLIC Inc. is strictly prohibited.
- 14. For more details on the information described herein, contact our sales office.

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